



Lecture 13: Modelling "State"

→ What is State?

- ↪ statespace for an object
- ↪ concrete vs. abstract states

→ Finite State Machines

- ↪ states and transitions
- ↪ events and actions

→ Modularized State machine models: Statecharts

- ↪ superstates and substates
- ↪ Guidelines for drawing statecharts

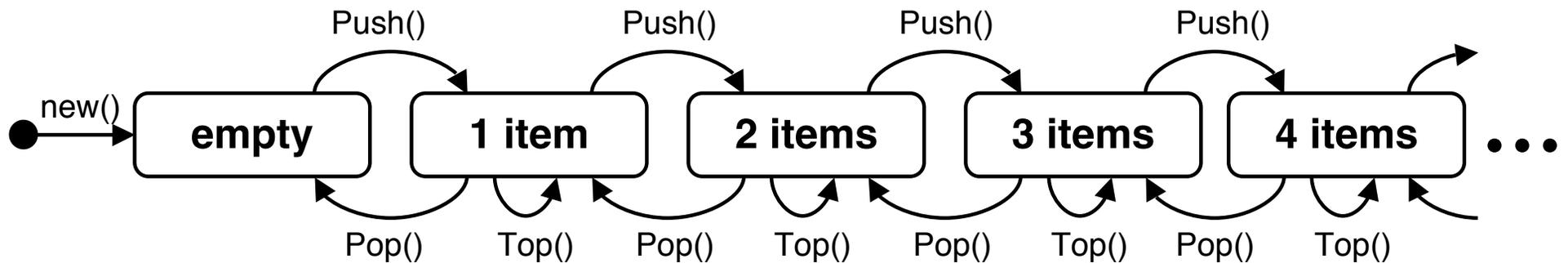


Getting objects to behave

→ All objects have "state"

- ↳ The object either exists or it doesn't
- ↳ If it exists, then it has a value for each of its attributes
- ↳ Each possible assignment of values to attributes is a "state"
 - (and non-existence of the object is also a state)

→ E.g. For a stack object



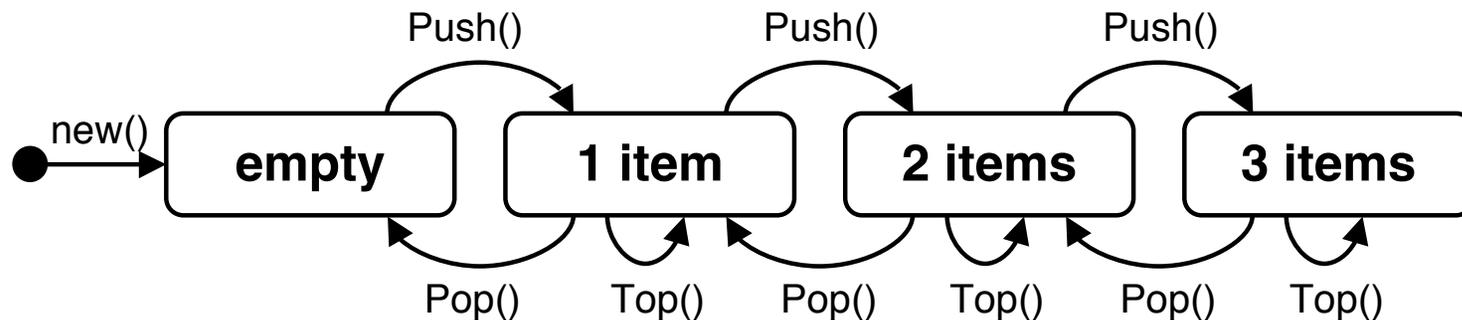


What does the model mean?

→ Finite State Machines

↪ There are a finite number of states (all attributes have finite ranges)

➤ E.g. imagine a stack with max length = 3



↪ The model specifies a set of traces

➤ E.g. `new();Push();Push();Top();Pop();Push()...`

➤ E.g. `new();Push();Pop();Push();Pop()...`

➤ There may be an infinite number of traces (and traces may be of infinite length)

↪ The model excludes some behaviours

➤ E.g. no trace can start with a `Pop()`

➤ E.g. no trace may have more Pops than Pushes

➤ E.g. no trace may have more than 3 Pushes without a Pop in between



Abstraction

→ The state space of most objects is enormous

↳ State space size is the product of the range of each attribute

- E.g. object with five boolean attributes: 2^5+1 states
- E.g. object with five integer attributes: $(\text{maxint})^5+1$ states
- E.g. object with five real-valued attributes: ...?

↳ If we ignore computer representation limits, the state space is infinite

→ Only part of that state space is “interesting”

↳ Some states are not reachable

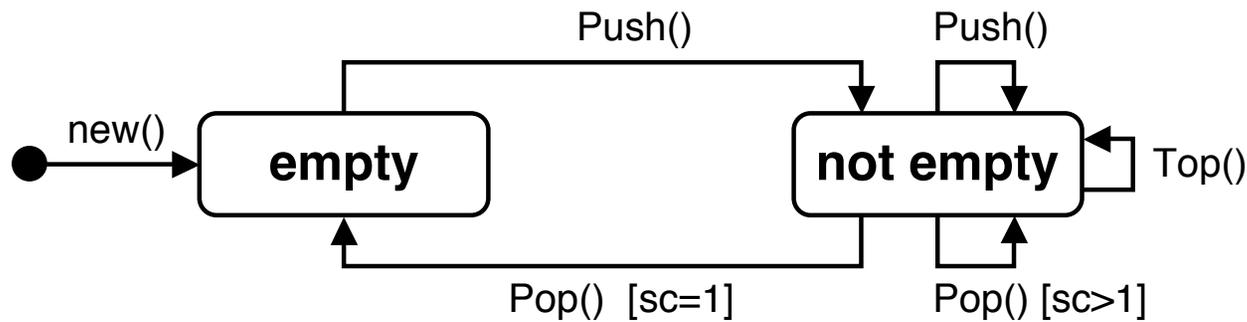
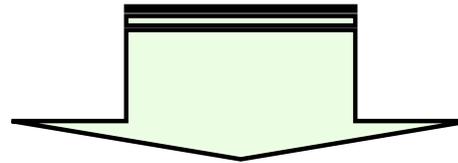
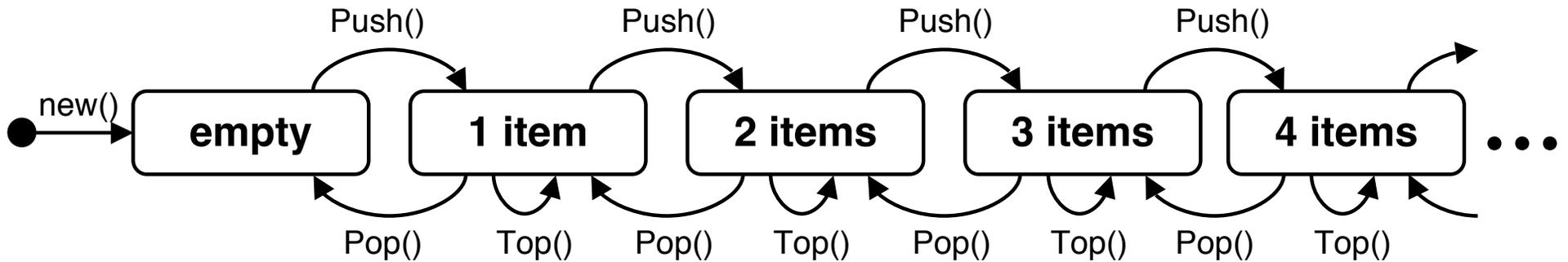
↳ Integer and real values usually only vary within some relevant range

↳ Often, we're only interested in certain thresholds:

- E.g. for *Age*, we may be interested in $\text{age} < 18$; $18 \leq \text{age} \leq 65$; and $\text{age} > 65$
- E.g. for *Cost*, we may want to distinguish $\text{cost} \leq \text{budget}$, $\text{cost} = 0$, $\text{cost} > \text{budget}$, and $\text{cost} > (\text{budget} + 10\%)$



Collapsing the state space



↪ The abstraction usually permits more traces

- E.g. this model does not prevent traces with more pops than pushes
- But it still says something useful

What are we modelling?

Application Domain

Machine Domain

D - domain properties

R - requirements

S - specification



C - computers

P - programs

(D) Observed states of an application domain entity?

➤ E.g. a phone can be idle, ringing, connected, ...

↪ Model shows the states an entity can be in, and how events can change its state

↪ This is an **indicative** model

(R) Required behaviour of an application domain entity?

➤ E.g. a telephone switch shall connect the phones only when the callee accepts the call

↪ Model distinguishes between traces that are desired and those that are not

↪ This is an **optative** model

(S) Specified behaviour of a machine domain entity?

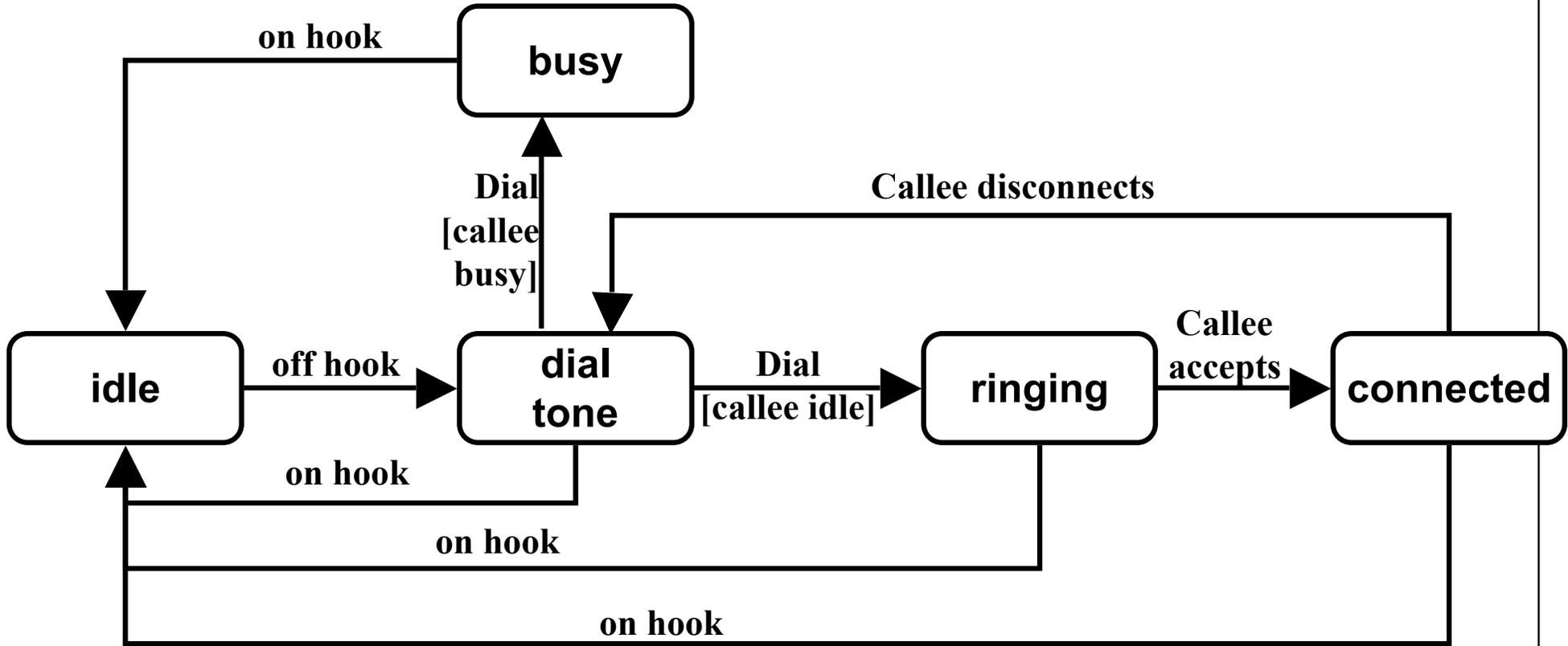
➤ E.g. when the user presses the 'connect' button the incoming call shall be connected

↪ Model specifies how the machine should respond to input events

↪ This is an **optative** model, in which all events are shared phenomena

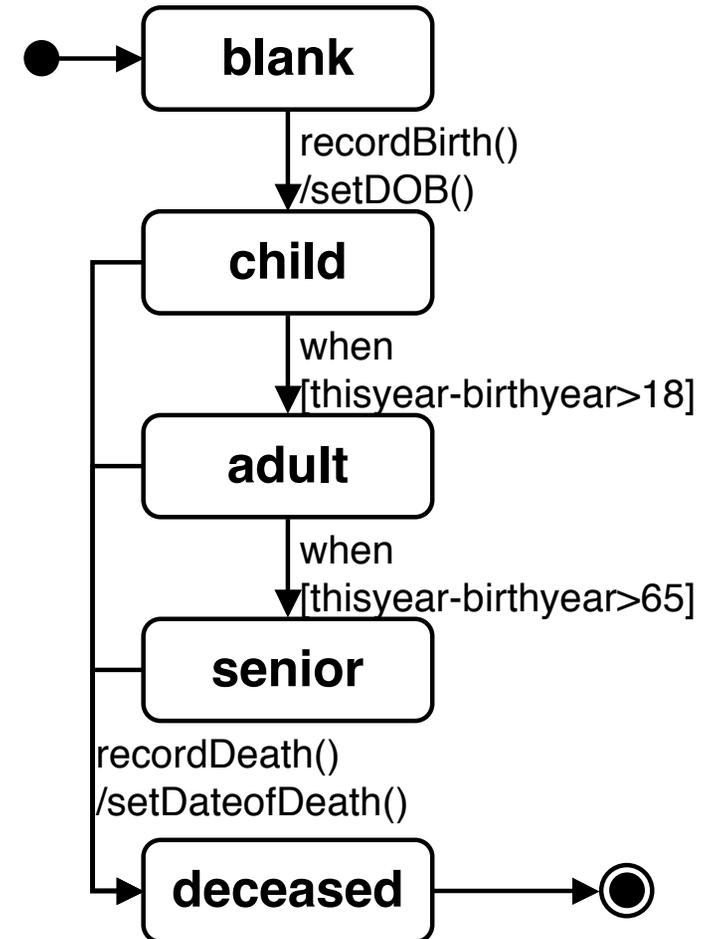
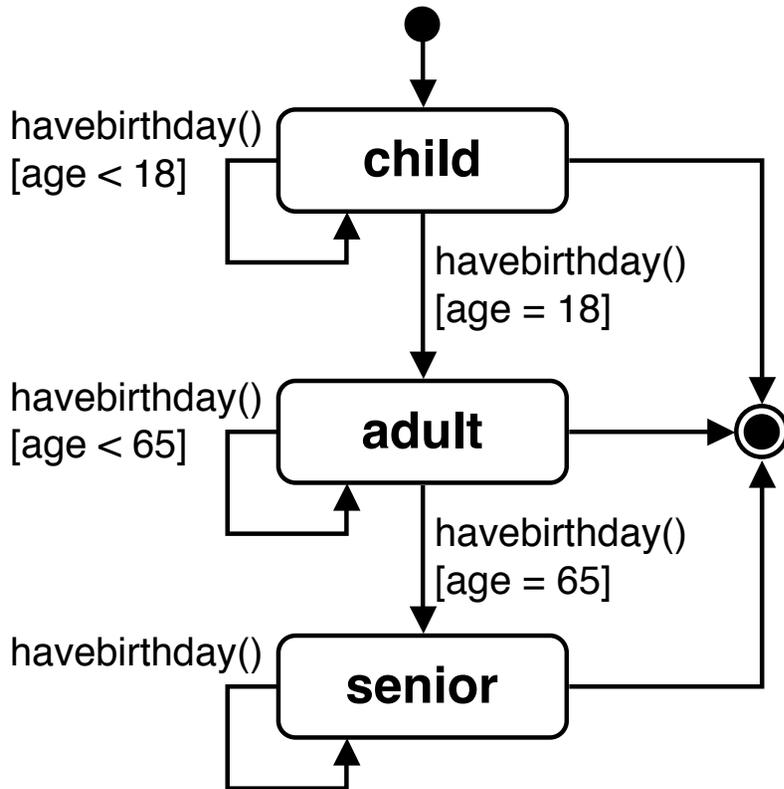
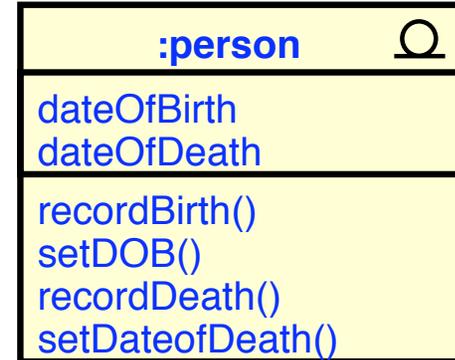


Is this model indicative or optative?





the world vs. the machine





StateCharts

→ Notation:

↪ States

- “interesting” configurations of the values of an object’s attributes
- may include a specification of action to be taken on entry or exit
- States may be nested
- States may be “on” or “off” at any given moment

↪ Transitions

- Are enabled when the state is “on”; disabled otherwise
- Every transition has an **event** that acts as a trigger
- A transition may also have a condition (or **guard**)
- A transitions may also cause some action to be taken
- When a transition is enabled, it can **fire** if the trigger event occurs and it guard is true
- **Syntax:** event [guard] / action

↪ Events

- occurrence of stimuli that can trigger an object to change its state
- determine when transitions can fire



Superstates

→ States can be nested, to make diagrams simpler

↳ A superstate contains one or more substates.

↳ Superstates make it possible to view a state diagram at different levels of abstraction.

OR superstates

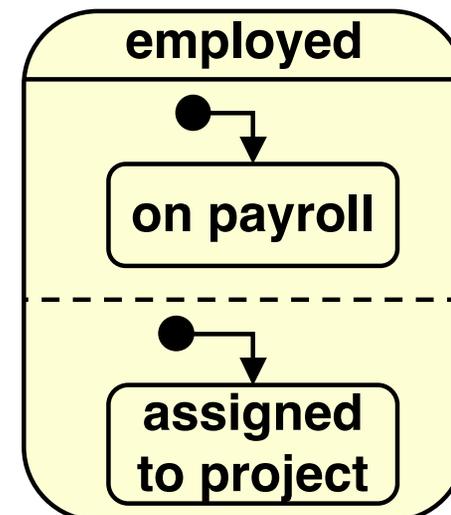
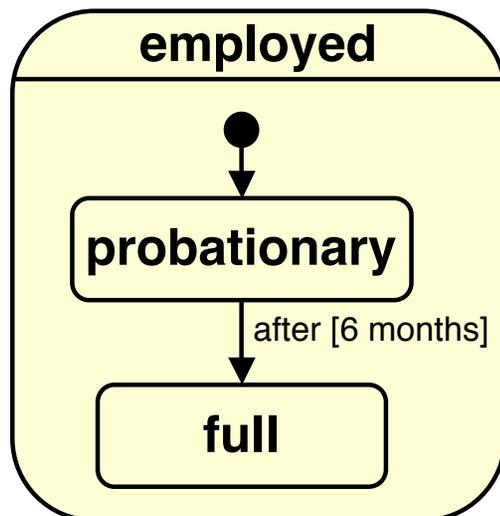
↳ when the superstate is "on", only one of its substates is "on"

AND superstates

(concurrent substates)

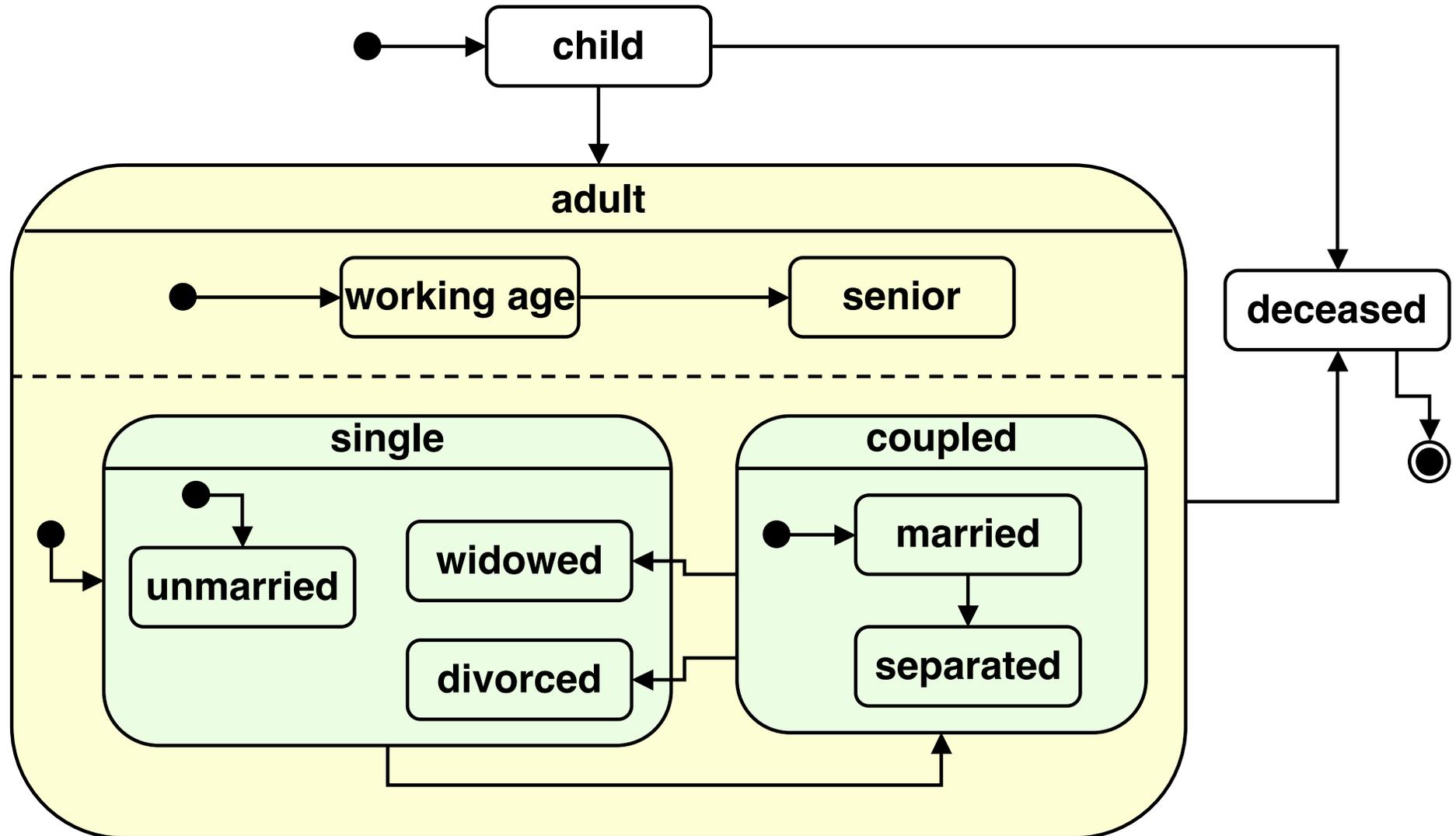
↳ When the superstate is "on", all of its states are also "on"

↳ Usually, the AND substates will be nested further as OR superstates





A more detailed example





States in UML

→ A state represents a time period during which

↳ A predicate is true

➤ e.g. $(\text{budget} - \text{expenses}) > 0$,

↳ An action is being performed, or an event is awaited:

➤ e.g. checking inventory for order items

➤ e.g. waiting for arrival of a missing order item

→ States can have associated activities:

↳ do/activity

➤ carries out some activity for as long as the state is "on"

↳ entry/action and exit/action

➤ carry out the action whenever the state is entered (exited)

↳ include/stateDiagramName

➤ "calls" another state diagram, allowing state diagrams to be nested



Events in UML

→ Events are happenings the system needs to know about

- ↪ Must be relevant to the system (or object) being modelled
- ↪ Must be modellable as an instantaneous occurrence (from the system's point of view)
 - E.g. completing an assignment, failing an exam, a system crash
- ↪ Are implemented by message passing in an OO Design

→ In UML, there are four types of events:

- ↪ **Change events** occur when a condition becomes true
 - denoted by the keyword 'when'
 - e.g. when[balance < 0]
- ↪ **Call events** occur when an object receives a call for one of its operations to be performed
- ↪ **Signal events** occur when an object receives an explicit (real-time) signal
- ↪ **Elapsed-time events** mark the passage of a designated period of time
 - e.g. after[10 seconds]



Checking your Statecharts

→ Consistency Checks

- ↪ All events in a statechart should appear as:
 - operations of an appropriate class in the class diagram
- ↪ All actions in a statechart should appear as:
 - operations of an appropriate class in the class diagram

→ Style Guidelines

- ↪ Give each state a unique, meaningful name
- ↪ Only use superstates when the state behaviour is genuinely complex
- ↪ Do not show too much detail on a single statechart
- ↪ Use guard conditions carefully to ensure statechart is unambiguous
 - Statecharts should be deterministic (unless there is a good reason)

→ You probably shouldn't be using statecharts if:

- ↪ you find that most transitions are fired "when the state completes"
- ↪ many of the trigger events are sent from the object to itself
- ↪ your states do not correspond to the attribute assignments of the class