

HARDNESS ESCALATION IN COMMUNICATION COMPLEXITY

Toniann Pitassi



Joint work with :



Mika göös



Thomas Watson



Robert Robere



Ben Rossman



Stephen Cook

HARDNESS ESCALATION IN COMMUNICATION ?



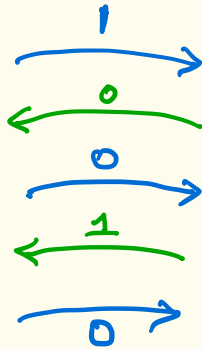
WHAT I WILL BE TALKING ABOUT:

- Models of interactive communication / information
- Their importance in so many areas of computer science
- A (relatively) new lower bound tool
hardness escalation / lifting
 - applications
 - some ideas of proof

← they capture information bottleneck

Communication Complexity (Yao '79)

$x = 10111$



$y = 10110$



last bit is $f(x, y)$

$$f: \{0,1\}^n \times \{0,1\}^n \rightarrow \{0,1\}$$

$$cc(f) = \min_{\Pi \text{ computing } f} cc(\Pi)$$

Example: EQUALITY(x, y)

x = 10111



x $\stackrel{?}{=}$ y

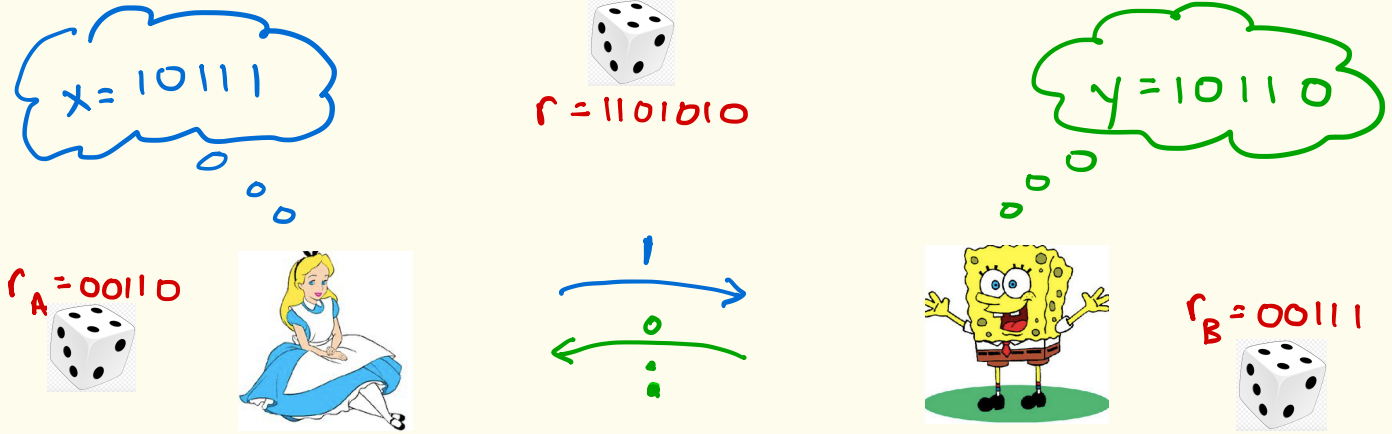
y = 10110



Deterministic CC = $\Omega(n)$

Randomized CC = $O(1)$

Randomized Communication Complexity



Π computes f if:

$$\forall x, y \quad \Pr_{r_A, r_B, r} [\Pi(x, y) \neq f(x, y)] \leq \frac{1}{3}$$

$$rCC(f) = \min_{\Pi} cC(\Pi)$$

Equivalent Definition of Randomized CC

$rCC(f)$ = cost of best randomized protocol for f , with error $< 1/3$ on every input

$CC_{1/3}^{\mu}(f)$ = cost of best deterministic protocol for f over distribution μ , with error $< 1/3$

Theorem (Yao Min-max for CC)

$$rCC(f) = \max_{\mu} CC_{1/3}^{\mu}(f)$$

Rich History of Communication Complexity

- The most successful concrete model of computation for proving lower bounds

applications: streaming algorithms
cryptography (secret sharing schemes)
proof complexity
limitations of LP/SDP for NP-hard problems
game theory
distributed computing
graph theory
data structures,
circuit complexity,

...

Rich History of Communication Complexity

- The most successful concrete model of computation for proving lower bounds

- Many variants: communication analog of complexity classes

P^{cc} , BPP^{cc} , NP^{cc}

Rich History of Communication Complexity

- The most successful concrete model of computation for proving lower bounds
- Many variants: communication analog of complexity classes
- Tightly connected to interactive theory of communication

Classical Information Theory [Shannon '48]

11010111 ~ Z



transmitter



receiver

Data Compression Thm Every message
can be compressed to its info-theoretic content

$$H(Z) \leq C(Z) < H(Z) + 1$$

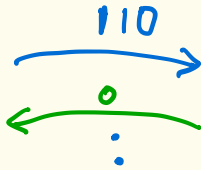
[Noiseless, Huffman coding]

(Interactive) Information Complexity

[CSWY '01
BJKS '04
BBCR '13]

$x = 10111$

$y = 10110$



$r_A = 1101011$

$r_B = 0011011$

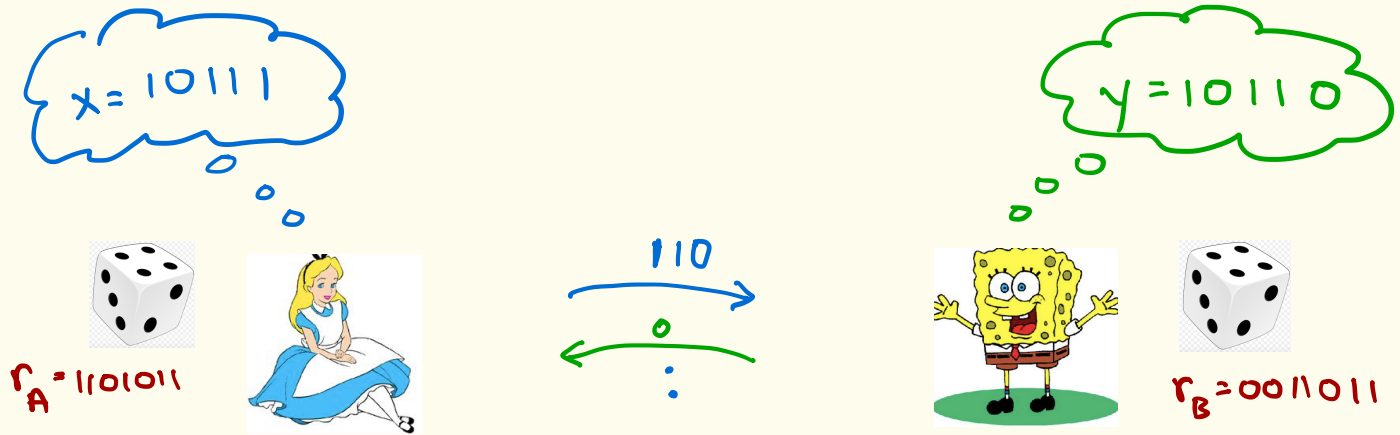
Internal Information Cost $IC_{\mu}(\pi)$:

$$I_{\mu}(\pi; Y | X) + I_{\mu}(\pi; X | Y)$$

↑
What Alice learns about Y

←
What Bob learns about X

(Interactive) Information Complexity



Internal Information Cost $IC_{\mu}(\pi)$:

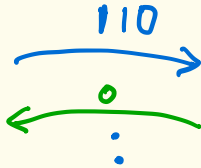
$$I_{\mu}(\pi; Y | X) + I_{\mu}(\pi; X | Y)$$

- * $\pi(x, y)$ is a random variable - distribution over transcript of messages sent on (x, y)
- * $(x, y) \sim \mu$

(Interactive) Information Complexity

$x = 10111$

$y = 10110$



$r_A = 1101011$

$r_B = 0011011$

$$IC_{\mu}(f) = \min_{\pi \text{ computing } f} IC_{\mu}(\pi)$$

$$IC(f) = \max_{\mu} IC_{\mu}(f)$$

Big Q: Can interactive communication
be compressed? [$IC(f) \approx rCC(f)$?]

- Essentially all lower bound measures used to prove randomized cc LBS also give IC lower bounds

Big Q: Can interactive communication be compressed?

- Essentially all lower bound measures used to prove randomized cc LBs also give IC lower bounds

- Compression Results

① communication information $\frac{C}{I} \Rightarrow \min \left\{ 2^I, \sqrt{I \cdot C} \right\}$ [BBCR'10]

② product distributions $\Rightarrow \min \left\{ I^2, I \cdot \text{polylog}(C) \right\}$
[BBCR'10, KOL'16, S'16]

suppressing low order terms

Big Q: Can interactive communication be compressed?

- Essentially all lower bound measures used to prove randomized CC LBs also give IC lower bounds

- Compression Results

- Lower Bound [Ganor-Kol-Raz '16]

There is a boolean function f
with $I = \log \log \log n$ but $rCC \in \Omega(\log \log n)$

↑
exponential separation but in very low
CC regime.

Big Q: Can interactive communication
be compressed?

OPEN #1 $I, C \stackrel{?}{\Rightarrow} I \cdot \text{polylog} C$ communication

BIG QUESTION: $IC(f) = rCC(f)$?

[Can communication be compressed in the interactive setting?]

OPEN #1 $I, C \stackrel{?}{\Rightarrow} I \cdot \text{polylog} C$ communication

OPEN #2 $I \in \Omega(\log n) \stackrel{?}{\Rightarrow} \text{poly}(I)$ communication

LOWER BOUND METHODS IN CC

- ① Find a matrix property implied by low cc protocol that f doesn't have
[ex. rank, discrepancy, corruption]
- ② Information theory proof (via direct sum property)
- ③ Hardness Escalation
(Query to communication Lifting)

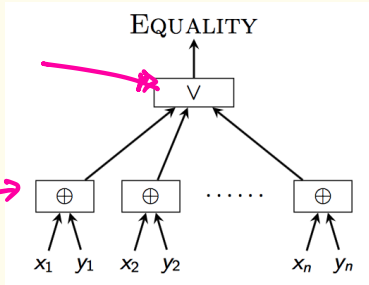
LOWER BOUND METHODS IN CC

- ① Find a matrix property implied by low cc protocol that f doesn't have
[ex. rank, discrepancy, corruption]
- ② Information theory proof (via direct sum property)
- ③ Hardness Escalation
(Query to communication Lifting)

INTUITION: MOST HARD COMMUNICATION PROBLEMS ARE COMPOSED FUNCTIONS $f \circ g^n$

f: OR

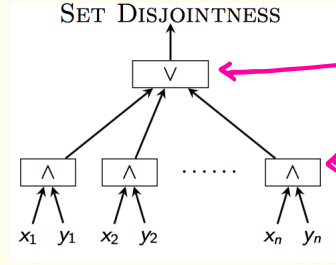
g: \oplus



SET DISJOINTNESS

f: OR

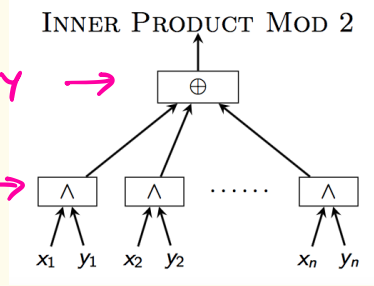
g: AND



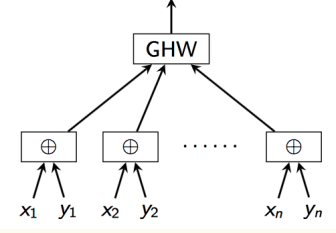
INNER PRODUCT MOD 2

f: PARITY

g: AND

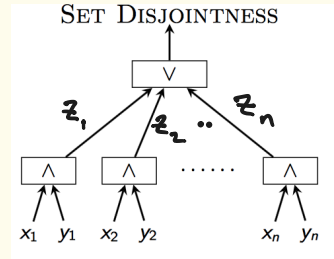


GAP HAMMING DISTANCE

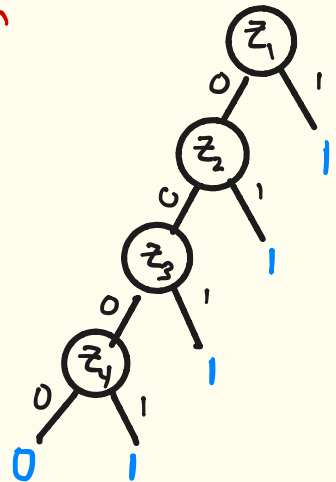


HARDNESS ESCALATION ("Lifting")

Intuition If g sufficiently hard, the best protocol for $fo g^n$ will simulate the best decision tree for f



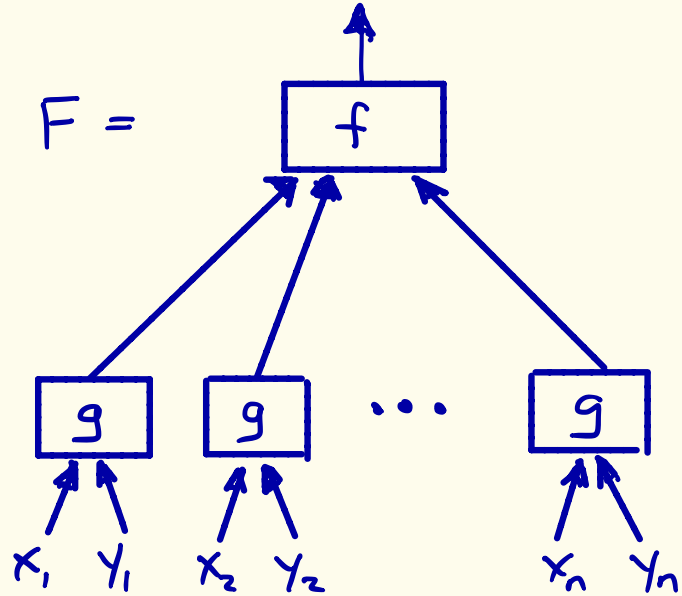
Query Complexity of $f \approx$ Communication Complexity of $fo g^n$



Query-to-communication Lifting

$$f: \{0,1\}^n \rightarrow \{0,1\} \rightsquigarrow$$

$F =$

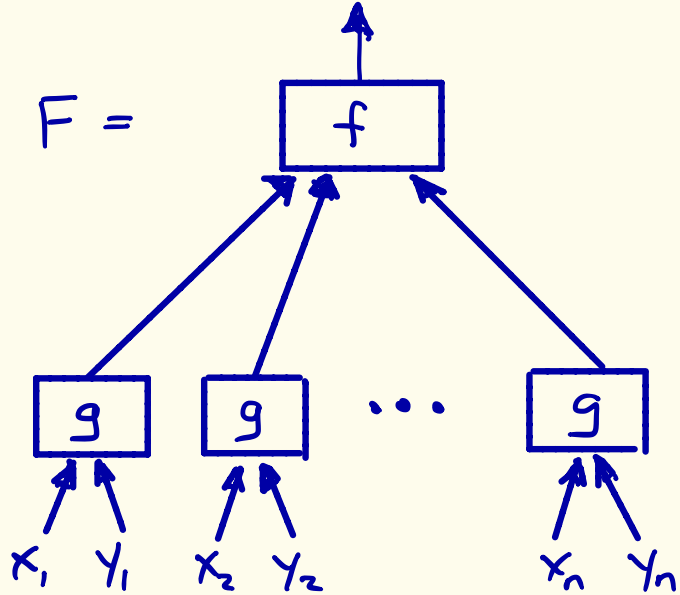


$g(x_i, y_i) \rightarrow \{0,1\}$ small "gadget"

Query-to-communication Lifting

$$f: \{0,1\}^n \rightarrow \{0,1\}$$

$\rightsquigarrow F =$



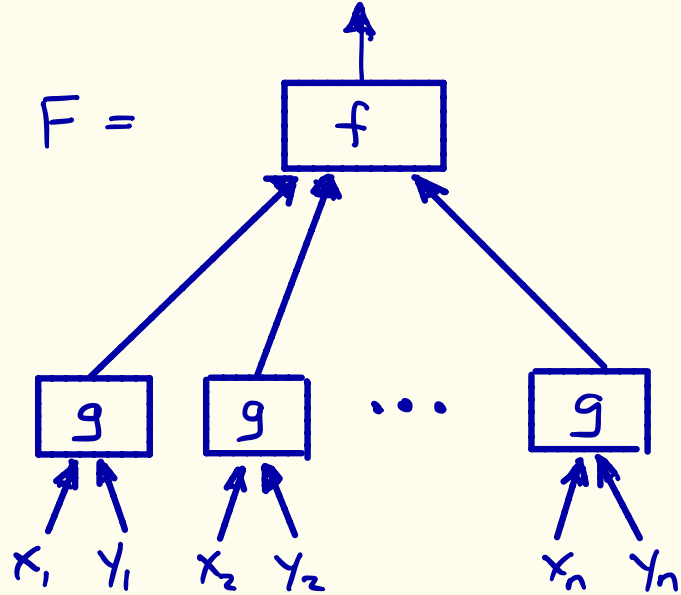
Easiness Escalation:

Decision tree for $f \rightsquigarrow$ Communication protocol for F

Query-to-communication Lifting

$$f: \{0,1\}^n \rightarrow \{0,1\} \rightsquigarrow$$

$F =$



Hardness Escalation

Decision tree for f



Communication protocol for F

An Abridged History

[Nisan, Wigderson FOCS '94]

Rank vs. communication

[Raz, McKenzie FOCS '97]

Monotone circuit depth (deterministic lifting)

[Sherstov STOC '08]

Polynomial degree \rightarrow rank (pattern matrix method)

[Göös, Lovett, Meka, Watson, Zuckerman STOC '15]

Nonneg Junta degree \rightarrow Nonneg rank

[Göös, Pitassi, Watson FOCS '15]

Explicit/simplified deterministic lifting

[Göös, Pitassi, Watson FOCS '17]

BPP (randomized) lifting

Lifting Theorems Makes Lower Bounds Easy!



2 step recipe :

- ① Prove problem specific query lower bound
- ② Apply Lifting theorem to obtain communication complexity lower bound

Applications

1. Monotone formula size / circuit lower bounds
2. Cryptography: Lower bounds for Linear secret sharing schemes (+ span programs)
3. Linear Programming: Extended formulations
4. Game Theory: Nash Equilibrium
5. Graph Theory: Alon-Saks-Seymour Conjecture
6. Proof Complexity
7. Communication Complexity separations
8. Quantum Lower Bounds

Applications

1. Monotone formula size / circuit lower bounds
2. Cryptography: Lower bounds for Linear secret sharing schemes (+ span programs)
3. Linear Programming: Extended formulations
4. Game Theory: Nash Equilibrium
5. Graph Theory: Alon-Saks-Seymour Conjecture
6. Proof Complexity
7. Communication Complexity separations
8. Quantum Lower Bounds

[KW] COMMUNICATION COMPLEXITY
LOWER BOUNDS



FORMULA SIZE
LOWER BOUNDS

Let f be a Boolean function

KW_f : Alice gets $x \in f^{-1}(1)$ Bob gets $y \in f^{-1}(0)$
 $KW_f(x, y)$: output i s.t. $x_i \neq y_i$

Theorem [KW]

The communication complexity of KW_f
equals the minimum Boolean circuit depth for f !

[KW] COMMUNICATION COMPLEXITY
LOWER BOUNDS



FORMULA SIZE
LOWER BOUNDS

Let f be a Boolean function

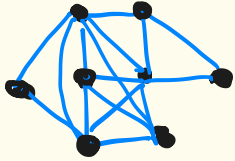
$\boxed{mKW_f}$: Alice gets $x \in f^{-1}(1)$ Bob gets $y \in f^{-1}(0)$
 $mKW_f(x, y)$: output i s.t. $x_i = 1$ $y_i = 0$

Theorem [KW]

The communication complexity of KW_f
equals the minimum monotone Boolean circuit depth for f

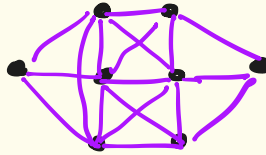
Example $f = \text{SCLIQUE}$

Alice



$g \in f^{-1}(1)$

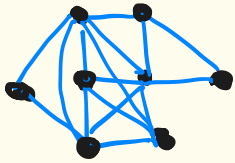
Bob



$g \in f^{-1}(0)$

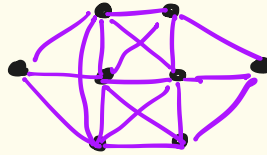
Example $f = \text{5CLIQUE}$

Alice



$g \in f^{-1}(1)$

Bob



$g \in f^{-1}(0)$

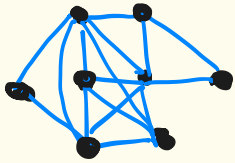
Theorem Monotone formulas for clique
require size $2^{\Omega(n/\log n)}$

Previous proofs: $2^{\Omega(n^{\epsilon})}$

← USES
BPP
LIFTING
Theorem

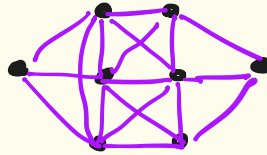
Example $f = \text{5CLIQUE}$

Alice



$g \in f^{-1}(1)$

Bob



$g \in f^{-1}(0)$

Theorem [ggks '18]

Monotone circuits for clique require exponential size

← New proof
Using
BPP
LIFTING
Theorem

Applications

1. Monotone formula size / circuit lower bounds
2. Cryptography: Lower bounds for Linear secret sharing schemes (+ span programs)
3. Linear Programming: Extended formulations
4. game Theory: Nash Equilibrium
5. graph Theory: Alon-Saks-Seymour Conjecture
6. Proof Complexity
7. Communication Complexity separations
8. Quantum Lower Bounds

(MONOTONE) SPAN PROGRAMS [KW '93]

x_1	1	0	0	0	0	0	0	0
x_2	0	1	0	0	0	0	0	0
x_2	0	1	0	0	0	0	0	0
x_3	0	1	0	1	0	1	0	1
x_4	0	0	1	1	1	1	1	1
x_5	0	0	1	1	1	1	1	1

M

accept input α iff $\bar{1}$ in $\text{span}(M|_{\alpha})$

(MONOTONE) SPAN PROGRAMS

x_1	1	0	0	0	0	0	0	0
x_2	0	1	0	0	0	0	0	0
x_2	0	1	0	0	0	0	0	0
x_3	0	1	0	1	0	1	0	1
x_4	0	0	1	1	1	1	1	1
x_5	0	0	1	1	1	1	1	1

M

Example: $\alpha = 11001$
is accepted !

IMPORTANCE OF SPAN PROGRAMS

- poly size monotone SPAN programs stronger than formulas (and incomparable to monotone circuits)
- Monotone Span Programs characterize Linear Secret Sharing Schemes
- Close connection to Quantum Query Algorithms

Theorem [P. Robere '18] Clique requires exponential-size monotone span programs

(and hence expl size linear secret sharing schemes)

Applications

1. Monotone formula size / circuit lower bounds
2. Cryptography: Lower bounds for Linear secret sharing schemes (+ span programs)
3. Linear Programming: Extended formulations
4. Game Theory: Nash Equilibrium
5. Graph Theory: Alon-Saks-Seymour Conjecture
6. Proof Complexity
7. Communication Complexity separations
8. Quantum Lower Bounds

2-Player ϵ -Nash is Hard

2 players. Each has an $N \times N$ payoff matrix




.3	.6	.5
.2	.4	.1
.9	0	1



.1	.5	.9
.2	.4	.1
1	.9	0


2-Player ϵ -Nash is Hard

2 players. Each has an $N \times N$ payoff matrix



A =

.3	.6	.5
.2	.4	.1
.9	0	1



B =

.1	.5	.9
.2	.4	.1
1	.9	0

(\hat{x}, \hat{y}) is an ϵ -Nash Equilibrium if:

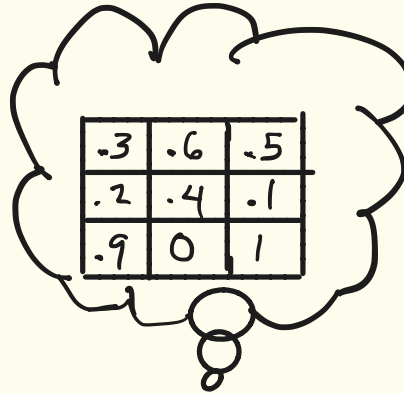
$$\hat{x}^T A \hat{y} \geq x^T A \hat{y} - \epsilon \quad \forall x$$

$$\hat{x}^T B \hat{y} \geq \hat{x}^T B y - \epsilon \quad \forall y$$

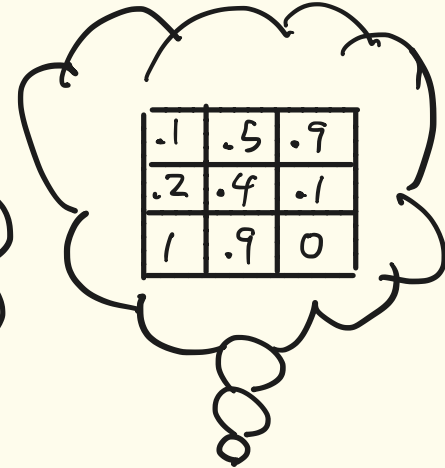
Finding ϵ -Nash Equilibrium is Hard

Theorem [Göös-Rubinfeld '18]

The randomized communication complexity of finding an ϵ -Nash equilibrium is $\geq N^{2-o(1)}$



.3	.6	.5
.2	.4	.1
.9	0	1



.1	.5	.9
.2	.4	.1
1	.9	0



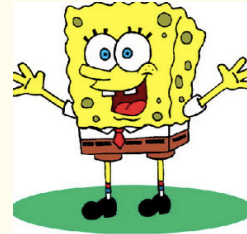
Applications

1. Monotone formula size / circuit lower bounds
2. Cryptography: Lower bounds for Linear secret sharing schemes (+ span programs)
3. Linear Programming: Extended formulations
4. Game Theory: Nash Equilibrium
5. Graph Theory: Alon-Saks-Seymour Conjecture
6. Proof Complexity
7. Communication Complexity separations
8. Quantum Lower Bounds

Clique vs Independent Set



Clique $x \subseteq [n]$
of G



Independent set $y \subseteq [n]$
of G

$$CIS_G(x, y) = \begin{cases} 0 & \text{if } |x \cap y| = 1 \\ 1 & \text{if } |x \cap y| = 0 \end{cases}$$

Clique vs Independent Set

Yannakakis Question:

Is there an $O(\log n)$ nondeterministic cc protocol for CIS_g ?



Alon-Saks-Seymour Conjecture:

$\forall g \quad \chi(g) \leq \text{poly}(bp(g))$?

Clique vs Independent Set

Yannakakis Question:

Is there an $O(\log n)$ nondeterministic cc protocol for CIS_g ?



BOTH ARE FALSE!

Alon-Saks-Seymour Conjecture:

$\forall g \quad x(g) \leq \text{poly}(bp(g))$?

Theorem [göös '15]

$\exists g$, any nondet. cc protocol for $CIS_g \in \Omega(\log^{1.13} n)$

BPP LIFTING THEOREM

Theorem [Göös-P-Watson '17]

Randomized
decision tree
complexity of f

\approx

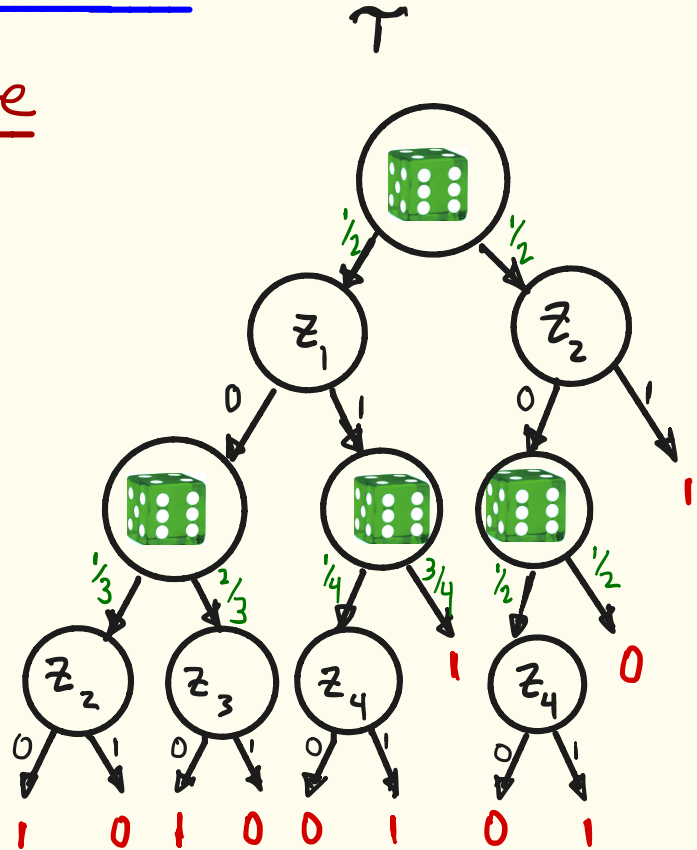
Randomized
communication
complexity of
 $f \circ g^n$

Randomized Decision Trees

A randomized decision tree

for $f(z_1, z_2, z_3, z_4)$:

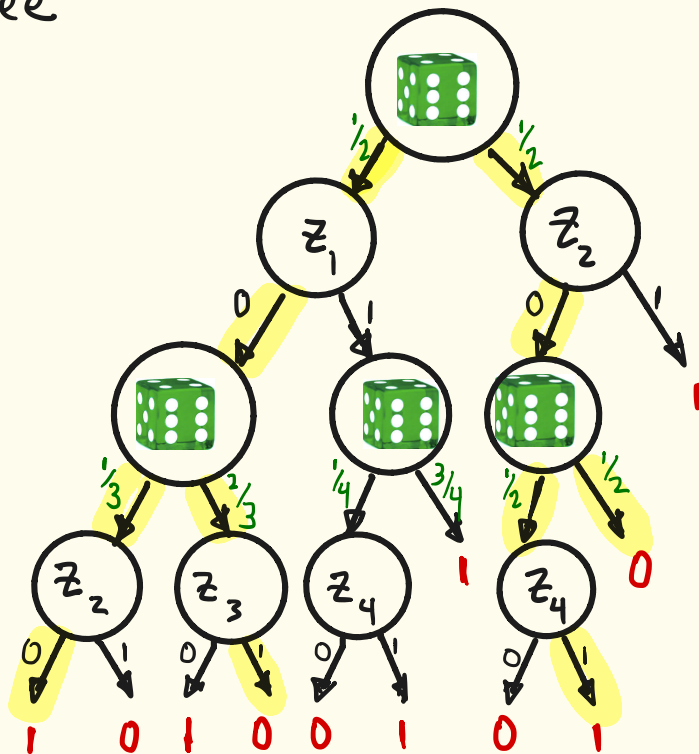
height(τ) = max number
of decision vertices



Randomized Decision Trees

A randomized decision tree
for $f(z_1, z_2, z_3, z_4)$:

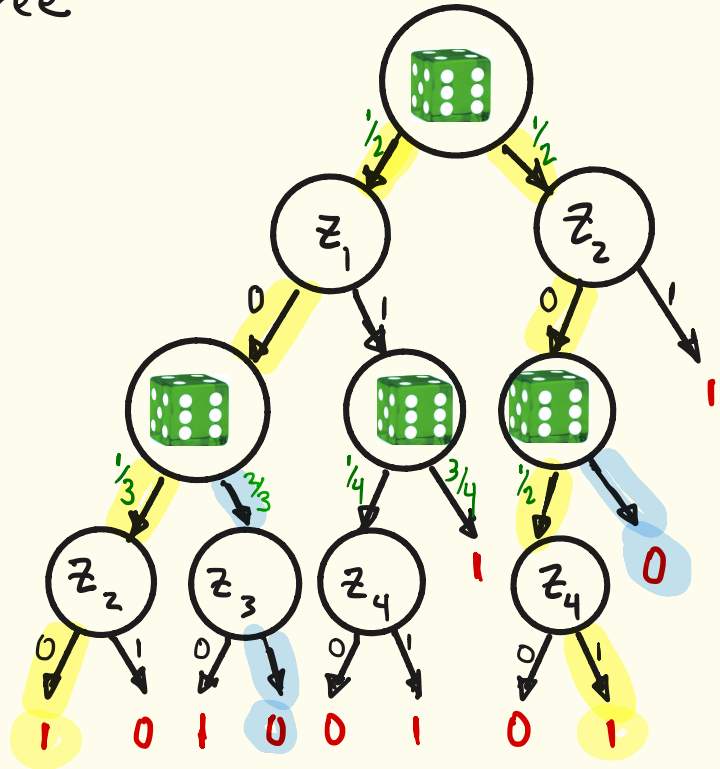
$$\Pr[\mathcal{T}(0011) = 1]$$



Randomized Decision Trees

A randomized decision tree
for $f(z_1, z_2, z_3, z_4)$:

$$\begin{aligned} \Pr[\mathcal{T}(0011) = 1] \\ &= \frac{1}{2} \frac{1}{3} + \frac{1}{2} \frac{1}{2} \\ &= \frac{5}{12} \end{aligned}$$

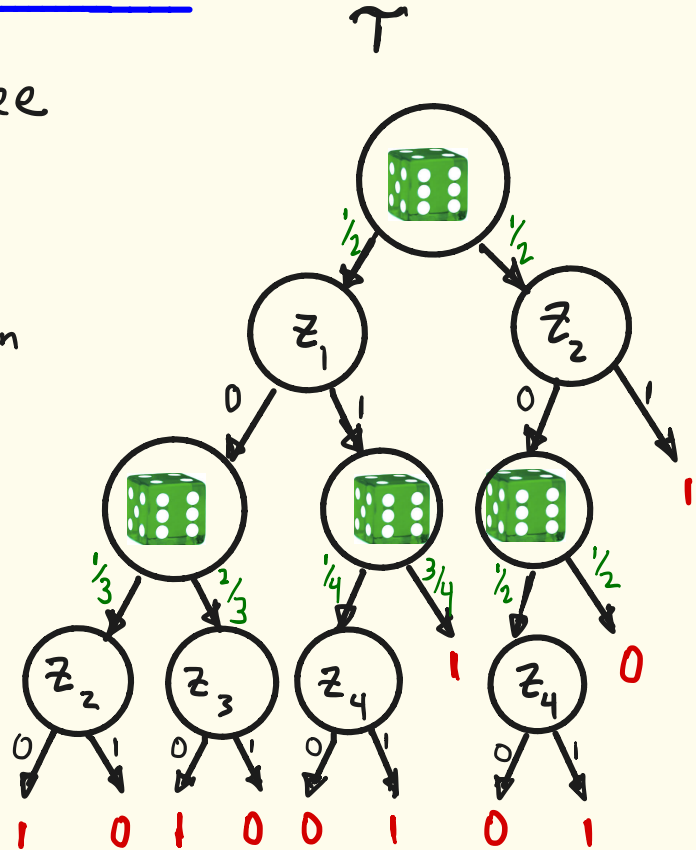


Randomized Decision Trees

A randomized decision tree
for $f(z_1, z_2, z_3, z_4)$:

\mathcal{T} computes f if $\forall z \in \{0,1\}^n$

$$\Pr[\mathcal{T}(z) \neq f(z)] \leq \frac{1}{3}$$



BPP LIFTING THEOREM

Theorem [GPW '17]

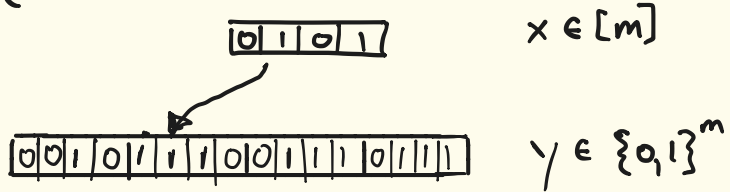
Randomized
decision tree
complexity of f

\approx

Randomized
communication
complexity of
 $f \circ g^n$

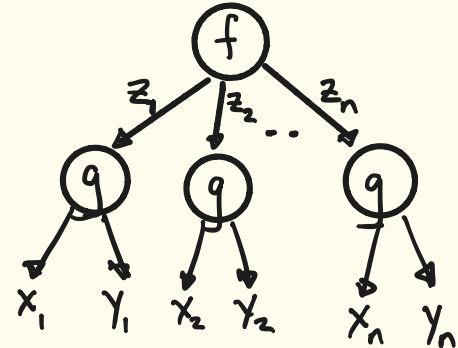
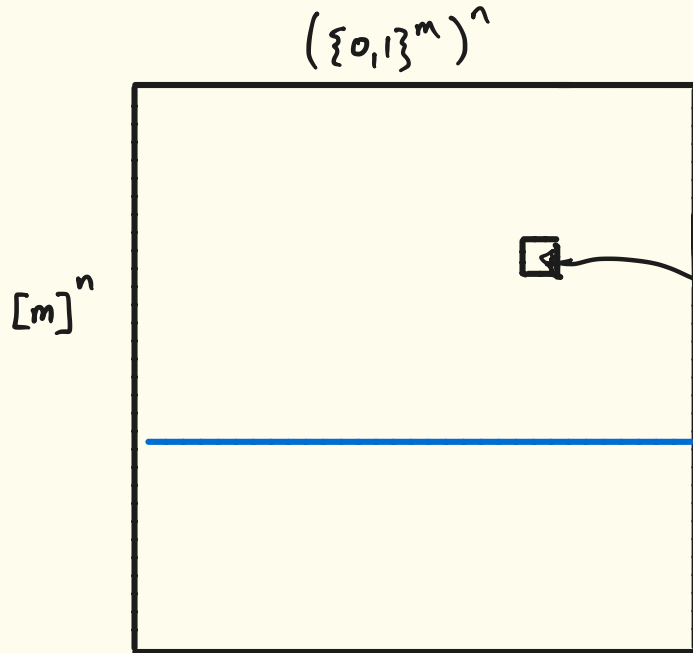
$g =$ "index gadget"

$$g(x, y) = x|_y$$



HOW TO PROVE BPP LIFTING THEOREM?

wlog start with a deterministic cc protocol Π for $f \circ g^n$

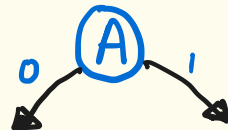
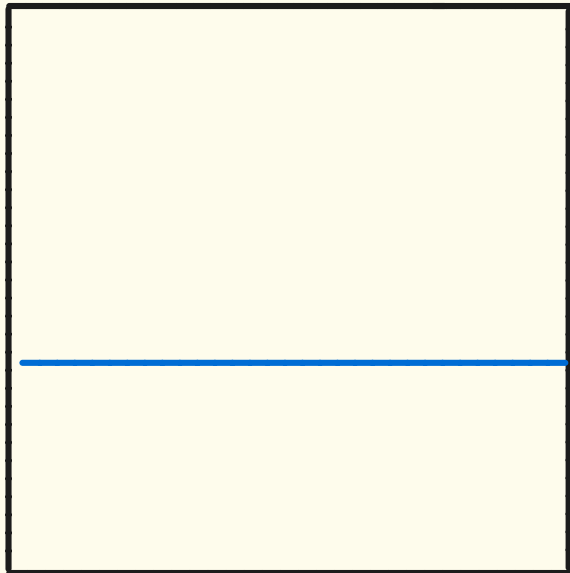


Each entry $((x_1 \dots x_n), (y_1 \dots y_n))$
labelled by $z \in \{0,1\}^n$

rows: all possible inputs for Alice
cols: " " " " Bob

How to prove BPP LIFTING THEOREM ?

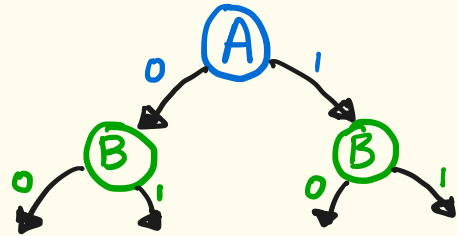
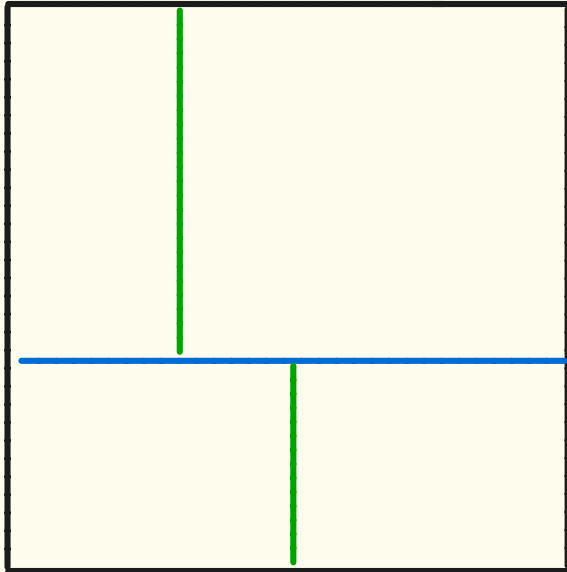
$(\{0,1\}^m)^n$



How to prove BPP LIFTING THEOREM ?

$(\{0,1\}^m)^n$

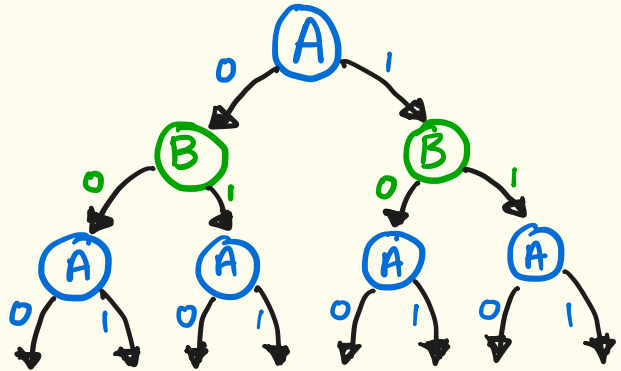
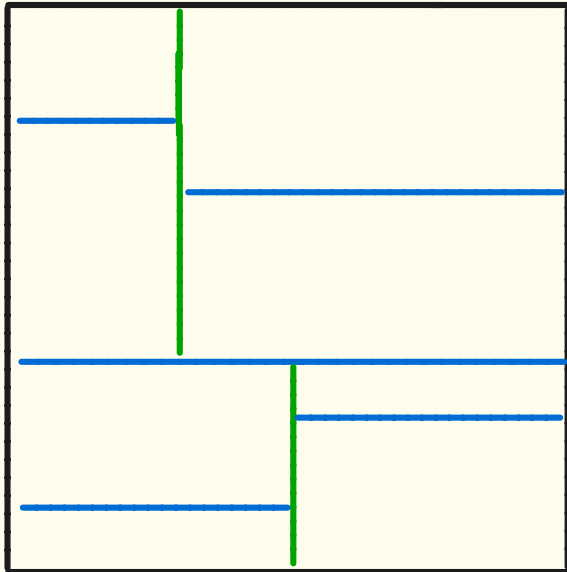
$[m]^n$



How to prove BPP LIFTING THEOREM ?

$(\{0,1\}^m)^n$

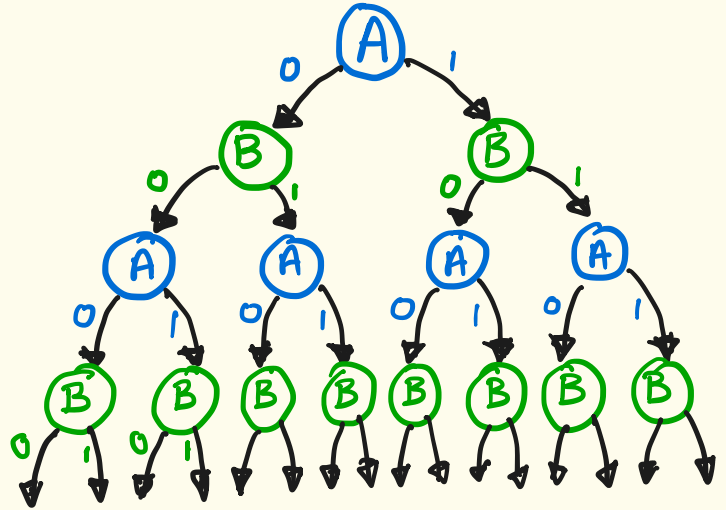
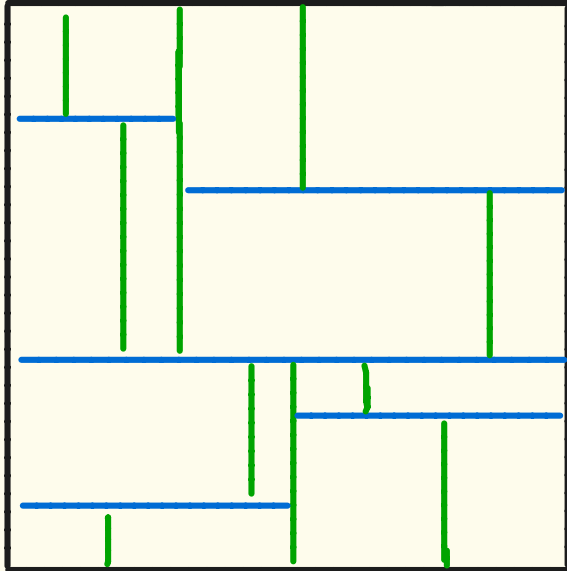
$[m]^n$



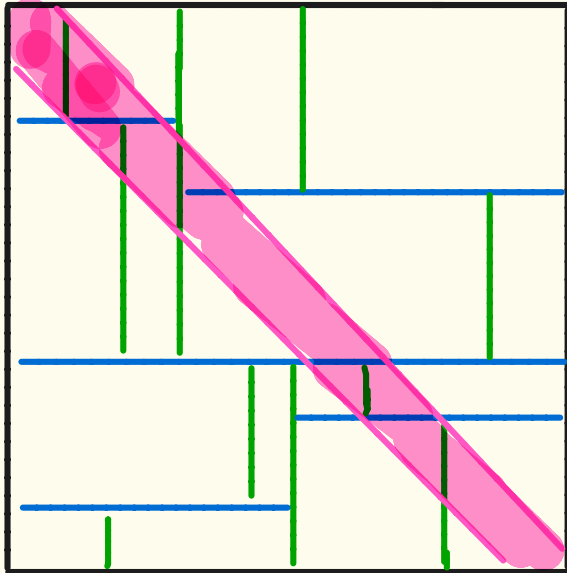
How to prove BPP LIFTING THEOREM ?

$(\{0,1\}^m)^n$

$[m]^n$



How to prove BPP LIFTING THEOREM ?



Let $z \in \{0,1\}^n$

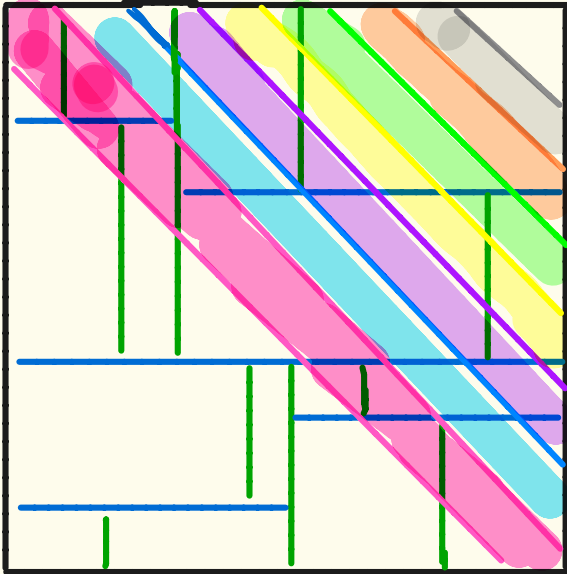
The z -slice are the
inputs $(x,y) \in (Q^n)^{-1}(z)$

(the inputs to Alice/Bob
consistent with z)

How to prove BPP LIFTING THEOREM ?

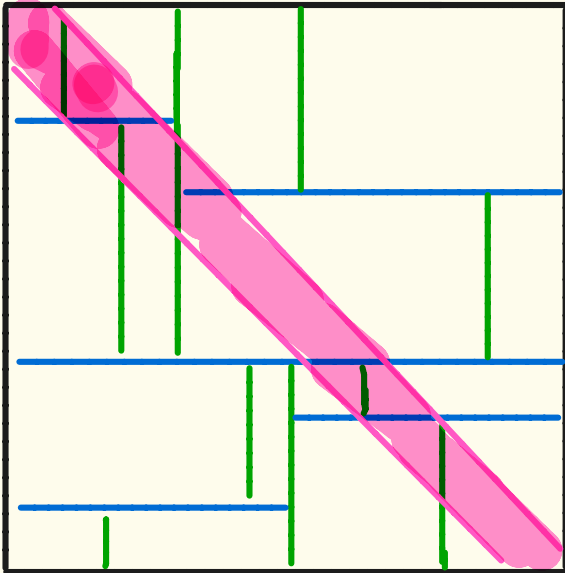
$[m]^n \times (\{0,1\}^m)^n$ partitioned into

2^n z -slices, one for each $z \in \{0,1\}^n$



SIMULATION

Π :

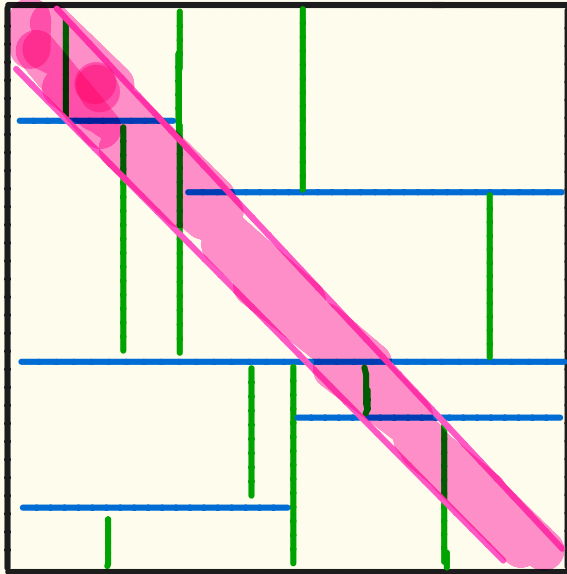


"Simulate Π " by a randomized decision tree \mathcal{T}

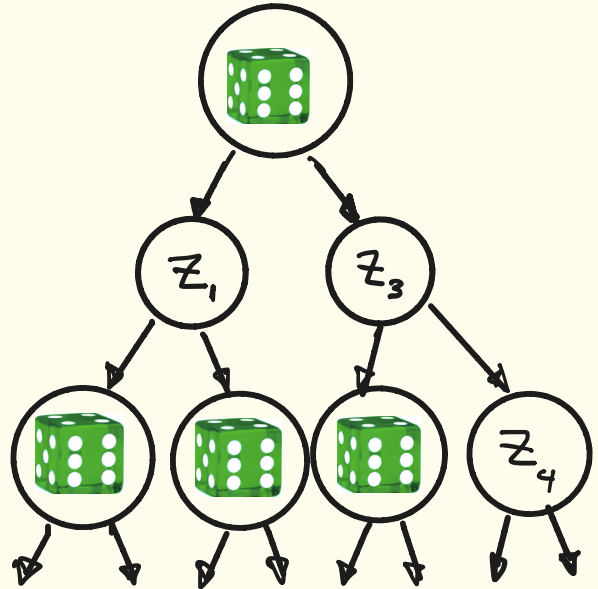
SIMULATION

"simulate Π " by a randomized decision tree \mathcal{T}

Π :



\mathcal{T} :

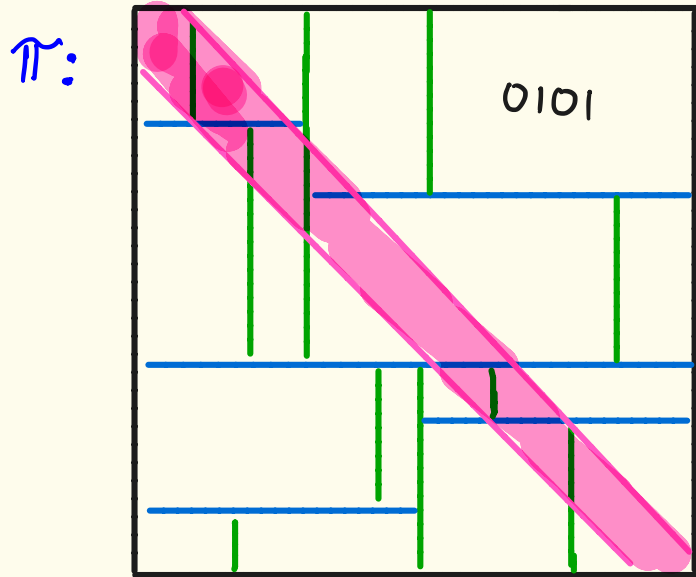


leaves of \mathcal{T} labelled by transcripts (rectangles) of Π

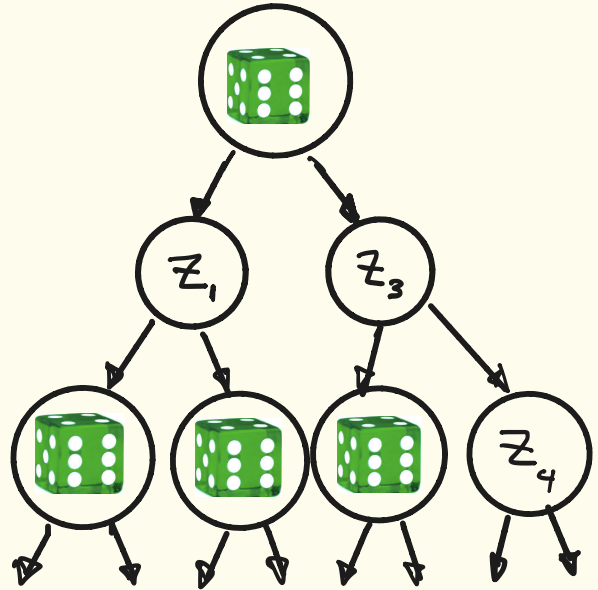
GOAL $\forall z \in \{0,1\}^n$ $\boxed{1} \approx \boxed{2}$

$\boxed{1}$ $\mathcal{T}(z)$ = output of randomized decision tree on z

$\boxed{2}$ Distribution over transcripts generated by \mathcal{T} on $(x,y) \sim (g^n)^{-1}(z)$



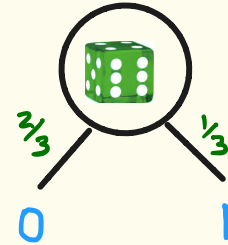
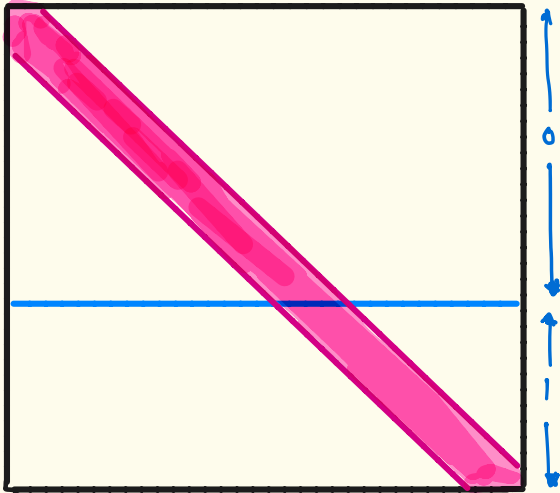
\mathcal{T} :



GOAL $\forall z$ $\boxed{1} \approx \boxed{2}$

$\boxed{1}$ $\gamma(z)$

$\boxed{2}$ Distribution over transcripts generated by Π on $(x,y) \in (g^n)^{-1}(z)$



Idea:

Pretend marginals
are uniform!

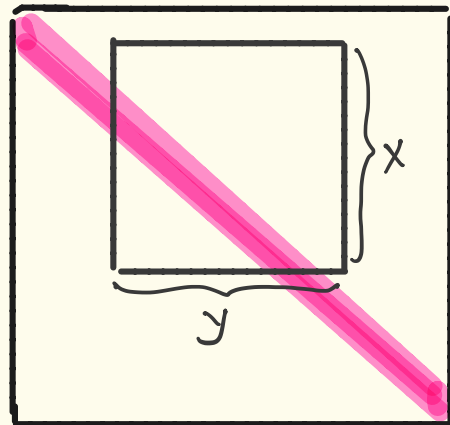
UNIFORM MARGINALS LEMMA

Let $X \subseteq [m]^n$ be DENSE

$Y \subseteq (\{0,1\}^m)^n$ be LARGE

Then $\forall z \in \{0,1\}^n$

$(x,y) \sim (g^n)^{-1}(z)$ has both
marginals close to uniform
on X and Y



DENSE: $H_\infty(X_I) \geq .9 |I| \log m \quad \forall I \subseteq [m]$

SIMULATION

I. If current X is DENSE AND Y is LARGE :
simulate according to marginal probabilities

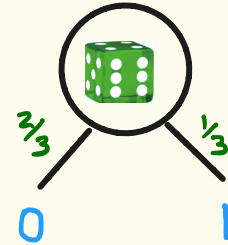
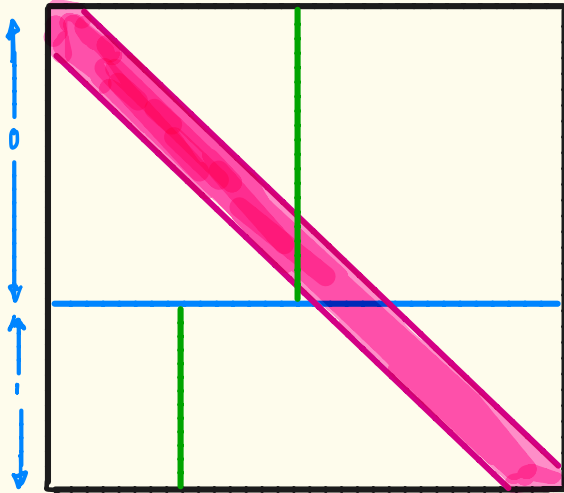
II Otherwise:

- 1 Compute partition $X = \cup_i X^i$ where each X^i is fixed on some $I \subseteq [n]$ and **dense** on \bar{I}
- 2 Update $X \leftarrow X^i$ with probability $|X^i|/|X|$
- 3 Query $z_I \in \{0,1\}^I$
- 4 Restrict Y so that $g^I(X_I, Y_I) = z_I$
- 5 Update $Y \leftarrow Y_{\bar{I}}$ and $X \leftarrow X_{\bar{I}}$ (which is **dense**)

SIMULATION

⇒ I. If current X DENSE + Y LARGE, SIMULATE
II OTHERWISE:

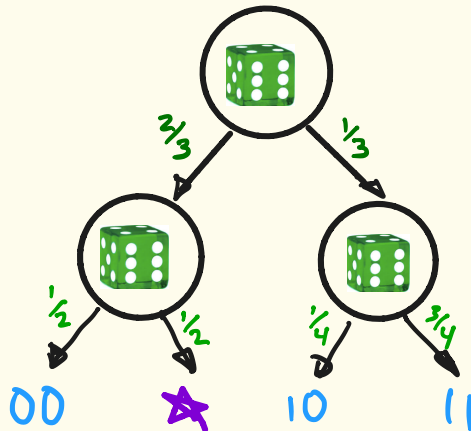
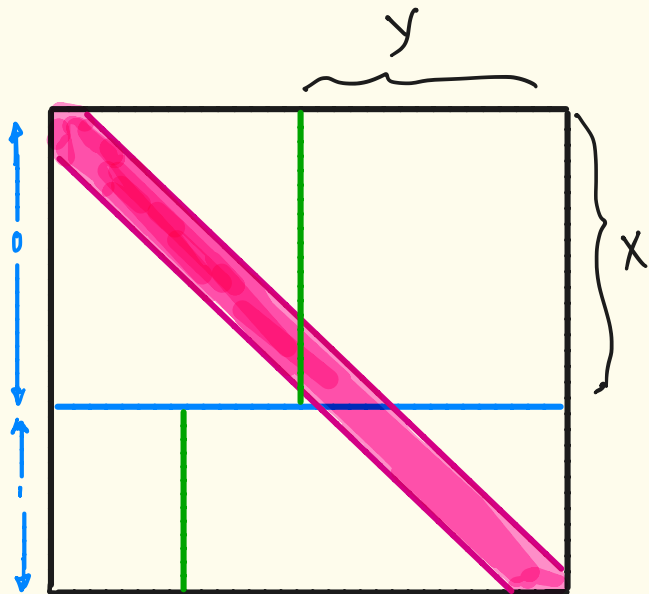
- 1 Compute partition $X = \cup_i X^i$ where each X^i is fixed on some $I \subseteq [n]$ and **dense** on \bar{I}
- 2 Update $X \leftarrow X^i$ with probability $|X^i|/|X|$
- 3 Query $z_I \in \{0, 1\}^I$
- 4 Restrict Y so that $g^I(X_I, Y_I) = z_I$
- 5 Update $Y \leftarrow Y_{\bar{I}}$ and $X \leftarrow X_{\bar{I}}$ (which is **dense**)



SIMULATION

I. If current X DENSE, Y LARGE, SIMULATE
→ II. ELSE

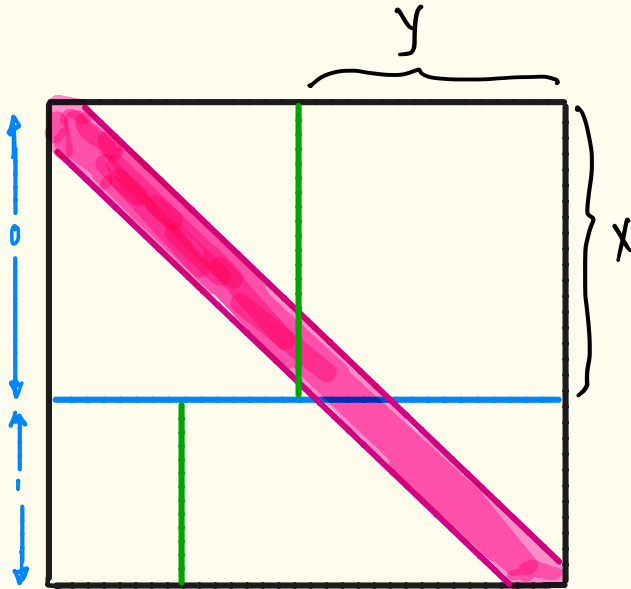
- 1 Compute partition $X = \cup_i X^i$ where each X^i is fixed on some $I \subseteq [n]$ and **dense** on \bar{I}
- 2 Update $X \leftarrow X^i$ with probability $|X^i|/|X|$
- 3 Query $z_I \in \{0,1\}^I$
- 4 Restrict Y so that $g^I(X_I, Y_I) = z_I$
- 5 Update $Y \leftarrow Y_I$ and $X \leftarrow X_{\bar{I}}$ (which is **dense**)



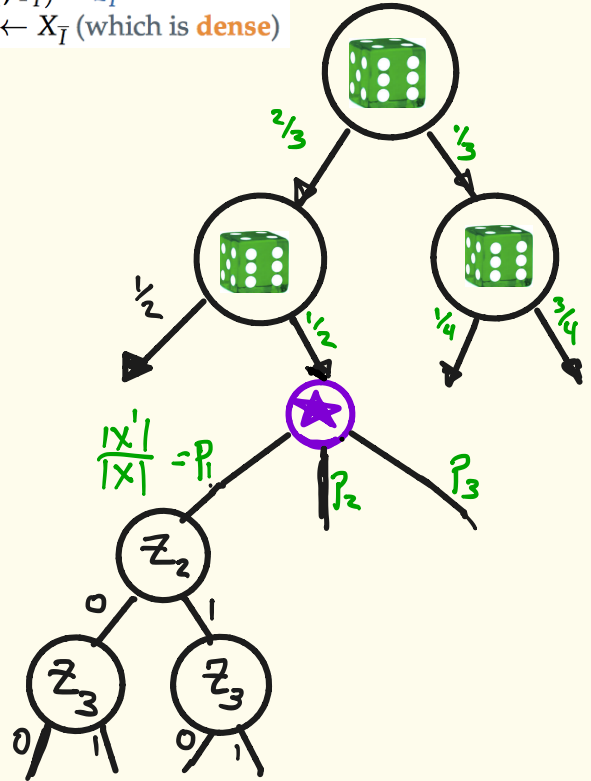
not dense!

SIMULATION

- 1 Compute partition $X = \cup_i X^i$ where each X^i is fixed on some $I \subseteq [n]$ and **dense** on \bar{I}
- 2 Update $X \leftarrow X^i$ with probability $|X^i|/|X|$
- 3 Query $z_I \in \{0,1\}^I$
- 4 Restrict Y so that $g^I(X_I, Y_I) = z_I$
- 5 Update $Y \leftarrow Y_{\bar{I}}$ and $X \leftarrow X_{\bar{I}}$ (which is **dense**)



Say X^i fixes coordinates 2,3



OPEN QUESTIONS

- Prove lifting theorems for information complexity
- Prove randomized Lifting theorem for constant-sized gadget g

Thanks!