

# A NEW REPRESENTATION OF THE RATIONAL NUMBERS FOR FAST EASY ARITHMETIC

E. C. R. HEHNER and R. N. S. HORSPOOL

**Abstract.** A novel system for representing the rational numbers based on Hensel's  $p$ -adic arithmetic is proposed. The new scheme uses a compact variable-length encoding that may be viewed as a generalization of radix complement notation. It allows exact arithmetic, and approximate arithmetic under programmer control. It is superior to existing coding methods because the arithmetic operations take particularly simple, consistent forms. These attributes make the new number representation attractive for use in computer hardware.

**Key words.** number systems, number representation, rational arithmetic,  $p$ -adic numbers, radix complement, floating-point

**1. Introduction.** “It's very illuminating to think about the fact that some –at most four hundred– years ago, professors at European universities would tell the brilliant students that if they were very diligent, it was not impossible to learn how to do long division. You see, the poor guys had to do it in Roman numerals. Now, here you see in a nutshell what a difference there is in a good and bad notation.” (Dijkstra 1977)

We consider that a good scheme for representing numbers, especially for computers, would have the following characteristics.

(a) All rational numbers are finitely representable. This requires that the representation be variable-length.

(b) The representation is compact. It should require less space, on average, than the fixed-length schemes commonly used in computers. Since the numbers provided by a fixed-length representation are not used equally often, compactness can be achieved by giving frequently-occurring numbers short encodings at the expense of longer encodings for less-frequent numbers.

(c) The addition, subtraction, and multiplication algorithms are those of the usual integer arithmetic. The division algorithm is as easy as multiplication, and it proceeds in the same direction as the other three algorithms. This property is important for the storage and retrieval of variable-length operands and results.

Although the desired representation is variable-length, there is no implication that operations must be performed serially by digit. Just as data can be retrieved and stored  $d$  digits at a time, so the arithmetic unit can be designed to perform operations  $d$  digits at a time. By choosing  $d$  to be large compared to the average length of operands, we can obtain the speed of a fixed-length design together with the ability to handle operands that are not representable in a fixed length (Wilner 1972).

**2. Background.** Before we present our proposal, we shall briefly review representations in common use. (For their history, see (Knuth 1969a).)

Almost universally, the sequence of digits

$$\cdots d_i \cdots d_3 d_2 d_1 d_0$$

is used to represent the nonnegative integer

$$n = \sum_i d_i b^i$$

where  $b$  (the base) is an integer greater than one (usually two or ten), and each digit  $d_i$ , represents an integer in the range  $0 \leq d_i < b$ . As a rule, we do not write leading 0s. We must break the rule, however, to represent zero (if we follow it, there is nothing to write).

There is no direct representation of negative integers in common use. Instead we prefix a unary operator to the representation of positive integers. The combination of “sign and magnitude” is indirect because, to perform arithmetic, we may first have to apply some algebraic transformations. If asked to add two numbers, we first examine the signs to determine whether to use the addition or subtraction algorithm; if we are using the subtraction algorithm, we compare the magnitudes to determine which is to be subtrahend, and which minuend. With a direct representation, if asked to add, we simply add. The radix complement representation is direct in this sense, but it includes only a finite subset of the integers.

Rationals are commonly represented by a pair of integers: a numerator and denominator. In this form, multiplication and division are reasonably easy, but addition and subtraction are relatively hard, and normalization is difficult (Horn 1977). When addition and subtraction are wanted more often than multiplication and division, a representation that makes the former easier at the expense of the latter would be preferable. For this reason, we usually restrict our numbers to a subset of the rationals known as the “fixed-point” or “floating-point” numbers. By inserting a radix point in a sequence of digits (fixed-point), or indicating by means of an exponent where a radix point should be placed (floating-point), we represent those rationals such that, in lowest terms, the denominator divides some power of the base. In this form, addition and subtraction are, after alignment of the radix point, the same as for integers. With a variable-length representation, a major difficulty with the usual division algorithm is that it proceeds from left to right, opposite to the direction of the other three algorithms. To simplify retrieval, processing, and storage, all algorithms should examine their operands and produce their results in the same direction.

The left-to-right division algorithm gives us a way of extending the fixed/floating point representation to include all positive rationals: an infinite but eventually repeating sequence of digits can be finitely denoted by indicating the repeating portion. On paper, the repeating portion is sometimes denoted by overscoring it; for example,  $611/495 = 1.2\overline{34}$ . A minor annoyance is the fact that representations are not unique; for example,  $0.\overline{9} = 1$  and  $0.4\overline{9} = 0.5$ . A major annoyance is that further arithmetic is awkward: addition normally begins with the rightmost digit, but a sequence that extends infinitely to the right has no rightmost digit.

The usual representation of nonnegative integers can be extended in various ways. The base may be negative (Songster 1963), or even imaginary (Knuth 1960). In the “balanced ternary” representation (Avizienis 1971), the base is three, and the digits represent the integers minus-one, zero, and one. Our extension, which we now present, is in quite a different direction.

**3. Constructing the representation.** To construct our representation, we shall follow the approach of Hensel's  $p$ -adic arithmetic (Hensel 1908, 1913). Hensel begins with the usual representation of nonnegative integers, that is, a sequence of digits  $\cdots d_3 d_2 d_1 d_0$ . Each digit  $d_i$  represents an integer in the range  $0 \leq d_i < b$ , where the base  $b$  is an integer greater than one. He then constructs the representation of other numbers (all rationals, some irrationals and some

imaginary numbers (Knuth 1969b)) by means of arithmetic. We shall limit ourselves to rational numbers, and give a finite representation of them that is implementable in computer hardware.

**3.1. Addition, subtraction and multiplication.** For the addition and subtraction algorithms, we adopt the usual algorithms for positive integers, with one qualification. When subtracting a digit of the subtrahend from a smaller digit of the minuend, rather than “borrow” one from a minuend digit some distance away, we “carry” one to the immediately neighboring digit of the subtrahend. For example,

$$\begin{array}{r} 27004 \\ - 3151216 \\ \hline 23478 \end{array}$$

beginning at the right, we subtract 6 from 4 to get 8 with a carry; then, rather than subtracting the 2 in the next position, we subtract 3 from 0 to get 7 with a carry; etc. Whether we “carry” or “borrow” is inconsequential; the important point is that we affect only the immediately neighboring digit, not a digit an arbitrary distance away. This form of subtraction is usual in circuit design; it is crucial to our number representation.

We now construct minus-one by subtracting one from zero.

$$\begin{array}{r} \dots 0000 \\ - \dots 0101011 \\ \hline \dots 9999 \end{array}$$

Beginning at the right, the subtraction algorithm generates a sequence of 9s. Though the sequence is unending, it is repetitive, and can be specified finitely. We shall use a quote (quotation mark) to mean that the digit(s) to its left is (are) to be repeated indefinitely to the left. Twenty-five, for example, is represented by 0'25 or by 0'025 or by 00'25. The first of these is called “normalized”; in general, a representation is normalized when it is as short as possible. A table of normalized representations of integers follows; each entry specifies the usual representation together with our representation.

	0: 0'	
1:	0'1	-1: 9'
2:	0'2	-2: 9'8
3:	0'3	-3: 9'7
:		:
9:	0'9	-9: 9'1
10:	0'10	-10: 9'0
11:	0'11	-11: 9'89
:		:

For brevity on the written page (the abbreviation is inapplicable in computer memories), we make the convention that when no quote appears in a number, 0' is assumed to be appended to its left. Thus the positive integers take their familiar form.

The reader may verify, with examples, that the addition and subtraction algorithms work consistently throughout the scheme. This is no surprise to anyone familiar with radix

complement arithmetic, for the similarity is apparent. The rule for negation is the radix complement rule: complement each digit (in decimal, change 0 to 9, 1 to 8, 2 to 7, etc.) and then add one. (Negation can be performed more simply; for example, in binary starting at the right, leave trailing 0s and rightmost 1 alone, flip the rest.) The definition of radix complement is made in terms of a fixed-size space available for storing numbers in computers (the “word”); for example, if  $w$  bits are available for encoding integers, two's complement is defined by performing arithmetic modulo  $2^w$ . We prefer to define it independent of space constraints, and to view the fixed-size scheme as a truncation of  $p$ -adic numbers to  $w$  bits. Radix complement is often preferred in computers because of its nice arithmetic properties; our finite representation of  $p$ -adic rationals enjoys these properties without suffering from the wasted space and overflow problems inherent in a fixed-length representation.

The usual multiplication algorithm need not be altered for use with negative integers. For example, multiplying minus-two by three, either way round, yields the desired result.

$$\begin{array}{r}
 9'8 \\
 * \quad 3 \\
 \hline
 9'4
 \end{array}
 \qquad
 \begin{array}{r}
 \qquad \qquad 3 \\
 \qquad * \quad 9'8 \\
 \hline
 \qquad \quad 2'4 \\
 \qquad \quad 2'7 \\
 \qquad \quad 2'7 \\
 \qquad \quad \vdots \\
 \qquad \quad \vdots \\
 \hline
 \qquad \quad 9'4
 \end{array}$$

**3.2 Division.** Before we present the division algorithm, let us look at a simple example. Since  $9'$  represents minus-one, we may expect division by 3 to give  $3'$  as the representation of minus-one-third. Let us test the consistency of this representation with our arithmetic. To negate, we first complement, obtaining  $6'$  (since  $6'$  is double  $3'$ , it represents minus-two-thirds); then we add one, obtaining  $6'7$  as our representation of one-third. Subtracting  $3'$  from  $0'$  also produces  $6'7$ . Multiplying  $6'7$  by 3 yields 1, confirming its consistency.

$$\begin{array}{l}
 0' - 1 = 9' \quad (\text{minus-one}) \\
 9' \div 3 = 3' \quad (\text{minus-one-third}) \\
 \text{complement of } 3' = 6' \\
 \text{or} \quad 3' * 2 = 6' \quad (\text{minus-two-thirds}) \\
 \quad \quad 6' + 1 = 6'7 \quad (\text{one-third}) \\
 \text{or} \quad 0' - 3' = 6'7 \\
 \quad \quad 6'7 * 3 = 1
 \end{array}$$

We now present the division algorithm by means of an example. For the moment, we restrict ourselves to integer dividends and divisors, and further to divisors whose rightmost digit is nonzero and relatively prime to the base. (Two integers are relatively prime if and only if their only common divisor is 1. In decimal, the divisor's final digit must be 1, 3, 7, or 9.) We shall remove all restrictions shortly.

For our example, we divide 191 by 33. The rightmost digit of the result,  $d_0$ , when multiplied by the rightmost digit of the divisor, 3, must produce a number whose rightmost digit

is the rightmost digit of the dividend, 1. Our restrictions ensure that there is exactly one such digit:  $d_0 * 3$  must end with 1, therefore  $d_0 = 7$ . We subtract  $7 * 33$  from 191; ignoring the rightmost digit, which must be 0, we use the difference in place of the dividend, and repeat.

$$\begin{array}{r}
 191 \div 33 = 12'7 \\
 - 231 \\
 \hline
 9'6 \\
 - 66 \\
 \hline
 9'3 \\
 - 33 \\
 \hline
 9'6
 \end{array}$$

When the difference is one we have seen before, we can insert the quote, and stop.

Like multiplication, the division algorithm produces each digit by table look-up. Compare this with the left-to-right division algorithm: a “hand calculation” requires a guess that may need to be revised; a “machine calculation” requires repeated subtraction to produce each digit of the result.

The right-to-left division algorithm is well-defined only when the divisor's final digit is relatively prime to the base. For example, an attempt to divide 1 by 2 in decimal fails because no multiple of 2 has 1 as its final digit. Therefore, the means presented so far enable us to represent only a subset of the rationals: those rationals such that, in lowest terms, the denominator has no factors that are factors of the base. Compare this with the fixed/floating-point representation; it represents those rationals such that, in lowest terms, the denominator has only factors that are factors of the base. The two representations are, in a sense, complementary; combining them, we are able to represent all rationals. We allow a radix point, whose position is independent of the quote, or an exponent, as in scientific notation. For example,

$$\begin{aligned}
 12'34 \div 10 &= 12'3.4 \\
 12'3.4 \div 10 &= 12!34 \\
 12!34 \div 10 &= 1.2'34 \\
 1.2'34 \div 10 &= .12'34 \\
 .12'34 \div 10 &= .21'234
 \end{aligned}$$

The last example is probably best written with an exponent, and suggests that the more appropriate machine representation uses an exponent rather than a radix point. This requires a normalization rule: when normalized, the mantissa's rightmost digit is not 0. Thus 12'300E2 becomes 12'3E4, and 120'E2 becomes 012'E3. All rationals except zero have a unique normalized representation.

To divide two arbitrary integers in decimal, we must first “cast out” all 2 and 5 factors from the divisor. These factors can be determined, one at a time, by inspecting the divisor's final digit. A 2 is cast out by multiplying both dividend and divisor by 5; similarly, a 5 is cast out with a multiplication by 2. The generalization to arbitrary (rational) operands is now easy.

**4. Binary is beautiful.** Base two, a common choice in computers for circuit reasons, has two important advantages for us. First, it is a prime number. Since it has no factors, there is no “casting out”; division of two normalized operands can always proceed directly. Second, multiplication and division tables are trivial. This advantage for multiplication is well-known: the right-to-left division algorithm is a true analogue of multiplication, so the same advantage applies. At each step, the rightmost bit of the dividend remaining

- (a) is the next bit of the result, and
- (b) specifies whether or not to subtract the divisor.

For example, dividing 1 (one) by 11 (three) proceed as follows.

$$\begin{array}{r}
 1 \div 11 = 01'1 \\
 - 11 \\
 \hline
 1' \\
 - 11 \\
 \hline
 1'0
 \end{array}$$

1. Dividend = 1. Its rightmost bit = 1. Therefore
  - (a) Rightmost bit of result = 1.
  - (b) Subtract divisor, and ignore rightmost 0.
2. Dividend remaining = 1'. Its rightmost bit = 1. Therefore
  - (a) Next bit of result = 1.
  - (b) Subtract divisor, and ignore rightmost 0.
3. Dividend remaining = 1'0. Its rightmost bit = 0. Therefore
  - (a) Next bit of result = 0.
  - (b) Do not subtract divisor; ignore rightmost 0.
4. Dividend remaining = 1' as in step 2. Therefore insert quote. Result = 01'1.

**5. Radix conversion algorithm.** The algorithm for converting the representation of a positive integer from one base to another is well-known. The given integer is repeatedly divided by the base of the new representation; the sequence of remainders gives, from right to left, the digits of the new representation. For example, converting eleven from decimal to binary

$$\begin{array}{l}
 11 = 2*5+1 \\
 5 = 2*2+1 \\
 2 = 2*1+0 \\
 1 = 2*0+1
 \end{array}$$

gives 1011. The algorithm is usually considered to terminate when the quotient is zero; if it is allowed to continue, an endless sequence of 0s is produced.

Let us apply the algorithm to a negative integer. For example, converting minus-eleven from decimal to binary

$$\begin{aligned}
-11 &= 2 * -6 + 1 \\
-6 &= 2 * -3 + 0 \\
-3 &= 2 * -2 + 1 \\
-2 &= 2 * -1 + 0 \\
-1 &= 2 * -1 + 1 \\
-1 &= 2 * -1 + 1
\end{aligned}$$

gives  $\dots 1110101$ , which is the  $p$ -adic form. Note that the remainders must be digits in the new base. By recognizing a repeated state of the computation, we are able to insert a quote and arrive at our finite representation  $1'0101$ .

If we begin with a fraction, we must allow the quotients to be fractions. We then need an extra criterion to make the algorithm deterministic. For example, converting one-third to binary, we might begin either with

$$1/3 = 2 * -1/3 + 1$$

or with

$$1/3 = 2 * 1/6 + 0$$

To produce a result without a radix point, the original fraction, and each quotient fraction, in lowest terms, must have denominators that are relatively prime to the new base. The implied criterion is that the denominator must remain unchanged.

$$\begin{aligned}
1/3 &= 2 * -1/3 + 1 \\
-1/3 &= 2 * -2/3 + 1 \\
-2/3 &= 2 * -1/3 + 0
\end{aligned}$$

When a quotient is obtained that has appeared before, a cycle is recognized. Placing the quote accordingly, we have produced the binary representation of one-third, namely  $01'1$ . Thus the usual radix conversion algorithm naturally produces our representation.

In the preceding examples, we began with numbers in their familiar decimal representations: sign-and-magnitude, numerator/denominator. If we begin instead with our representation, the algorithm remains the same for rationals (without radix points) as for positive integers. For example, beginning with  $6'7$  (one-third in decimal), we see that the rightmost digit is odd, therefore the rightmost binary digit is 1.

$$\begin{aligned}
(6'7-1) \div 2 &= 3' \\
(3'-1) \div 2 &= 6' \\
(6'-0) \div 2 &= 3'
\end{aligned}$$

The division by two is performed as a multiplication by five, discarding the rightmost digit of the result, which is 0. In general, when converting from base  $b_1$  to base  $b_2$ , a finite number of rightmost digits of each quotient is sufficient to determine the next digit of the result if all factors of  $b_2$  are factors of  $b_1$ .

**6. Properties of the proposed number system.** Excluding the radix point or exponent, the general form of our representation is

$$d_{n+m}d_{n+m-1} \cdots d_{n+1}'d_n d_{n-1} \cdots d_2 d_1 d_0$$

The number represented is

$$\sum_{i=0}^n d_i b^i - \sum_{i=n+1}^{n+m} d_i b^i / (b^m - 1)$$

where  $b$  is the base of the representation. To justify this formula, we shall break the digit sequence into two parts: the digits to the left of the quote will be called the “negative part”, and the digits to its right will be called the “positive part”. The positive part was our starting point for the construction of the representation.

$$d_n \cdots d_0 = \sum_{i=0}^n d_i b^i$$

The negative part can be found as follows.

$$\begin{aligned} d_{n+m}d_{n+m-1} \cdots d_{n+1}' &= d_{n+m}d_{n+m-1} \cdots d_{n+1}'0 \cdots 0 + d_{n+m}d_{n+m-1} \cdots d_{n+1}' \\ &= d_{n+m}d_{n+m-1} \cdots d_{n+1}' * b^m + \sum_{i=n+1}^{n+m} d_i b^{i-n-1} \end{aligned}$$

Therefore

$$d_{n+m} \cdots d_{n+1}' = - \sum_{i=n+1}^{n+m} d_i b^{i-n-1} / (b^m - 1)$$

Putting the positive and negative parts together, we find

$$d_{n+m} \cdots d_{n+1}'d_n \cdots d_0 = d_{n+m} \cdots d_{n+1}' * b^{n+1} + d_n \cdots d_0$$

and hence we obtain the above formula.

From the formula, we see that sign determination is trivial. If both positive and negative parts are present, we merely compare their leading digits. Assuming the representation to be normalized,  $d_{n+m} \neq d_n$ .

If  $d_{n+m} < d_n$ , the number is positive.

If  $d_{n+m} > d_n$ , the number is negative.

If one part is absent, the sign is given by the part that is present. If both parts are absent, the number is zero.

The formula can be used to convert from our representation to numerator/denominator representation, if one so desires. For example, in decimal  $12'7 = 7-120/99=191/33$ ; in binary

$01'1=1-010/11=1/11$  (one-third). From this formula, we can also derive an easy method for converting to a right-repeating decimal expansion (or binary expansion). Simply subtract the negative part from the positive part with their leading digits aligned and the negative part repeated indefinitely to the right.

$$12'345 = 345 - 121.\overline{21} = 223.\overline{78}$$

$$123'45 = 45 - 12.\overline{312} = 32.\overline{687}$$

$$43'21 = 21 - 43.\overline{43} = -22.\overline{43}$$

The opposite conversion can be performed by reversing the steps.

$$2.\overline{34} = 2 - 34' = 56'8$$

The above paragraphs suggest two comparison algorithms. The first is to subtract the comparands, then determine the sign of the result. The second is to convert the comparands to right-repeating form, then perform the usual digit-by-digit comparison. The first has the advantage that it is a right-to-left algorithm, but the second may have an efficiency advantage.

**7. Length of representation.** When two  $p$ -adic rational numbers are added, subtracted, multiplied, or divided, the result is an infinite but eventually repeating sequence of digits. For termination of the arithmetic algorithms, and for finite representation of the result (placing the quote), one must be able to recognize when the state of the computation is one that has occurred before. In a hand calculation, recognition poses no problem: one merely scans the page. The analogous approach for machines requires the arithmetic unit to contain some associative memory. Each state of the computation is compared (associatively, in parallel) with all stored states; if a match is found, the operation is complete, otherwise the state is stored and the operation continues. The resulting digit sequence must be checked for normalization.

A method of recognizing the repeated state that requires storing only one state, at the expense of possibly delaying recognition by a few digits, is the following (Brent 1978). If the states are  $S_1, S_2, S_3, \dots$ , then test  $(S_1 \text{ vs. } S_2), (S_2 \text{ vs. } S_3, S_4), (S_4 \text{ vs. } S_5, \dots, S_8), \dots$ , until a match is found. Again, the resulting digit sequence must be normalized.

**7.1. Length Bounds.** An alternative method of implementing the arithmetic algorithms is as follows:

- (a) calculate a bound for the length (number of digits) of the result;
- (b) calculate a correct, though not necessarily minimal, length for the negative (repeating) part;
- (c) produce a sufficient number of digits to ensure that a repetition of the length calculated in (b) has occurred;
- (d) normalize the result.

This approach obviates the need to recognize a repeated state. However, the complexity of our formulae for the length bounds makes the approach unattractive.

The bounds are summarized in Table 1. The notation used in the table is the following.

$b$ : the base of the representation

$p_i$ : the length of the positive part (i.e. the number of digits to the right of the quote) in the base  $p$  representation of  $x_i$

$n_i$ : the length of the negative part (i.e. the number of digits to the left of the quote) in the base  $p$  representation of  $x_i$

$\phi$ : Euler's  $\phi$  function;  $\phi(m)$  is defined, for positive integer  $m$ , as the number of positive integers not exceeding  $m$  that are relatively prime to  $m$ .

Table 1

*Length Bounds*

$x_3 = x_1 + x_2$	$p_3 \leq \text{MAX}(p_1, p_2) + n_3 + 2$
$x_3 = x_1 - x_2$	$n_3$ is a divisor of $\text{LCM}(n_1, n_2)$
$x_3 = x_1 * x_2$	$p_3 \leq p_1 + p_2 + n_3 + 1$
	$n_3$ is a divisor of $\text{LCM}(n_1, n_2)$
$x_3 = x_1 \div x_2$	$p_3 \leq p_1 + p_2 + n_3 + 1$ if $p_2 \leq n_2$
	$p_3 \leq p_1 - p_2 + n_3 + 1$ if $n_2 < p_2 \leq p_1$
	$p_3 \leq n_3 + 1$ if $p_1, n_2 < p_2$
	$n_3$ is a divisor of $\text{LCM}(n_1, \phi(x_2(b^{n_2} - 1)))$

**7.2. Approximation.** Our representation provides a service that is unavailable to users of fixed-length floating-point hardware: exact results. As arithmetic operators are applied repeatedly during a computation, this extra service may begin to cost extra: the length of representation of the results may tend to grow. As the lengths grow, storage costs increase; as the lengths become greater than the number of digits that a data path or arithmetic unit can accommodate at one time, processing time increases. Many users do not require perfect accuracy, and are unwilling to pay extra for it.

Users of fixed-length floating-point hardware have their accuracy and expense chosen for them by the computer designer. The designer's impossible task is to choose one accuracy and expense (amount of storage per number) to satisfy all users at all times. Some designers give their users a choice of two accuracies (single and double precision); it seems preferable to allow each user to choose any accuracy, from none to complete.

For reasons of mathematical cleanliness, we prefer not to provide approximate versions of the addition, subtraction, multiplication, and division operators, but to provide a separate approximation operator. Two possible (and ideal) forms of this operator are:

- (a) Given a number  $n$ , and a number of digits  $d$ ,  $n @ d$  = a number that is closest to  $n$  and whose representation has no more than  $d$  digits.
- (b) Given a number  $n$ , and a tolerance  $t$ ,  $n @ t$  = a number in the range  $n \pm nt$  whose representation is shortest.

The second form has the advantage that its specification is independent of representation. In either form, the problem of finding a “closest” or “shortest” result is a hard one; in practice, a reasonably close or short result is easy to obtain, and acceptable. One method is to convert the number to right-repeating form (using the algorithm in § 6) and then truncate the result. For example,  $12'34.567$  is first converted to  $22.445\overline{78}$  and this may be approximated to  $0'22.4458$ , to  $0'22.436$ , or to  $0'22.45$ , etc. In general, if the final truncated result has  $k$  digits to the right of the radix point, then it is easy to show that the error introduced by the approximation is less than  $b^{-k}$  where  $b$  is the base of the number system. This form of approximation corresponds to the first style of approximation operator given above.

The role of the numerical analyst has traditionally been to analyze the accuracy (error) provided by the manufacturer, and to design algorithms which make the best use of this accuracy (i.e., whose final result is most accurate). With our proposal, the numerical analyst's role will be to choose approximations that make a computation as cheap as possible, while achieving the desired accuracy. Correctness proofs will be facilitated by making the chosen approximations explicit.

**7.3. Compactness.** We would like to compare the computing expense of solving a sample of numerical problems using a fixed-length floating-point representation with the expense using our representation. To make the comparison, it would be unfair to use existing programs, since they are designed to run on existing floating-point machines. We should proceed as follows.

1. Ascertain the accuracy achieved by each of the existing programs for floating-point.
2. Write programs for our representation that achieve the same accuracy as cheaply as possible. This requires numerical analysis that has not yet been developed.
3. Compare the cost of running the programs on their respective machines.

Even then, the comparison will be biased in favor of fixed-length floating-point, since its users are not given the option of more or less accuracy. Needless to say, we have not made the desired comparison.

We have, however, tested our representation on integer data (Hehner 1976). Our sample was a large, well-known compiler (XCOM, the compiler for XPL (McKeeman 1970)). The integer constants in the program require, on average, 5.7 bits each. A complete trace of the values of all integer variables and integer-valued array elements during an execution of the program (compiling itself) revealed that they require, on average, 6.4 bits each. There are some essential overhead costs associated with the use of variable-length data items. To be easily accessible, the data items may need to be addressed indirectly. Furthermore, memory compactations may be necessary with data items dynamically changing in size. Even when these costs are taken into account, there is a 31% saving compared to a 32-bit fixed-length encoding. (The cost is measured as a space-time product, since space is being traded for time when using a variable-length encoding.) Therefore, for this data, our representation is significantly more economical than a well-known standard.

**8. Conclusion.** The representation of the rational numbers presented in this paper has several appealing properties. Given the usual representation of the positive integers, it is, in a genuine sense, the natural extension to the rationals. The algorithms for addition, subtraction, and multiplication are those of the usual integer arithmetic; the division algorithm is truly the analogue of multiplication.

The complexity of rational arithmetic in numerator/denominator form has not been reduced by our representation, but it has been redistributed and its character has changed. For humans, the problems of detecting a repeated state and normalization have the character of a pattern-match. If they can be solved economically for computers, then we believe rational arithmetic with programmer-controlled accuracy will become an attractive proposition.

The notation introduced in this paper may be generalized in several directions. For integer base  $b > 1$ , the digit set can represent any  $b$  integers that are all different modulo  $b$  (balanced ternary is a special case). The base need not be a positive integer. And the representation can be used for rational power series. Krishnamurthy has considered the use of a fixed-length truncation of  $p$ -adic numbers with the result that arithmetic is exact within a limited range (Krishnamurthy 1977).

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