CSCC24 2023 Summer – Assignment 2 Due: Sunday July 2, 11:59PM This assignment is worth 10% of the course grade.

In this assignment, we investigate some properties of lazy and/or self-referencing data structures.

This assignment is mainly theory and calculations. Please hand in your answer in a text file A2.txt

# Question 1: iterate

In lectures we have seen that the library function iterate is handy for generating an infinite list of the form  $[x, f(x), f(f(x)), \ldots]$  to help with search problems. We now investigate its memory cost under different use cases.

For concreteness and focus, we work a special case, the following function r:

r x = x : r (x+2)

### 1(a): The *n*th element [6 marks]

The following function gives the nth item (base-0 indexing) of a list, assuming it's long enough. (It is basically (!!) in the library.)

get 0 (x:\_) = x get n (\_:xs) = get (n-1) xs

Show the lazy evaluation steps of get 3 (r 10) until you get the numeric answer.

### 1(b) [1 mark]

In general, how much space does it take to evaluate get n (r 10)? You can give a big- $\Theta$  answer.

#### 1(c): Search [6 marks]

You see that r (and iterate) can be too lazy in its elements. We usually don't mind it because the most common use cases are not asking for the *n*th element, but rather searching for an element by a criterion.

Below is a toy example (but it gets the point across) that searches for a particular number.

Show the lazy evaluation steps of find 16 (r 10) until you get True.

#### 1(d) [1 mark]

In general, how much space does it take to evaluate find k (r 10)? You can give a big- $\Theta$  answer. We assume that k can be found.

## Question 2: Memory from Feedback Loop

This is basically an exam question last year, but without Functor and Applicative, focusing on the feedback loop; plus, you possess a powerful tool that students last year didn't have: the method of successive approximations! (The one about  $\perp$ .)

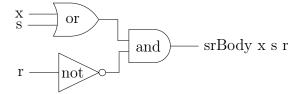
We will use the built-in list type for its nicer syntax, instead of the custom-made type in the exam question. Hence, we use [Bool] as infinite lists for inputs and outputs of digital circuits under discrete time.

### 2(a) [2 marks]

Implement

```
srBody :: [Bool] -> [Bool] -> [Bool] -> [Bool]
srBody x s r = ...
```

to model this circuit (no delay or feedback loop for now):

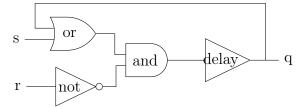


We assume that the inputs are infinite lists; you do not need a base case for the empty list.

Although this part is marked by a TA, starter code (SRLatch.hs) with test cases is provided to help clarify what you need to do. However, you stil have to copy your solution to A2.txt.

#### SR AND-OR Latch

The SR AND-OR latch (Wikipedia entry) is the feedback circuit shown below; in a discrete-time model such as our Haskell code, an extra delay is also needed<sup>1</sup>:



Soon we will discover its functionality:

- Whenever r (short for "reset") becomes 1 for a moment, q becomes 0, and stays that way even after r goes back to 0.
- Whenever s (short for "set") becomes 1 for a moment (and r stays 0), q becomes 1, and stays that way even after s goes back to 0.

So it is 1 bit of memory, and you write 0 or 1 by sending a pulse to r or s.

In the remainder of this question, I use "0" and "1" instead of False and True to make things look nicer. You may do the same in your answers.

<sup>&</sup>lt;sup>1</sup>continuous-time models and real gates also have tiny delays

# 2(b) [2 marks]

First we see why the model needs a delay—by omitting it and seeing what happens. With no delay, the model becomes (with sample input)

Use the method of successive approximations to explain why  $bad = \bot$ .

## 2(c) [8 marks]

If the model includes a delay, it becomes (with sample input)

Calculate the approximation  $q_8$ , which should be enough to illustrate how q behaves.

Since this is doing math, the steps you show are for the purpose of "show your work". You can also write like " $1 \mid 0 \& ~0$ " to keep things short.

End of questions.