## **Invertible Residual Networks**

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## What are Invertible Neural Networks?

Invertible Neural Networks (INNs) are bijective function approximators which have a **forward mapping** 

 $F_{\theta} : \mathbb{R}^d \to \mathbb{R}^d$  $x \mapsto z$ 

and an inverse mapping

$$F_{\theta}^{-1} : \mathbb{R}^d \to \mathbb{R}^d$$
$$z \mapsto x$$





# Why Invertible Networks?

- Mostly known because of Normalizing Flows
  - Training via maximum-likelihood and evaluation of likelihood



Generated samples from GLOW (Kingma et al. 2018)





# Why Invertible Networks?

- Generative modeling via invertible mappings with exact likelihoods (Dinh et al. 2014, Dinh et al. 2016, Kingma et al. 2018, Ho et al. 2019)
  - Normalizing Flows
- Mutual information preservation

 $I(Y;X) = I(Y;F_{\theta}(X))$ 

- Analysis and regularization of invariance (Jacobsen et al. 2019)
- Memory-efficient backprop (Gomez et al. 2017)
- Analyzing inverse problems (Ardizzone et al. 2019)

Workshop: Invertible Networks and Normalizing Flows





#### Invertible Networks use Exotic Architectures

- Dimension partitioning and coupling layers (Dinh et al. 2014/2016, Gomez et al. 2017, Jacobsen et al. 2018, Kingma et al. 2018)
  - Transforms one part of the input at a time
  - Choice of partitioning is important





#### Invertible Networks use Exotic Architectures

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  - Transforms one part of the input at a time
  - Choice of partitioning is important
- Invertible dynamics via Neural ODEs (Chen et al. 2018, Grathwohl et al. 2019)
  - Requires numerical integration
  - Hard to tune and often slow due to need of ODE-solver



Why do we move away from standard architectures?

- Partitioning, coupling layers, ODE-based approaches move further away from standard architectures
  - Many new design choices necessary and not well understood yet
- Why not use most successful discriminative architecture?

ResNets

• Use connection of ResNet and Euler integration of ODEs (Haber et al. 2018)



# Making ResNets invertible

**Theorem** (sufficient condition for invertible residual layer): Let  $F_{\theta}^{t}(x) = x + g_{\theta}^{t}(x)$  be a residual layer, then it is invertible if

$$\operatorname{Lip}(g_{\theta}^t) < 1$$

where

$$||g(x) - g(y)||_2 \le \operatorname{Lip}(g)||x - y||_2$$



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#### Invertible Residual Networks (i-ResNet)

$$F_{\theta} = F_{\theta}^T \circ \cdots \circ F_{\theta}^1$$



# i-ResNets: Constructive Proof

**Theorem:** (invertible residual layer) Let F(x) = x + g(x) be a residual layer, then it is invertible if  $\operatorname{Lip}(g) < 1$ 

#### **Proof:**

Features:

$$z := F(x)$$

Fixed-point equation: x = z - g(x)



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 $\rightarrow$  Use fixed-point iteration:

$$x^{(0)} = z$$

 ${\mathcal X}$ 

$$x^{(i+1)} = z - g(x^{(i)})$$



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 $\rightarrow$  Guaranteed convergence to x if g contractive (Banach fixed-point theorem)

# Inverting i-ResNets

- Inversion method from proof
- Fixed-point iteration:

– Init:

$$x^{(0)} = z$$

- Iteration:

$$x^{(i+1)} = z - g(x^{(i)})$$



# Inverting i-ResNets



- Rate of convergence depends on Lipschitz constant
- In practice: cost of inverse is 5-10 forward passes

Fixed-point Iterations

# How to build i-ResNets

• Satisfy Lip-condition: data-independent upper bound

 $g = W_3 \circ \phi \circ W_2 \circ \phi \circ W_1 \circ \phi$ 

 $\operatorname{Lip}(g) \le \|W_3\|_2 \cdot \|W_2\|_2 \cdot \|W_1\|_2$ 



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• Spectral normalization (Miyato et al. 2018, Gouk et al. 2018)  $ilde{W} = c \frac{W}{\hat{\sigma_1}}, \quad 0 < c < 1$ 

 $\hat{\sigma_1}$  approx of largest singular value via power-iteration



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```
def invertible_residual_block(self):
    layers = []
    layers.append(nn.ReLU)
    layers.append(spectral_norm(nn.Linear(in_dim, hidden_dim)))
    layers.append(nn.ReLU)
    layers.append(spectral_norm(nn.Linear(hidden_dim, in_dim)))
```



# Validation

• Reconstructions



CIFAR10 Data

Reconstructions: i-ResNet

Reconstructions: standard ResNet



# **Classification Performance**

		ResNet-164	Vanilla	c = 0.9
Classification	MNIST	-	0.38	0.40
Error %	CIFAR10	5.50	6.69	6.78
	CIFAR100	24.30	23.97	24.58
Guaranteed Inverse		No	No	Yes

- Competetive performance
- But what do we get additionally?

Generative models via Normalizing Flows



#### Maximum-Likelihood Generative Modeling with i-ResNets

• We can define a simple generative model as

 $z \sim p_Z(z)$  $x = F_{\theta}^{-1}(z)$ 

Gaussian distribution



 $\mathcal{Z}$ 





 ${\mathcal X}$ 

Data distribution



#### Maximum-Likelihood Generative Modeling with i-ResNets

• We can define a simple generative model as

 $z \sim p_Z(z)$  $x = F_{\theta}^{-1}(z)$ 

 Maximization (and evaluation) of likelihood via change-of-variables

 $\log p_X(x) = \log p_Z(F_\theta(x)) + \log |\det J_{F_\theta}(x)|$ 

#### ... if $F_{\theta}$ is invertible



Gaussian distribution



Data distribution

 $\mathcal{Z}$ 

 $F_{\theta}^{-1}(z)$ 

 $\mathcal{X}$ 

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#### Maximum-Likelihood Generative Modeling with i-ResNets

 Maximization (and evaluation) of likelihood via change-of-variables

 $\log p_X(x) = \log p_Z(F_\theta(x)) + \log |\det J_{F_\theta}(x)|$ 

- ... if  $F_{\theta}$  is invertible
- Challenges:
  - Flexible invertible models
  - Efficient computation of log-determinant

Gaussian distribution



 $\mathcal{Z}$ 





X

Data distribution

# Efficient Estimation of Likelihood

• Likelihood with log-determinant of Jacobian

 $\log p_X(x) = \log p_Z(F_\theta(x)) + \log |\det J_{F_\theta}(x)|$ 

- Previous approaches:
  - exact computation of log-determinant via constraining architecture to be triangular (Dinh et al. 2016, Kingma et al. 2018)
  - ODE-solver and estimation only of trace of Jacobian (Grathwohl et al. 2019)
- We propose an **efficient estimator for i-ResNets** based on trace-estimation and truncation of a power series



## **Generative Modeling Results**





Data Samples

GLOW





## **Generative Modeling Results**







GLOW



i-ResNets









# **Generative Modeling Results**

Method	MNIST	CIFAR10
NICE (Dinh et al., 2014)	4.36	4.48†
MADE (Germain et al., 2015)	2.04	5.67
MAF (Papamakarios et al., 2017)	1.89	4.31
Real NVP (Dinh et al., 2017)	1.06	3.49
Glow (Kingma & Dhariwal, 2018)	1.05	3.35
FFJORD (Grathwohl et al., 2019)	0.99	3.40
i-ResNet	1.06	3.45



GLOW (Kingma et al. 2018)

Invertible Residual Networks

FFJORD (Grathwohl et al. 2019)

i-ResNet





# i-ResNets Across Tasks

 i-ResNet as an architecture which works well both in discriminative and generative modeling

Affine Glow $1 \times 1$ Conv	Additive Glow	i-ResNet	i-ResNet
	Reverse	Glow-Style	164
12.63	12.36	8.03	6.69

- i-ResNets are generative models which use the best discriminative architecture
- Promising for:
  - Unsupervised pre-training
  - Semi-supervised learning



# Drawbacks

- Iterative inverse
  - Fast convergence in practice
  - Rate depends on Lip-constant and not on dimension

- Requires estimation of log-determinant
  - Due to free-form of Jacobian
  - Properties of i-ResNets allows to design efficient estimator



# Conclusion

- Simple modification makes ResNets invertible
- Stability is guaranteed by construction
- New class of likelihood-based generative models

   without structural constraints
- Excellent performance in discriminative/ generative tasks
  - with one unified architecture
- Promising approach for:
  - unsupervised pre-training
  - semi-supervised learning
  - tasks which require invertibility

## See us at Poster #11 (Pacific Ballroom)









Code:





Invertible Residual Networks





Follow-up work:

Residual Flows for Invertible Generative Modeling

Invertible Networks and Normalizing Flows, workshop on Saturday (contributed talk)