



# Lecture 15: Modelling "State"

## → What is State?

- ↳ statespace for an object
- ↳ concrete vs. abstract states

## → Finite State Machines

- ↳ states and transitions
- ↳ events and actions

## → Modularized State machine models: Statecharts

- ↳ superstates and substates
- ↳ Guidelines for drawing statecharts

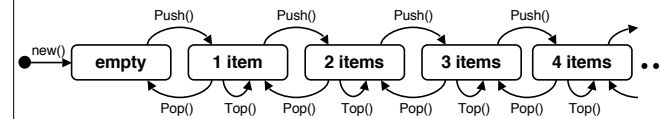


# Getting objects to behave

## → All objects have "state"

- ↳ The object either exists or it doesn't
- ↳ If it exists, then it has a value for each of its attributes
- ↳ Each possible assignment of values to attributes is a "state"
  - (and non-existence is a state, although we normally ignore it)

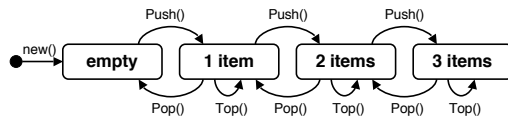
## → E.g. For a stack object



# What does the model mean?

## → Finite State Machines

- ↳ There are a finite number of states (all attributes have finite ranges)
  - E.g. imagine a stack with max length = 3



- ↳ The model specifies a set of traces
  - E.g. new();Push();Push();Top();Pop();Push()...
  - E.g. new();Push();Pop();Push();Pop()...
  - There may be an infinite number of traces (and traces may be of infinite length)
- ↳ The model excludes some behaviours
  - E.g. no trace can start with a Pop()
  - E.g. no trace may have more Pops than Pushes
  - E.g. no trace may have more than 3 Pushes without a Pop in between



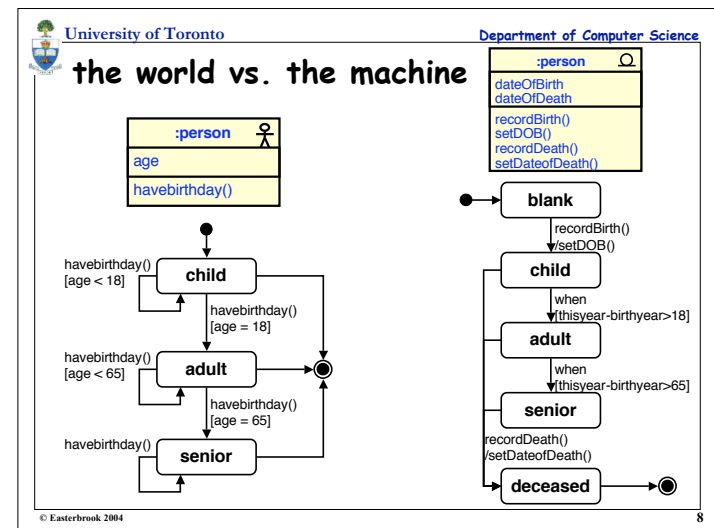
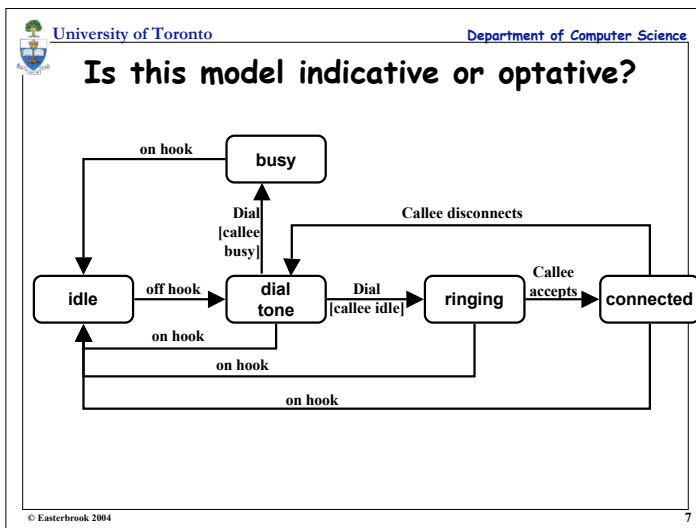
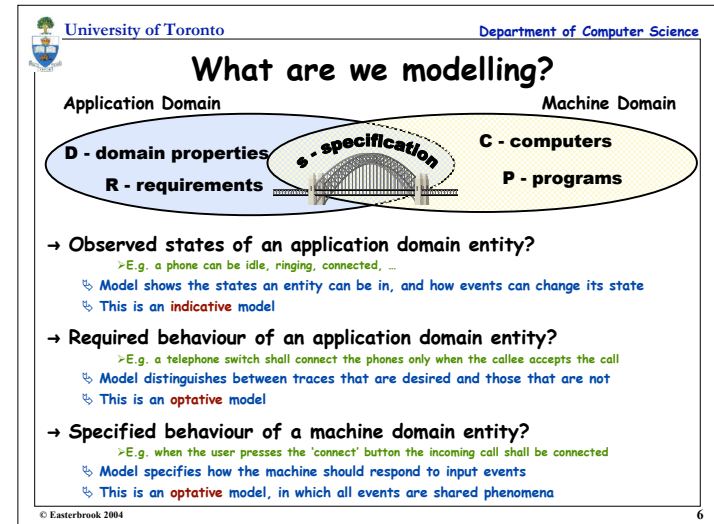
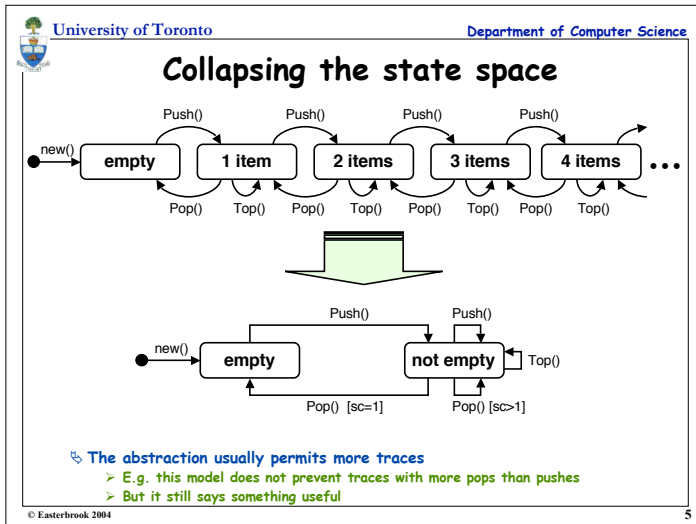
# Abstraction

## → The state space of most objects is enormous

- ↳ State space size is the product of the range of each attribute
  - E.g. object with five boolean attributes:  $2^5=1$  states
  - E.g. object with five integer attributes:  $(maxint)^5+1$  states
  - E.g. object with five real-valued attributes: ...?
- ↳ If we ignore computer representation limits, the state space is infinite

## → Only part of that state space is "interesting"

- ↳ Some states are not reachable
- ↳ Integer and real values usually only vary within some relevant range
- ↳ We're usually not interested in the actual values, just certain ranges:
  - E.g. for Age, we may be interested in  $age < 18$ ;  $18 \leq age < 65$ ; and  $age > 65$
  - E.g. for Cost, we may only be interested in  $cost \leq budget$ ,  $cost = 0$ ,  $cost > budget$ , and  $cost > (budget + 10\%)$



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## StateCharts

→ Notation:

- States
  - "interesting" configurations of the values of an object's attributes
  - may include a specification of action to be taken on entry or exit
  - States may be nested
  - States may be "on" or "off" at any given moment
- Transitions
  - Are enabled when the state is "on"; disabled otherwise
  - Every transition has an **event** that acts as a trigger
  - A transition may also have a condition (or **guard**)
  - A transitions may also cause some action to be taken
  - When a transition is enabled, it can **fire** if the trigger event occurs and it guard is true
  - Syntax: event [guard] / action
- Events
  - occurrence of stimuli that can trigger an object to change its state
  - determine when transitions can fire

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## Superstates

→ States can be nested, to make diagrams simpler

- A superstate consists of one or more states.
- Superstates make it possible to view a state diagram at different levels of abstraction.

**OR superstates**

- when the superstate is "on", only one of its substates is "on"

**AND superstates (concurrent substates)**

- When the superstate is "on", all of its states are also "on"
- Usually, the AND substates will be nested further as OR superstates

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## A more detailed example

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## States in UML

→ A state represents a time period during which

- A predicate is true
  - e.g.  $(\text{budget} - \text{expenses}) > 0$ ,
- An action is being performed, or an event is awaited:
  - e.g. checking inventory for order items
  - e.g. waiting for arrival of a missing order item

→ States can have associated activities:

- do/activity
  - carries out some activity for as long as the state is "on"
- entry/action and exit/action
  - carry out the action whenever the state is entered (exited)
- include/stateDiagramName
  - "calls" another state diagram, allowing state diagrams to be nested

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## Events in UML

### → Events are happenings the system needs to know about

- ↳ Must be relevant to the system (or object) being modelled
- ↳ Must be modellable as an instantaneous occurrence (from the system's point of view)
  - E.g. completing an assignment, failing an exam, a system crash
- ↳ Are implemented by message passing in an OO Design

### → In UML, there are four types of events:

- ↳ **Change events** occur when a condition becomes true
  - denoted by the keyword 'when'
  - e.g. when[balance < 0]
- ↳ **Call events** occur when an object receives a call for one of its operations to be performed
- ↳ **Signal events** occur when an object receives an explicit (real-time) signal
- ↳ **Elapsed-time events** mark the passage of a designated period of time
  - e.g. after[10 seconds]



## Checking your Statecharts

### → Consistency Checks

- ↳ All events in a statechart should appear as:
  - operations of an appropriate class in the class diagram
- ↳ All actions in a statechart should appear as:
  - operations of an appropriate class in the class diagram and

### → Style Guidelines

- ↳ Give each state a unique, meaningful name
- ↳ Only use superstates when the state behaviour is genuinely complex
- ↳ Do not show too much detail on a single statechart
- ↳ Use guard conditions carefully to ensure statechart is unambiguous
  - Statecharts should be deterministic (unless there is a good reason)

### → You probably shouldn't be using statecharts if:

- ↳ you find that most transitions are fired "when the state completes"
- ↳ many of the trigger events are sent from the object to itself
- ↳ your states do not correspond to the attribute assignments of the class