

Support For User Generated Evolutions Of Goal Models

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Alicia M. Grubb



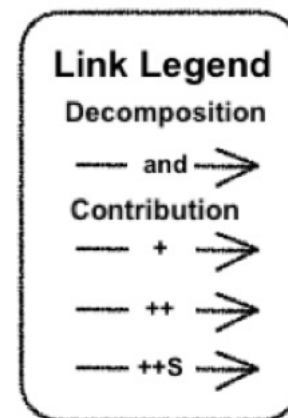
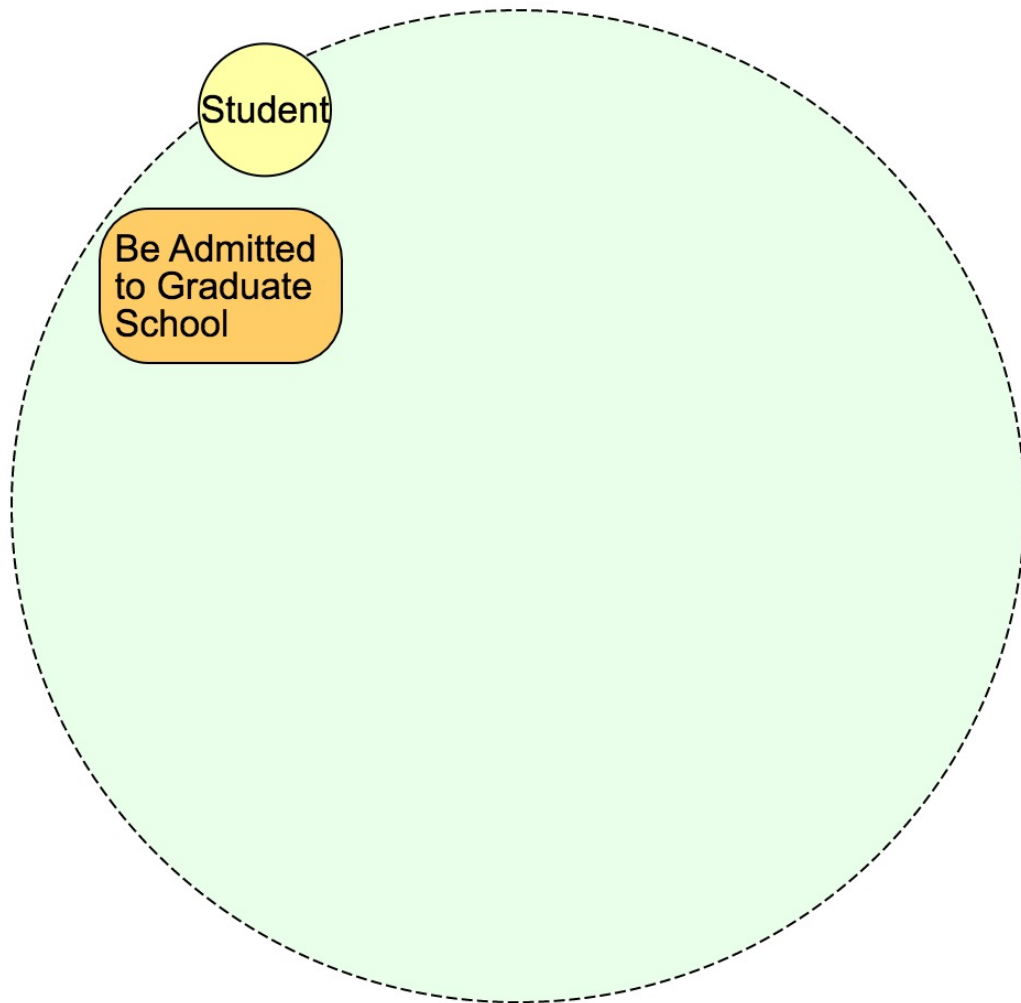
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SMITH COLLEGE

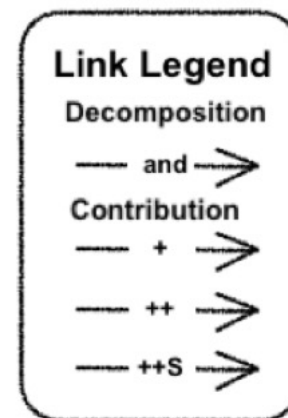
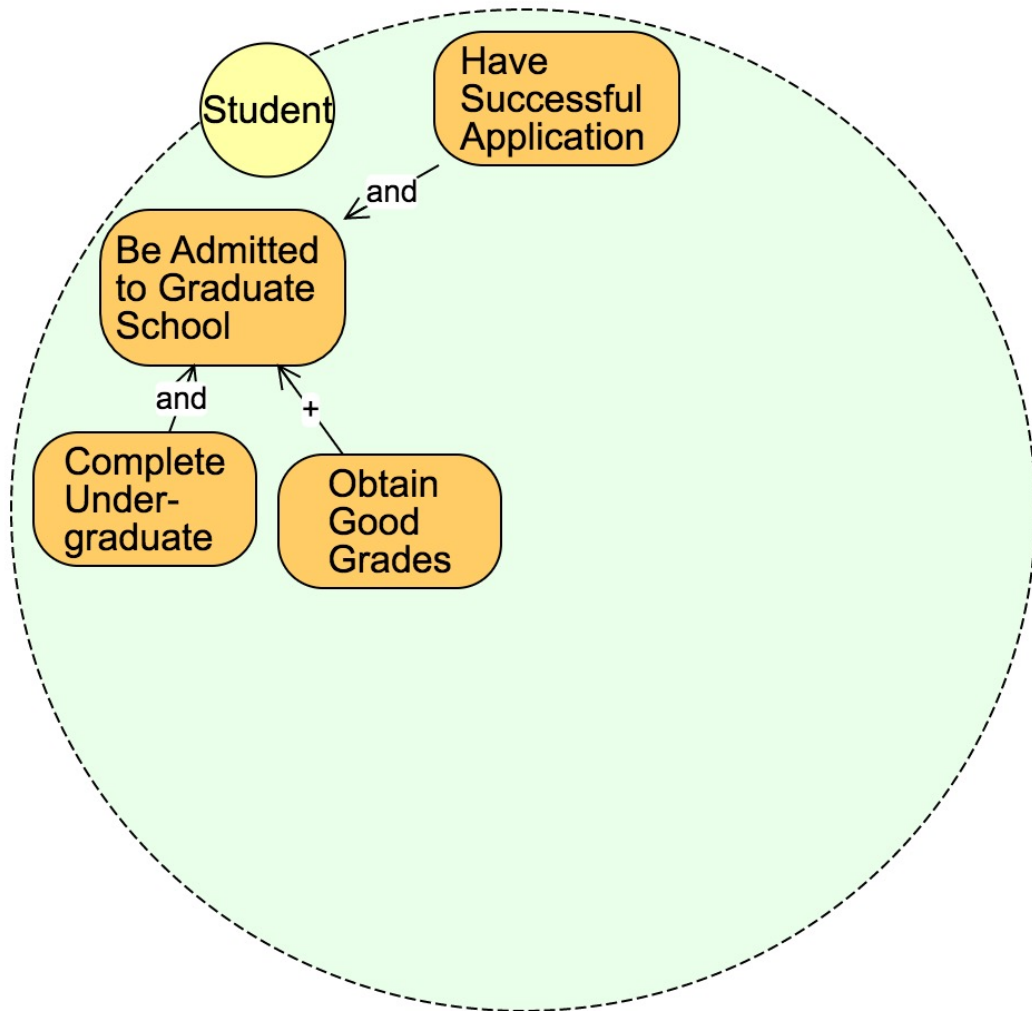
Motivating Example - GRAD

An undergraduate student interested in graduate school.



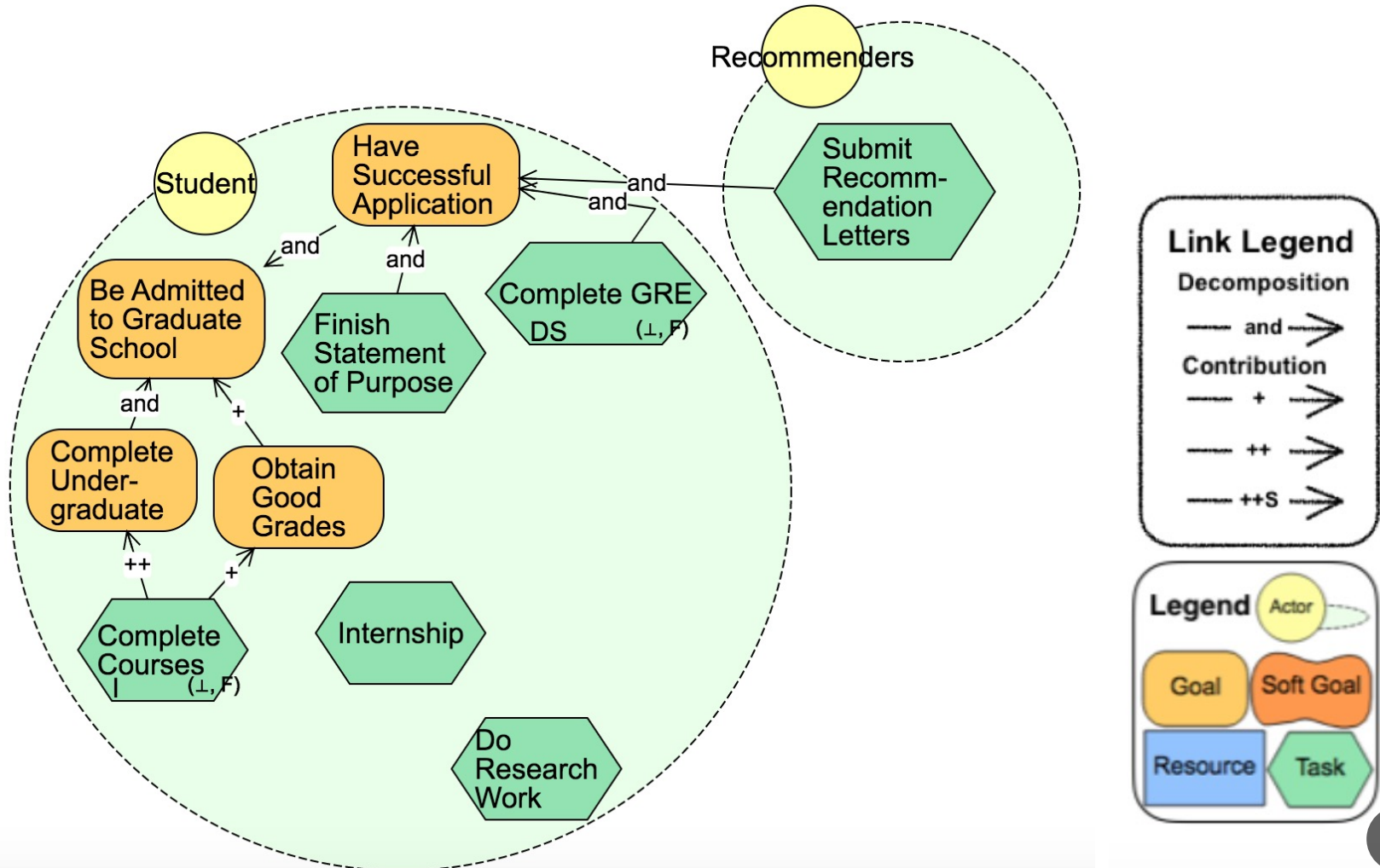
Motivating Example - GRAD

Requirements for Graduate School.



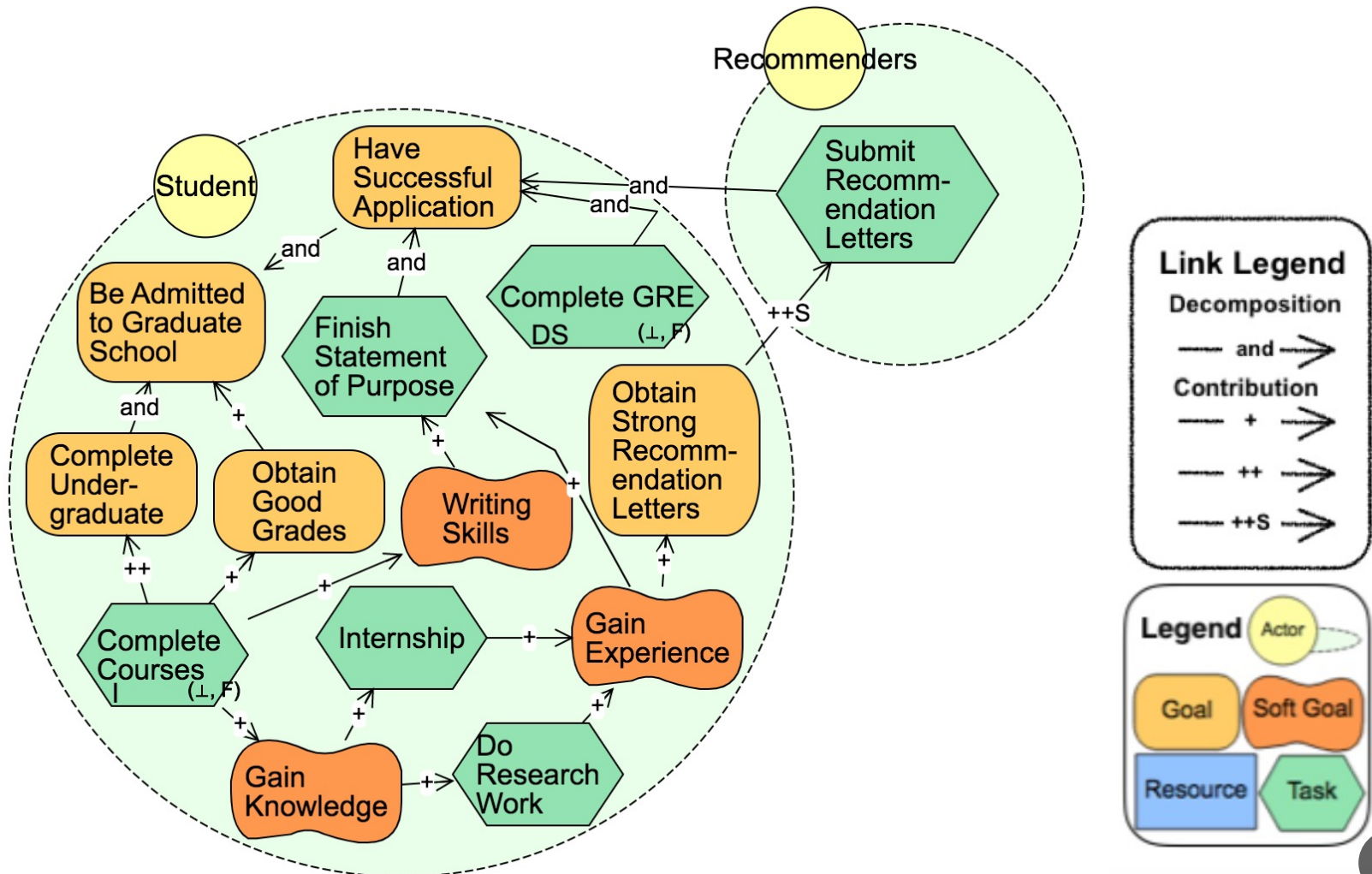
Motivating Example - GRAD

Tasks/Goal to satisfy the requirements.



Motivating Example - GRAD

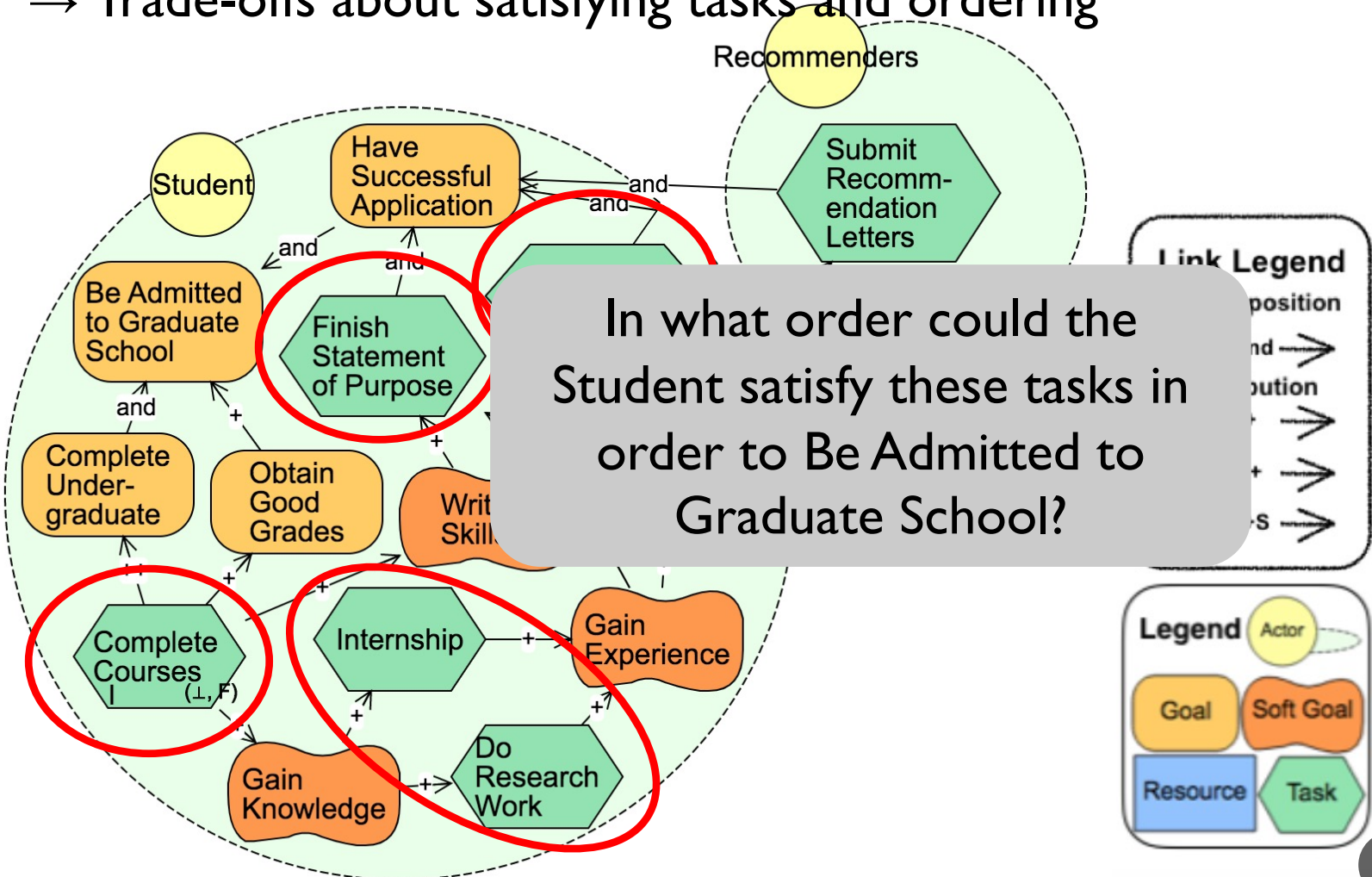
Additional Soft Goals that helps with the tasks.



Motivating Example - GRAD

To satisfies all the requirements

→ Trade-offs about satisfying tasks and ordering



In what order could the Student satisfy these tasks in order to Be Admitted to Graduate School?

BloomingLeaf

Evolving Intentions Framework:
Analysis of goal models when
intention evaluations change over time



Will demonstrate through

BloomingLeaf

BloomingLeaf

web-based goal modeling tool with automated formal analysis

BloomingLeaf

Undo Redo Clear Save Load Zoom In Zoom Out Open as SVG Font Size Help Analysis

Standard Functionality

Analysis

Node Name:

Complete GRE

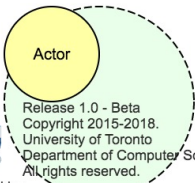
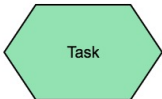
Initial Satisfaction Value:

Denied (L, F)

Function Type:

ed Satisfied

Satisfaction Value?
Functions?







Release 1.0 - Beta
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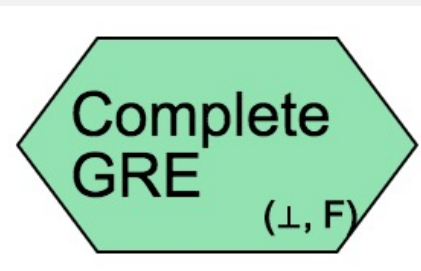
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client IO. All rights reserved.
JointJS: an HTML 5 diagramming
component.
<http://jointjs.com>

Evidence Pairs

		$s \in \{F, P, \perp\}$: for fulfillment		
		Full (F)	Partial (P)	No Evidence (\perp)
d $\in \{F, P, \perp\}$: against fulfillment	Full (F)	(F, F) 	(P, F) 	(\perp , F)
	Partial (P)	(F, P) 	(P, P) 	(\perp , P)
	No Evidence (\perp)	(F, \perp)	(P, \perp)	(\perp , \perp)

 : Conflict value

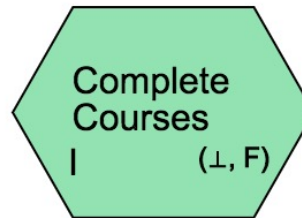
- **evidence pairs (s, d)**
- **s** - evidence **for** the fulfillment of an intention (satisfaction)
- **d** – evidence **against** the fulfillment of an intention (denial)



This goal is fully evidence against fulfillment (fully denied)

Evolving Intentions

- Fulfillment of intentions changes over time
- Intentions are assigned **functions** prior to analysis
- Four atomic functions: **CONSTANT**, **INCREASE**, **DECREASE**, and **STOCHASTIC**



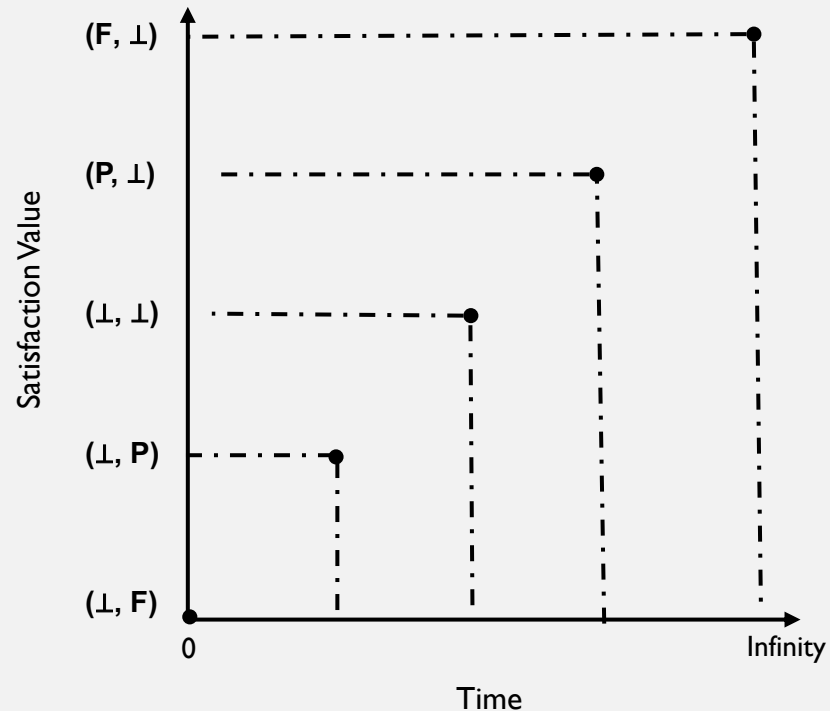
Initial Satisfaction Value:

Denied (\perp , F)

Function Type:

Increase

Satisfied (F, \perp)



Evolving Intentions

- Fulfillment of intentions changes over time
- **Functions** for the intention evolution assigned prior to analysis.
- Four atomic functions: **CONSTANT**, **INCREASE**, **DECREASE**, and **STOCHASTIC**

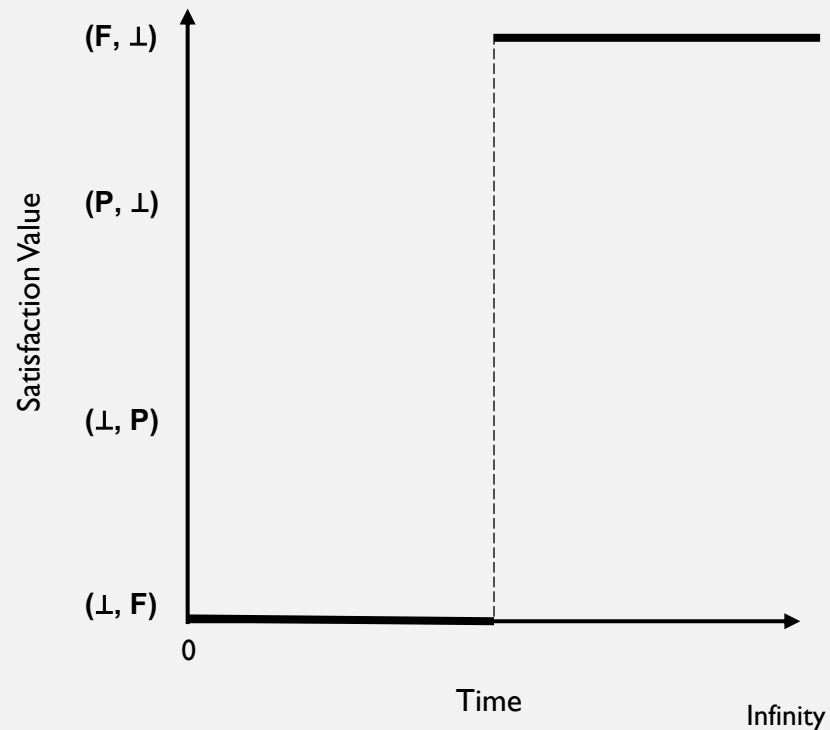


Initial Satisfaction Value:

Denied (⊥, F)

Function Type:

Denied Satisfied



BloomingLeaf

web-based goal modeling tool with automated formal analysis

BloomingLeaf

Undo

Redo

Clear

Save

Load

Zoom In

Zoom Out

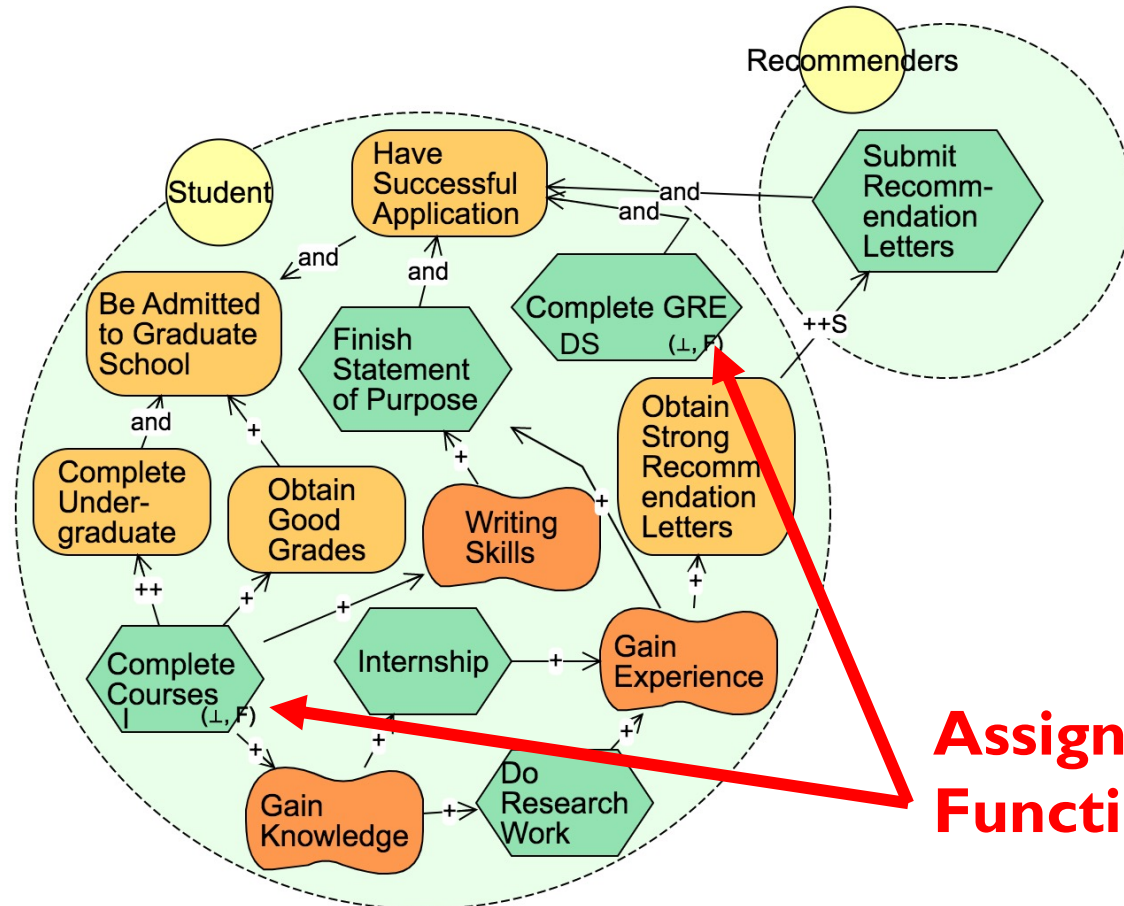
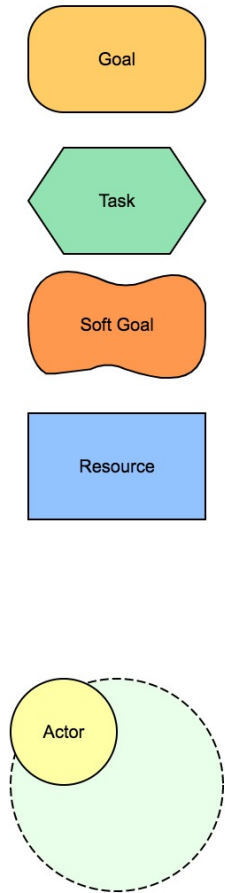
Open as SVG

Font Size

Help

Analysis

Modeling View



Assigned Functions

Single Path Analysis

one possible evolution of the model over a pre-specified number of time points.

Simulation Start: 0

Max Absolute Time

100

Conflict Prevention Level

Strong

Num Relative Time Points

10

Absolute Time Points

(e.g. 5 8 22)

View List of Assignments

View Intermediate Values

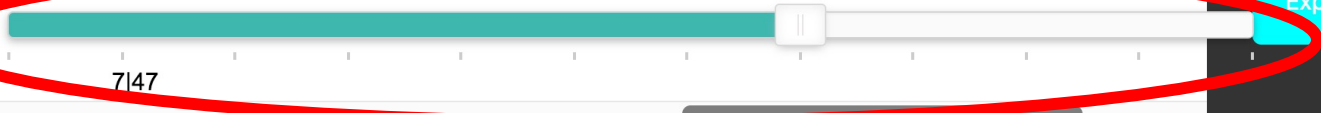
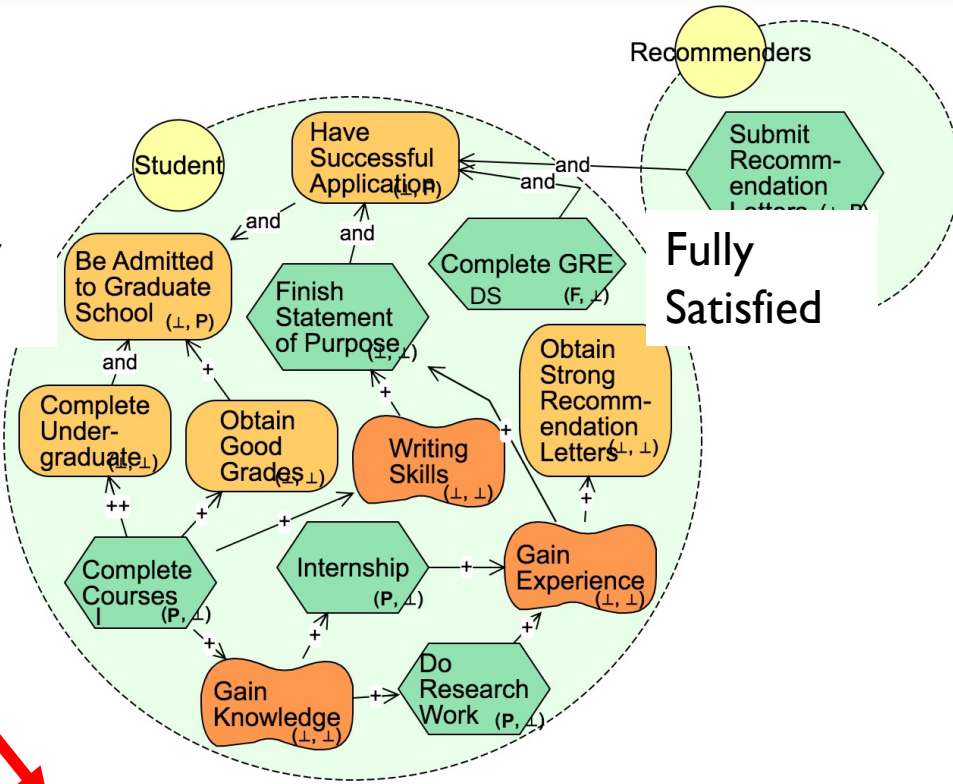
Simulate Single Path

Explore Possible Next States


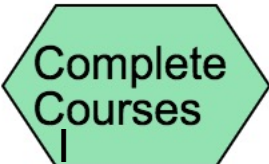


Partially Denied

Fully Satisfied

7th time point



Single Path For The Grad Model

	Time Point 6	Time Point 7	Time Point 8	Time Point 9
	(⊥, P) Partially Denied	(P, ⊥) Partially Satisfied	(P, ⊥) Partially Satisfied	(F, ⊥) Fully Satisfied
	<p>Is it possible to fulfill Internship prior to Do Research Work?</p>			(F, ⊥) Fully Satisfied
	(P, ⊥) Partially Satisfied	(P, ⊥) Partially Satisfied	(F, ⊥) Fully Satisfied	(F, ⊥) Fully Satisfied
	(⊥, F) Fully Denied	(F, ⊥) Fully Satisfied	(F, ⊥) Fully Satisfied	(F, ⊥) Fully Satisfied

New Single Paths

Be Admitted to Graduate School	(⊥, P) Partially Denied	(⊥, ⊥) No Information	(⊥, ⊥) No Information	(⊥, ⊥) No Information	(⊥, ⊥) No Information
--------------------------------	----------------------------	--------------------------	--------------------------	--------------------------	--------------------------

Be Admitted to Graduate School	(⊥, ⊥) No Information	(P, P) Conflict Value	(P, F) Conflict Value	(F, F) Conflict Value	(F, F) Conflict Value
--------------------------------	--------------------------	--------------------------	--------------------------	--------------------------	--------------------------





Be Admitted to Graduate School	(⊥, ⊥) No Information	(F, P) Conflict Value	(F, F) Conflict Value	(P, P) Conflict Value	(P, F) Conflict Value
--------------------------------	--------------------------	--------------------------	--------------------------	--------------------------	--------------------------



time

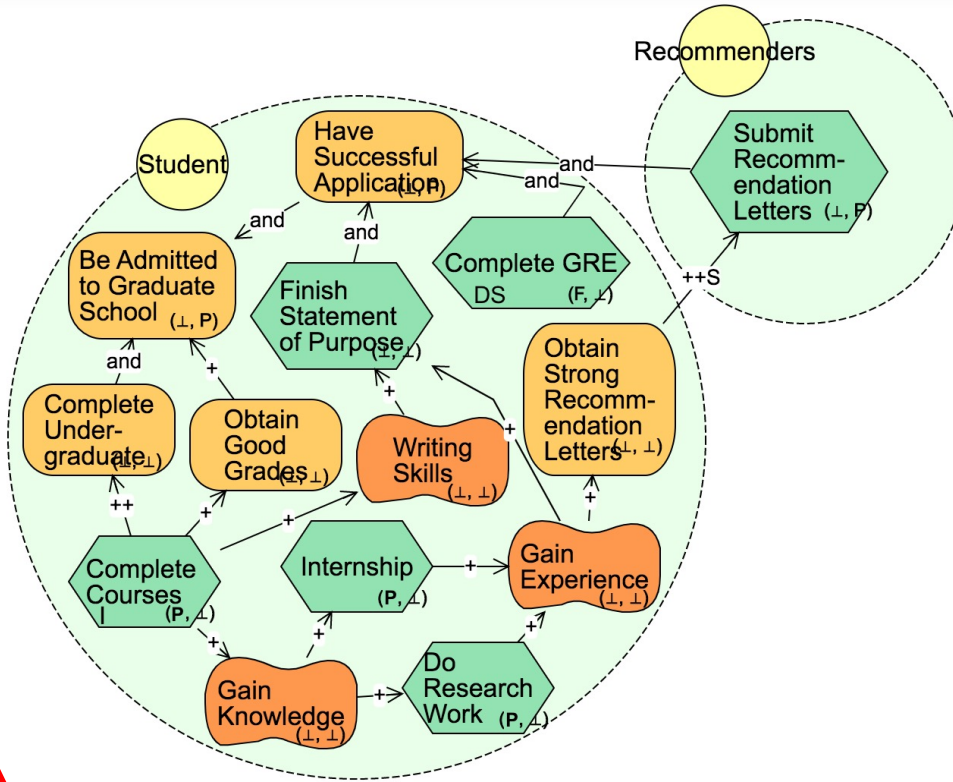
Single Path For The Grad Model

Explore all possibilities after time point 7

	Time Point 6	Time Point 7	Time Point 8	Time Point 9
	(⊥, P) Partially Denied	(P, ⊥) Partially Satisfied	(P, ⊥) Partially Satisfied	(F, ⊥) Fully Satisfied
	(P, ⊥) Partially Satisfied	(P, ⊥) Partially Satisfied	(F, ⊥) Fully Satisfied	(F, ⊥) Fully Satisfied
	(P, ⊥) Partially Satisfied	(P, ⊥) Partially Satisfied	(F, ⊥) Fully Satisfied	(F, ⊥) Fully Satisfied
	(⊥, F) Fully Denied	(F, ⊥) Fully Satisfied	(F, ⊥) Fully Satisfied	(F, ⊥) Fully Satisfied

Single Path Analysis

one possible evolution of the model over a pre-specified number of time points.



7th time point

Simulation Start: 0

Max Absolute Time

100

Conflict Prevention Level

Strong

Num Relative Time Points

10

Absolute Time Points

(e.g. 5 8 22)

View List of Assignments

View Intermediate Values

Simulate Single Path

Explore Possible Next States

Explore Next States At Time Point 7

allows users to step into any time point in the path and visualize all the possible next states

BloomingLeaf

Zoom In Zoom Out Font Size

Number of states
640
Navigate

640 !!??

Digit desired page Go

« 0 1 2
3 4 5 »

Filters

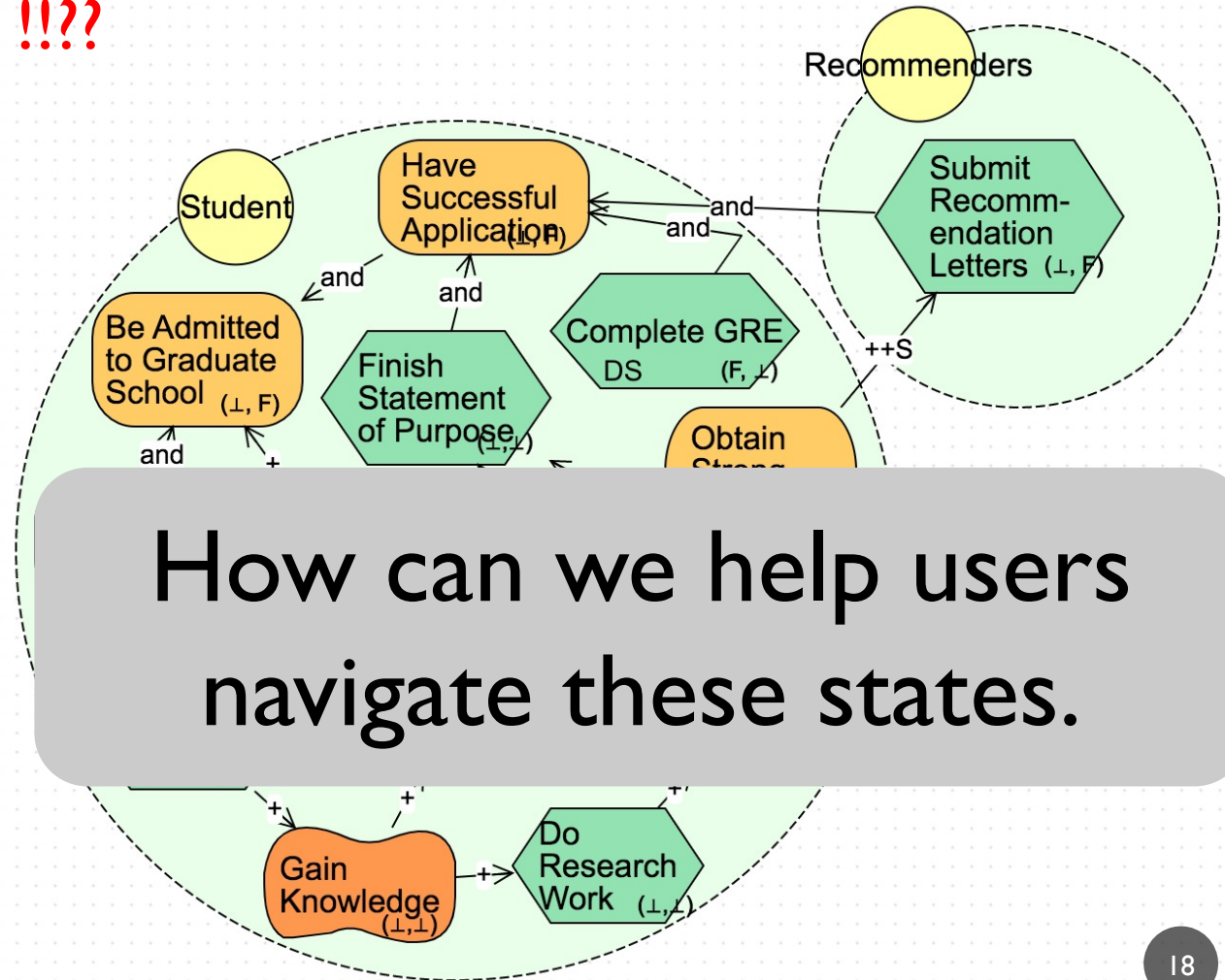
- Remove conflicts
- Remove (T,T)
- Least Task Satisfied
- Most Task Satisfied
- Least Resource Satisfied
- Most Resource Satisfied
- Least Goal Satisfied
- Most Goal Satisfied
- Least Actor Involved
- Most Actor Involved
- Satisfaction of the Most Constrained Intention

Actions

Save

Explore Next States

Close



Overview

Background

- Evidence Pairs
- Evolving Intention
- BloomingLeaf Analysis

Problems

Proposed Solution

Initial Validation

Explore Next States At Time Point 7

allows users to step into any time point in the path and visualize all the possible next states

BloomingLeaf

Zoom In Zoom Out Font Size

Number of states

640

Navigate

Digit desired page Go

« 0 1 2

3 4 5 »

Filters

- Remove conflicts
- Remove (T,T)
- Least Task Satisfied
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- Most Resource Satisfied
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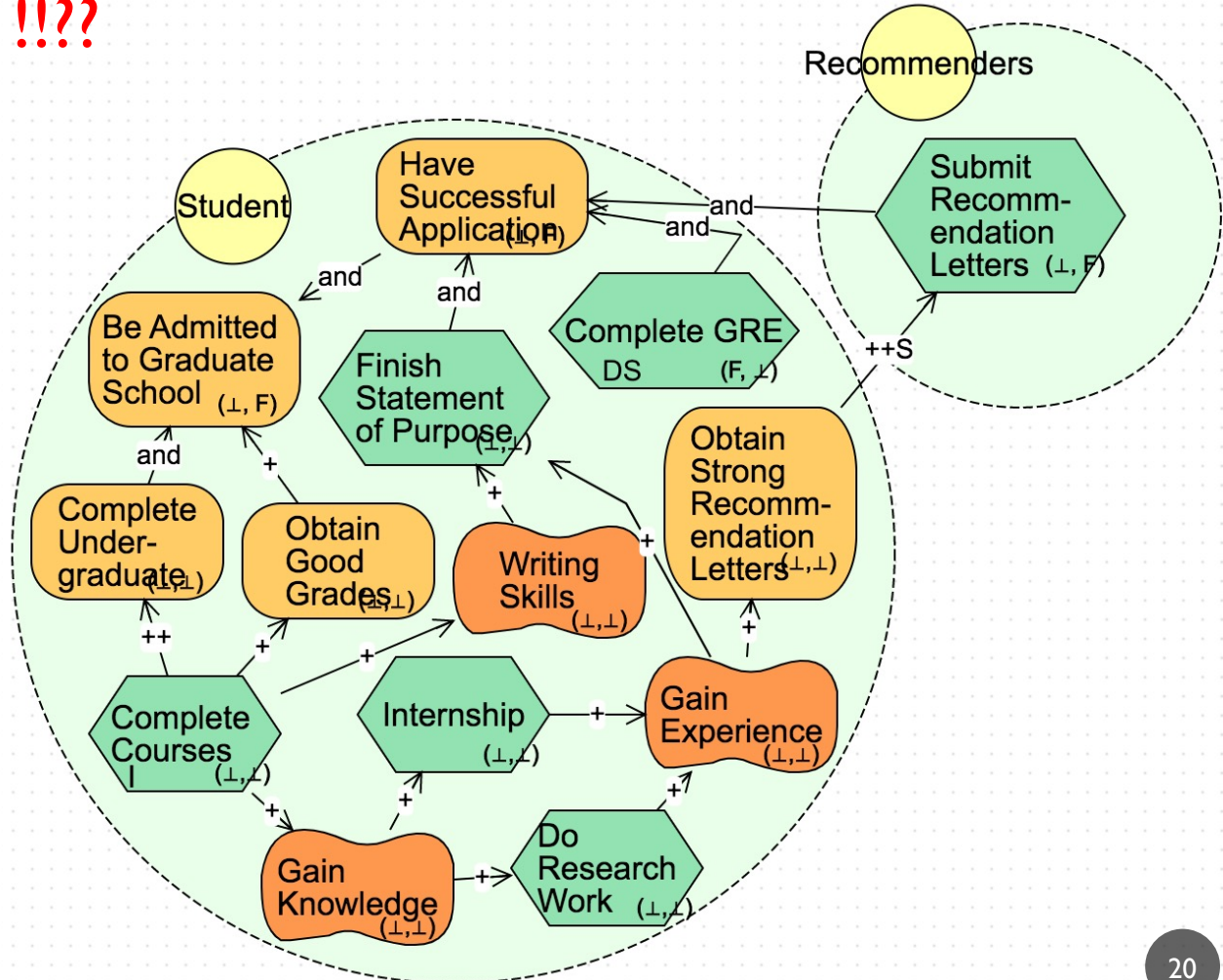
Actions

Save

Explore Next States

Close

640 !???



Solution Space Explosion Problem

- BloomingLeaf analysis uses Constraint Satisfaction Problems (CSPs)
 - CSPs often have high complexity
(Exhaustive Search -> NP-Hard)
 - Domain for each intention: 9 possible evidence pairs
 - (F, ⊥), (P, ⊥), (⊥, ⊥), (F, P), (P, P), (⊥, P), (F, F), (P, F), (⊥, F)
 - State space increases exponentially
 - Explore all possible next states is looking for all solutions
- Result: Huge solution space

Solution Space Explosion Problem

Huge solution space:

- Difficult to review
- Hard to make choices

Goal: Reduce the number of next states

Overview

Background

- Evidence Pairs
- Evolving Intention
- BloomingLeaf Analysis

Problems

- Huge solution space
- Difficult for users to review and customize

Proposed Solution

Initial Validation

Domain Reduction

Conflict Prevention:
 Remove Strong Conflict Values
 Remove Medium Conflict Values
 Remove Weak Conflict Values
Remove All Conflict Values
Remove No Information (\perp , \perp)

Analysis

Simulation Start: 0

		$s \in \{F, P, \perp\}$: for fulfillment		
		Full (F)	Partial (P)	No Evidence (\perp)
$d \in \{F, P, \perp\}$:against fulfillment	Full (F)	(F, F) 	(P, F) 	(\perp , F)
	Partial (P)	(F, P) 	(P, P) 	(\perp , P)
	No Evidence (\perp)	(F, \perp)	(P, \perp)	(\perp , \perp)

Solution Reduction

BloomingLeaf

Zoom In Zoom Out Font Size

Number of states

640

Navigate

Digit desired page

Go

« 0 1 2
3 4 5 »

Filters

- Remove conflicts
- Remove (T,T)
- Least Task Satisfied
- Most Task Satisfied
- Least Resource Satisfied
- Most Resource Satisfied
- Least Goal Satisfied
- Most Goal Satisfied
- Least Actor Involved
- Most Actor Involved
- Satisfaction of the Most Constrained Intention

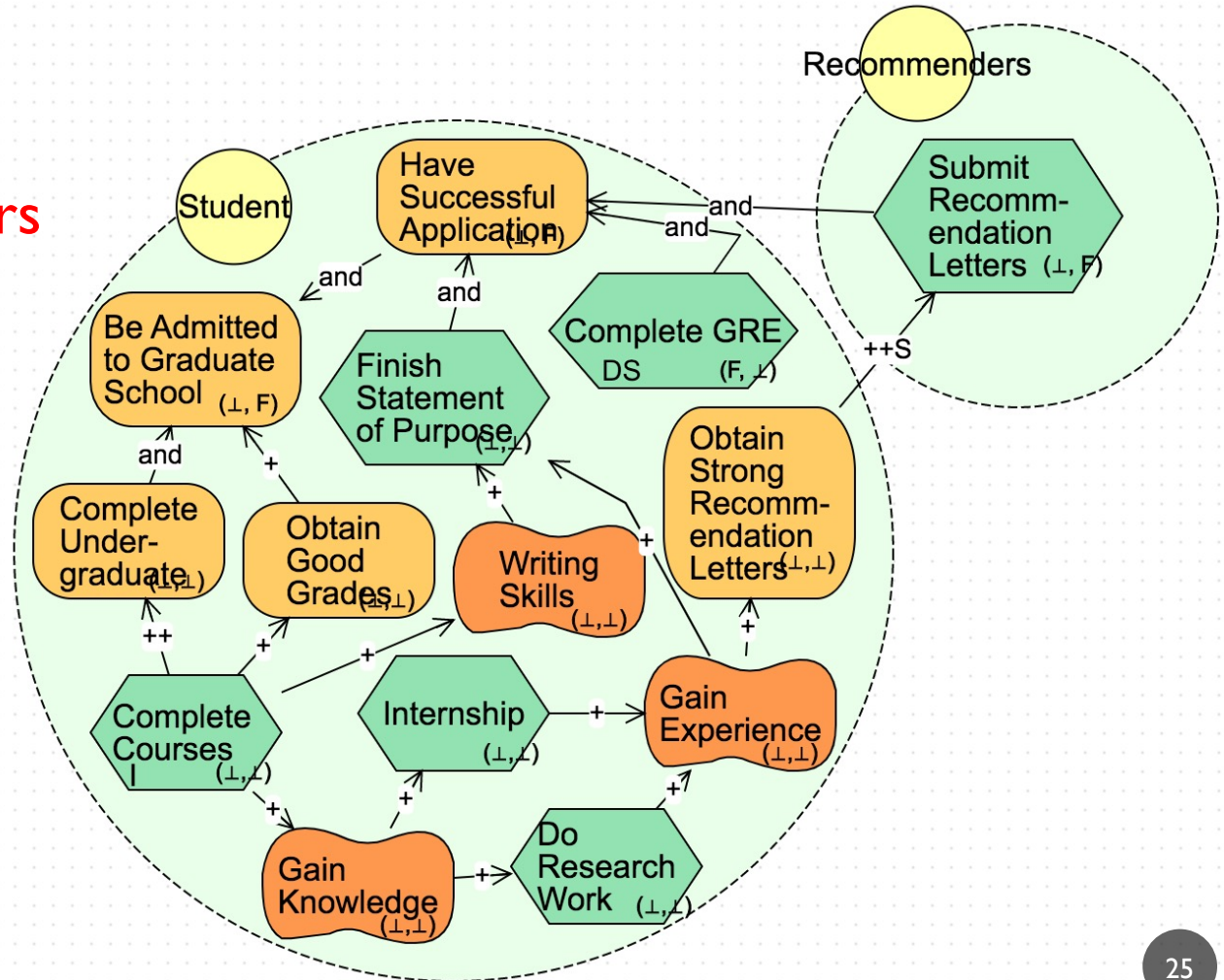
Actions

Save

Explore Next States

Close

Filters



Filters

Number of states
640
Navigate

Digit desired page Go

« 0 1 2
3 4 5 »

Filters

- Remove conflicts
- Remove (T,T)
- Least Task Satisfied
- Most Task Satisfied
- Least Resource Satisfied
- Most Resource Satisfied
- Least Goal Satisfied
- Most Goal Satisfied
- Least Actor Involved
- Most Actor Involved
- Satisfaction of the Most Constrained Intention

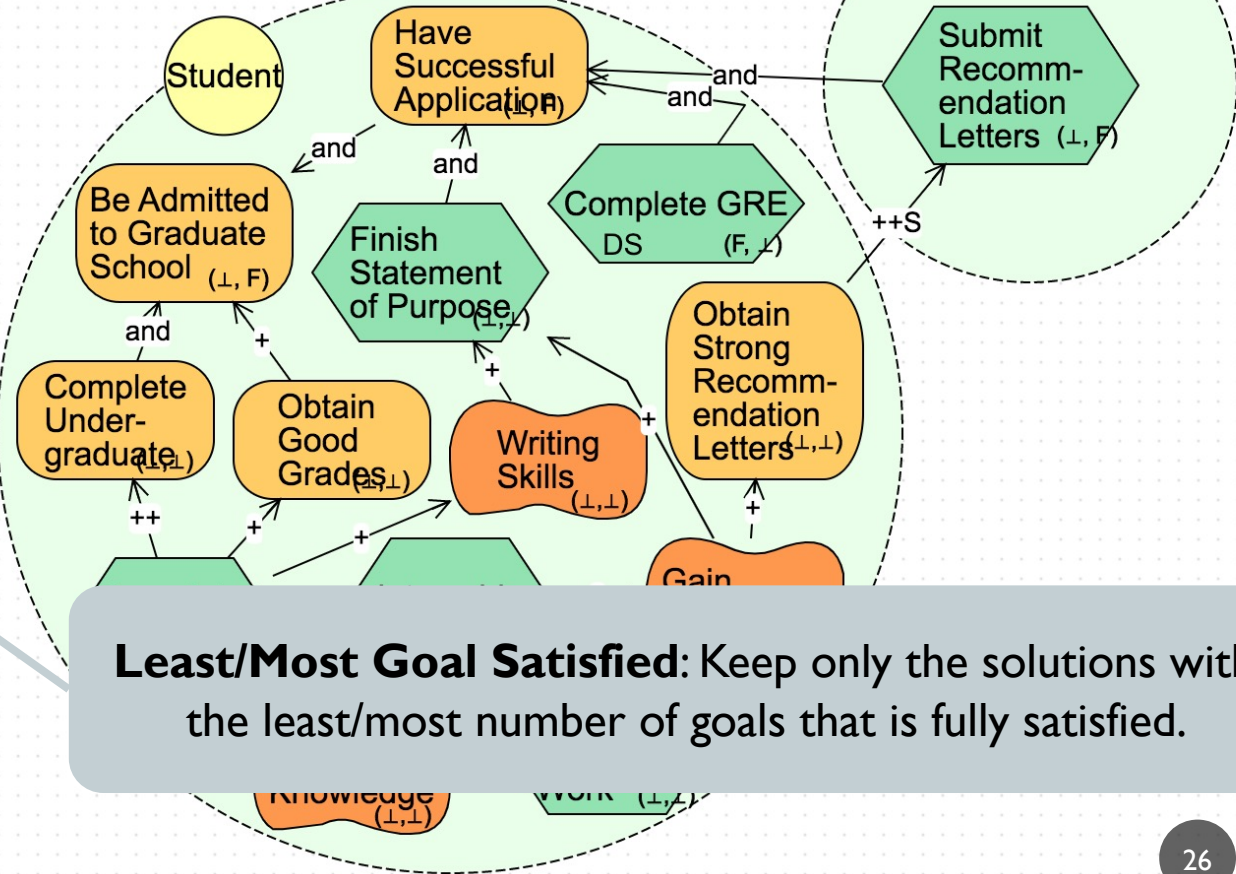
Actions

Save

Explore Next States

Close

Remove Conflicts, Remove (\perp , \perp): Also Filters



Least/Most Goal Satisfied: Keep only the solutions with the least/most number of goals that is fully satisfied.

Filters

Name	Description	Example Usage
Least/Most Tasks Satisfied	Keep only the solutions with the least/most number of tasks with the evaluation label satisfied (F, \perp).	In the GRAD example, if the student is looking for the minimum number of tasks he needs to complete to be admitted to graduate school.
Least/Most Goals Satisfied	Keep only the solutions with the least/most number of goals with the evaluation label satisfied (F, \perp).	This would be useful for the student in the GRAD example to view the worst case and best case scenario.
Least/Most Resources Satisfied	Keep only the solutions with the least/most number of resources with the evaluation label satisfied (F, \perp).	Consider a business person making budgets of all the resources he needs, <i>Least Resources Needed</i> would give a lower bound estimation and <i>Most Resources Needed</i> would give an upper bound.
Least/Most Actors Involved	Keep only the solutions with the least/most number of actors involved. An actor is involved when at least one of their intentions is satisfied.	In the GRAD example, if the student were to ask whether he can finish the entire application process all by himself.
Satisfaction of the Most Constrained Goal	Keep only the solutions with the status of the most constrained goal being satisfied. Most constrained goals are goals with the smallest domain in the model.	This usually helps when users want to explore the satisfiability of some or all goals in the model.

Filters

BloomingLeaf

Zoom In Zoom Out Font Size

Number of states

32

← 640 to 32

Navigate

Digit desired page

Go

« 0 1 2
3 4 5 »

Filters

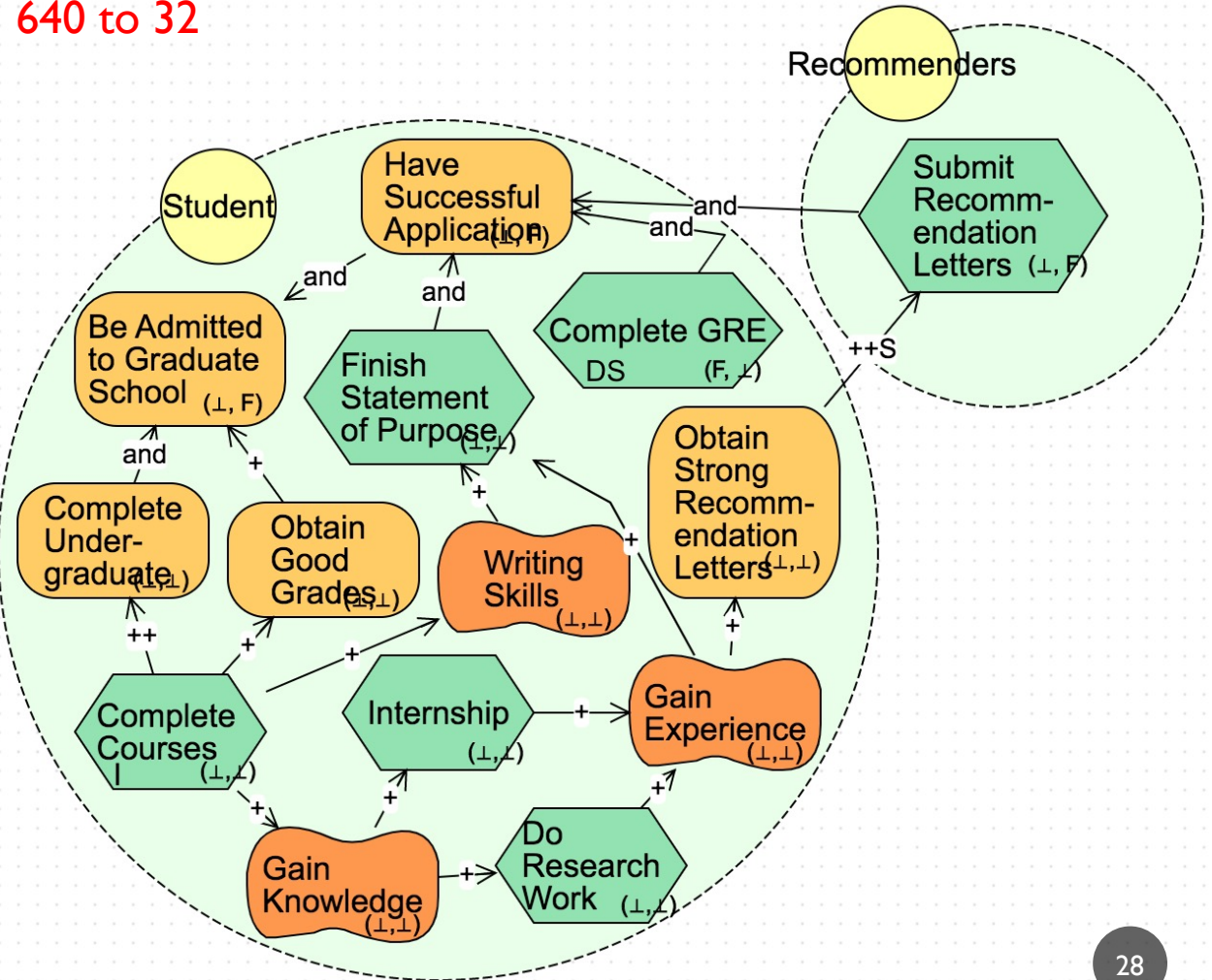
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- Most Resource Satisfied
- Least Goal Satisfied
- Most Goal Satisfied
- Least Actor Involved
- Most Actor Involved
- Satisfaction of the Most Constrained Intention

Actions

Save

Explore Next States

Close



Select A State

Is it possible to fulfill Internship prior to Do Research Work? **YES!**

	Time Point	Time Point 7	Time Point 8
Internship	Denied	(P, ⊥) Partially Satisfied	(F, ⊥) Fully Satisfied
Be Admitted to Graduate School		(P, ⊥) Partially Satisfied	(P, ⊥) Partially Satisfied

Is it possible to satisfy Be Admitted to Graduate School if Internship is fulfilled prior to Do Research Work?

Let's complete the path and find out

same as old path

new state the student selected

Answering student question...

BloomingLeaf

Zoom In Zoom Out Open as SVG Font Size Help Model

History Log

Step 1: Single Path

Step 2: Single Path

Analysis

Analysis

Simulation Start: 0

Max Absolute Time

100

Conflict Prevention Level

Remove All

Num Relative Time Points

10

Absolute Time Points

(e.g. 5 8 22)

View List of Assignments

View Intermediate Values

Simulate Single Path

Explore Possible Next States

Is it possible to satisfy Be Admitted to Graduate School if Internship is fulfilled prior to Do Research Work? **YES!**



11|97



Overview

Background

- Evidence Pairs
- Evolving Intention
- BloomingLeaf Analysis

Problems

- Huge solution space
- Difficult for users to review and customize

Proposed Solution

- Domain Reduction
- Solution Reduction

Initial Validation

Research Questions

- (RQ1) To what extent does the filters approach reduce computation time and the number of returned states?
- (RQ2) To what extent do users find this approach helpful?

(RQ1) To What Extent Does The Filters Approach Reduce Computation Time And The Number Of Returned States?

GRAD
BLE [11]
WME [11]
Scheduler [14]
Spadina Plan
Spadina Opp
Spadina Pro
Bike Lanes Full

Model Name	GRAD	BLE [11]	WME [11]	Scheduler [14]	Spadina Plan	Spadina Opp	Spadina Pro	Bike Lanes Full
Num. of States								30
Num. of Solutions								37
Meas.								
Exp								152
Rem								0
Rem								056
Mo								152
Lea								152
Mo								152
Lea								152
Mo								152
Lea								152
Mo								58
Leas								448
Satisfac								51152

Finding: The applicability of each filter varied based on the model structure, but overall applying solution reduction filters reduced the number of returned states and computation time

Measurement	Computation Time in milliseconds							
Explore Possible Next States - No Pref.	131	119	286	317	88	388	96	4141
Remove All Conflict Values	121	47	N/A	187	N/A	N/A	92	N/A
Remove No None	97	N/A	226	173	86	N/A	89	1444

N/A indicates that no measurement was collected because the model was over-constrained.

(RQ2) To What Extent Do Users Find This Approach Helpful?

Participants:

Five volunteers at the University of Toronto Software Engineering group

Observations:

1. Most time spent on selecting filters
2. All of the volunteers agreed that the filters saved them time and effort.

Findings:

1. Strengthened our hypothesis that filters are useful
2. Volunteers suggested significant tool improvements

Further empirical research is required to validate the usefulness of filters.

Summary

- We presented **Filters**:
 - **Reduce the state space** of the Explore Possible Next States analysis
 - **Help users review and customize** their simulation path.

Future Work

- **Guide users in selecting the most appropriate filters**
- Allow users to update the evidence pair assignments to further prune the solution space
- Validate the effectiveness of our approach with goal model users

SUPPORT FOR USER GENERATED EVOLUTIONS OF GOAL MODELS

Thank you!

Tool:

[http://www.cs.toronto.edu/~amgrubb/
dev/blooming/](http://www.cs.toronto.edu/~amgrubb/dev/blooming/)

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