CSCC24 2023 Summer - Assignment 2
Due: Sunday July 2, 11:59PM
This assignment is worth $10 \%$ of the course grade.
In this assignment, we investigate some properties of lazy and/or self-referencing data structures.

This assignment is mainly theory and calculations. Please hand in your answer in a text file A2.txt

## Question 1: iterate

In lectures we have seen that the library function iterate is handy for generating an infinite list of the form $[x, f(x), f(f(x)), \ldots]$ to help with search problems. We now investigate its memory cost under different use cases.

For concreteness and focus, we work a special case, the following function $r$ :
r $\mathrm{x}=\mathrm{x}$ : $\mathrm{r}(\mathrm{x}+2)$

## 1(a): The $n$th element [6 marks]

The following function gives the $n$th item (base-0 indexing) of a list, assuming it's long enough. (It is basically (!!) in the library.)
get $\left.0(x:)_{\text {) }}\right)=x$
get $\mathrm{n}\left(\mathrm{K}_{\mathrm{x}}: \mathrm{xs}\right)=\operatorname{get}(\mathrm{n}-1) \mathrm{xs}$
Show the lazy evaluation steps of get 3 ( r 10 ) until you get the numeric answer.

## 1(b) [1 mark]

In general, how much space does it take to evaluate get $n$ ( r 10 )? You can give a big- $\Theta$ answer.

## 1(c): Search [6 marks]

You see that r (and iterate) can be too lazy in its elements. We usually don't mind it because the most common use cases are not asking for the $n$th element, but rather searching for an element by a criterion.

Below is a toy example (but it gets the point across) that searches for a particular number.

```
find k (x:xs) | k==x = True
    | otherwise = find k xs
```

Show the lazy evaluation steps of find 16 ( r 10 ) until you get True.

## 1(d) [1 mark]

In general, how much space does it take to evaluate find $k$ ( r 10 )? You can give a big- $\Theta$ answer. We assume that $k$ can be found.

## Question 2: Memory from Feedback Loop

This is basically an exam question last year, but without Functor and Applicative, focusing on the feedback loop; plus, you possess a powerful tool that students last year didn't have: the method of successive approximations! (The one about $\perp$.)

We will use the built-in list type for its nicer syntax, instead of the custom-made type in the exam question. Hence, we use [Bool] as infinite lists for inputs and outputs of digital circuits under discrete time.

## 2(a) [2 marks]

Implement
srBody :: [Bool] -> [Bool] -> [Bool] -> [Bool]
srBody x s r = ...
to model this circuit (no delay or feedback loop for now):


We assume that the inputs are infinite lists; you do not need a base case for the empty list.
Although this part is marked by a TA, starter code (SRLatch.hs) with test cases is provided to help clarify what you need to do. However, you stil have to copy your solution to A2.txt.

## SR AND-OR Latch

The SR AND-OR latch (Wikipedia entry) is the feedback circuit shown below; in a discrete-time model such as our Haskell code, an extra delay is also needed ${ }^{1}$ :


Soon we will discover its functionality:

- Whenever $r$ (short for "reset") becomes 1 for a moment, $q$ becomes 0 , and stays that way even after $r$ goes back to 0 .
- Whenever $s$ (short for "set") becomes 1 for a moment (and $r$ stays 0 ), $q$ becomes 1 , and stays that way even after $s$ goes back to 0 .

So it is 1 bit of memory, and you write 0 or 1 by sending a pulse to $r$ or $s$.
In the remainder of this question, I use " 0 " and " 1 " instead of False and True to make things look nicer. You may do the same in your answers.

[^0]
## 2(b) [2 marks]

First we see why the model needs a delay-by omitting it and seeing what happens. With no delay, the model becomes (with sample input)
myS $=0: 1: 0: 0: 0: 0: 0: \ldots$ stays 0 forever
$\operatorname{myR}=0: 0: 0: 0: 1$ : $0: 0: \ldots$ stays 0 forever
bad $=$ srBody bad myS myR
Use the method of successive approximations to explain why bad $=\perp$.

## 2(c) [8 marks]

If the model includes a delay, it becomes (with sample input)

```
myS = 0 : 1 : 0: 0: 0:0: 0: 0: ... stays 0 forever
myR = 0 : 0 : 0: 0: 1 : 0 : 0 : 0 : ... stays 0 forever
q = 0 : srBody q myS myR
```

Calculate the approximation $q_{8}$, which should be enough to illustrate how $q$ behaves.
Since this is doing math, the steps you show are for the purpose of "show your work". You can also write like "1 | 0 \& $\sim 0$ " to keep things short.

End of questions.


[^0]:    ${ }^{1}$ continuous-time models and real gates also have tiny delays

