

Codifying Probabilities with The Last Full Measure

Albert Lai

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Introduction

Motivating Example

Laplace's Rule of Succession

Let $n, k \in \mathbb{N}$, $0 \leq k \leq n$, be given/fixed.

1. pick r from Uniform(0, 1)
2. pick c from Binomial(n, r)
3. on condition / restrict to $c = k$

Expected value of $r = (k + 1)/(n + 2)$

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- ▶ Hybrid continuous-discrete.
- ▶ Randomly choose a binomial distribution. 🤖

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(Finishing what 3Blue1Brown started: probabilities of probabilities [part 1](#), [part 2](#).)

Programming Probabilities

Random Number Generators

RNG X is set/type of programs that output a random X element
(probability depends on program)

Uniform : $\mathbb{R} \times \mathbb{R} \rightarrow \text{RNG } \mathbb{R}$

Uniform(a, b) picks real number from $[a, b]$ evenly.

Binomial : $\mathbb{N} \times [0, 1] \rightarrow \text{RNG } \mathbb{N}$

Binomial(n, r) tosses coin n times, head probability r , count heads.

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Binomial : $\mathbb{N} \times [0, 1] \rightarrow \text{RNG } \mathbb{N}$

Binomial(n, r) tosses coin n times, head probability r , count heads.

Unit $_X$: $X \rightarrow \text{RNG } X$

Unit $_X(x)$ Always outputs x . “Rare desert of determinism in vast oasis of randomization.” I omit subscript X if inferrable.

Chaining

Chaining operator “bind”, “then”, “flat-map”

$\gg= : \text{RNG } X \times (X \rightarrow \text{RNG } Y) \rightarrow \text{RNG } Y$

$g \gg= k$ passes output of g to parametrized RNG k

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Example:

1. pick r from $\text{Uniform}(0, 1)$
2. pick c from $\text{Binomial}(n, r)$
3. output (r, c)

$\text{Uniform}(0, 1) \gg= (\lambda r. \text{Binomial}(n, r) \gg= (\lambda c. \text{Unit}(r, c)))$

or

$\text{Uniform}(0, 1) \gg= \lambda r. \text{Binomial}(n, r) \gg= \lambda c. \text{Unit}(r, c)$

Restriction/Conditional

Restriction operator

$| : \text{RNG } X \times (X \rightarrow \mathbb{B}) \rightarrow \text{RNG } X$

($\mathbb{B} = \{\text{false}, \text{true}\}$)

$g | \textit{pred}$ = restrict g to when \textit{pred} is true.

(Rejection sampling: Keep retrying g until output satisfies \textit{pred} .)

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$g | \text{pred} =$ restrict g to when pred is true.

(Rejection sampling: Keep retrying g until output satisfies pred .)

Example:

1. pick x from $\text{Uniform}(0, 1)$
2. on condition $x > 0.3$
3. (output x)

$\text{Uniform}(0, 1) | (\lambda x. x > 0.3)$

Express as Program

Define

$$g = \text{Uniform}(0, 1) \gg= \lambda r. \text{Binomial}(n, r) \gg= \lambda c. \text{Unit}(r, c)$$

$$g' = g \mid (\lambda(r, c). c = k)$$

$$\mu = g' \gg= \lambda(r, c). \text{Unit}(r)$$

Then μ generates an r as prescribed.

Re-run many times to approximate distribution and expected value.

(Actual Haskell code modulo syntax.)

Re-read Program as Probability Measure

There is also a measure-theory reading of

$$g = \text{Uniform}(0, 1) \gg = \lambda r \cdot \text{Binomial}(n, r) \gg = \lambda c \cdot \text{Unit}(r, c)$$

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Then μ is the probability distribution/measure of the r in question.

Can find expected value and pdf.

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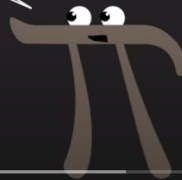
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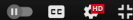
“Codifying probability with the last full measure.”



You may enjoy
"Measure theory"



6:54 / 10:00



Probability Measures

Measure Theory: Motivation 1/2

Integration by Lateral Thinking. Literally.

Riemann integral: Pixelate the x -axis.

$$\sum_i f(x_i) \times \text{length}[x_i, x_i + \epsilon)$$

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Lebesgue integral: Pixelate the y -axis.

$$\sum_i y_i \times \text{length}\left(f^{-1}[y_i, y_i + \epsilon)\right)$$

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Lebesgue integral: Pixelate the y -axis.

$$\sum_i y_i \times \text{length}(f^{-1}[y_i, y_i + \epsilon))$$

Need “length” for fairly general subsets. Require:

$$\text{length}(\bigcup_i A_i) = \sum_i \text{length}(A_i) \quad (\text{countable disjoint union})$$

Turns out problematic for all subsets. Settle for large enough family closed under complement, countable union.

Measure Theory: Motivation 2/2

Probability Theory

Sample space Ω .

\Pr : subsets of $\Omega \rightarrow [0, 1]$

Require:

$$\Pr(\bigcup_i A_i) = \sum_i \Pr(A_i) \quad (\text{countable disjoint union})$$

Hmm déjà vu...

Measure Theory: Motivation 2/2

Probability Theory

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Require:

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Moreover, expected value of $f : \Omega \rightarrow \mathbb{R}$ = use \Pr for “length” in Lebesgue integration!

$$\sum_i y_i \times \Pr(f^{-1}[y_i, y_i + \epsilon))$$

Measure Theory: Motivation 2/2

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$$\sum_i y_i \times \Pr(f^{-1}[y_i, y_i + \epsilon))$$

Riemann may not work: Ω may not even have “intervals”.

Measurable Space; σ -Algebra

Data of a measurable space:

- ▶ Set of points X .
- ▶ σ -algebra \mathfrak{M} or $\mathfrak{M}_X, \subseteq \wp(X)$, closed under:
 - ▶ owning X , owning \emptyset
 - ▶ complement, countable union
 - ▶ (corollary: also subtraction, countable intersection)

Members “measurable subsets”.

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Examples:

- ▶ X countable set, $\mathfrak{M} = \wp(X)$
- ▶ $X = \mathbb{R}$, \mathfrak{M} Borel algebra: smallest σ -algebra owning open sets.
- ▶ $X = \mathbb{R}$, \mathfrak{M} Lebesgue-measurable subsets (appendix). Larger than Borel algebra. Default.

Measures; Probability Measures

[Positive] Measure μ over measurable space (X, \mathfrak{M}) :

- ▶ $\mu : \mathfrak{M} \rightarrow [0, \infty]$
- ▶ $\mu(\bigcup_i A_i) = \sum_i \mu(A_i)$ for countable disjoint union
“countably additive”
- ▶ (corollary: $\mu(\emptyset) = 0$)
- ▶ (corollary: if $A \subseteq B$ then $\mu(A) \leq \mu(B)$)

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Probability measure a.k.a. distribution: Furthermore:

- ▶ $\mu(X) = 1$
- ▶ (corollary: $\mu : \mathfrak{M} \rightarrow [0, 1]$)

Define $\Pi X =$ set of probability measures over (X, \mathfrak{M}_X) .

Discrete Measures

Counting measure: X countable set, $\mathfrak{M} = \wp(X)$

$\# : \wp(X) \rightarrow \mathbb{N} \cup \{\infty\} \subseteq [0, \infty]$

$$\#(A) = \begin{cases} |A| & A \text{ finite} \\ \infty & A \text{ infinite} \end{cases}$$

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Binomial distribution: $X = \mathbb{N}$ (for simplicity), $\mathfrak{M} = \wp(X)$

Binomial : $\mathbb{N} \times [0, 1] \rightarrow \Pi \mathbb{N}$

$$\text{Binomial}(n, r)(A) = \sum_{\substack{i \in A \\ 0 \leq i \leq n}} \binom{n}{i} r^i (1-r)^{n-i}$$

Continuous Measures

Lebesgue measure: $X = \mathbb{R}$, \mathfrak{M} Lebesgue-measurable subsets.

$m : \mathfrak{M} \rightarrow [0, \infty]$

$m([a, b]) = b - a$, same for $(a, b]$ etc. Full defn in appendix.

Default.

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Uniform distribution: Lebesgue measure with rescaling:

Uniform : $\mathbb{R} \times \mathbb{R} \rightarrow \Pi \mathbb{R}$

$$\text{Uniform}(a, b)(A) = \frac{1}{b - a} m(A \cap [a, b])$$

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Other continuous distributions mentioned later after integration.

The Unit Measure

$\text{Unit}_X : X \rightarrow \Pi X$

$$\text{Unit}_X(x)(A) = \chi_A(x) = \begin{cases} 0 & x \notin A \\ 1 & x \in A \end{cases}$$

(χ_A characteristic function of set A)

Deterministic corner case.

X can be discrete or continuous or any measurable space.

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Deterministic corner case.

X can be discrete or continuous or any measurable space.

In the continuous case, no probability density function.



Measurable Functions

We will only integrate functions that satisfy:

$f : X \rightarrow [-\infty, \infty]$ measurable function iff any of:

- ▶ for all open B , $f^{-1}(B) \in \mathfrak{M}_X$
- ▶ for all $y \in \mathbb{R}$, $\{x \mid f(x) > y\} \in \mathfrak{M}_X$
- ▶ or \geq , or $<$, or \leq

Motivation: Need $\mu(f^{-1}[y, y + \epsilon])$, makes sense for \mathfrak{M}_X only.

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Motivation: Need $\mu(f^{-1}[y, y + \epsilon])$, makes sense for \mathfrak{M}_X only.

Easy: $f : \mathbb{N} \rightarrow [-\infty, \infty]$ is measurable using $\mathfrak{M} = \wp(\mathbb{N})$.

Theorem: Piecewise continuous $f : \mathbb{R} \rightarrow \mathbb{R}$ is measurable using Lebesgue-measurable subsets.

Lebesgue Integration: Idea

Notation: $\int f d\mu$ integrates f over all of X using measure μ .

Assume $f \geq 0$ for now. Approximate from below by simple functions (finite range).

Example: $X = [-4, 4]$, $f(x) = x^2$, an approximation is

$$s(x) = 4 \cdot \chi_{(-3, -2] \cup [2, 3)}(x) + 9 \cdot \chi_{[-4, -3] \cup [3, 4]}(x)$$

“Clearly”

$$\int s d\mu = 4 \cdot \mu((-3, -2] \cup [2, 3)) + 9 \cdot \mu([-4, -3] \cup [3, 4])$$

Take supremum over all approximations.

For general f , split into positive and negative parts, both treatable as above.

Lebesgue Integration

Simple functions (finite range):

$$\int \sum_{i=1}^n a_i \chi_{E_i} d\mu = \sum_{i=1}^n a_i \mu(E_i) \quad (a_i \in \mathbb{R}, E_i \in \mathfrak{M})$$

Extend to non-negative $f : X \rightarrow [0, \infty]$

$$\int f d\mu = \sup\{\int s d\mu \mid s \text{ simple}, 0 \leq s \leq f\}$$

Extend to full range $f : X \rightarrow [-\infty, \infty]$

$$\int f d\mu = \left(\int \max(0, f) d\mu \right) - \left(\int -\min(f, 0) d\mu \right)$$

assuming not $\infty - \infty$.

Lebesgue Integration

Notation: $\int_A f d\mu$ is over arbitrary $A \in \mathfrak{M}$, instead of all X .

Two equivalent treatments:

- ▶ Revise the definitions, change $\mu(E_i)$ to $\mu(E_i \cap A)$.
- ▶ Just use $\int f \chi_A d\mu$

Discrete Integration

X countable set, $\mathfrak{M} = \wp(X)$, counting measure:

$$\int f d\# = \sum_{i \in X} f(i)$$

(assume $f \geq 0$ or else absolute convergence or other conditions)

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$$\int f d\# = \sum_{i \in X} f(i)$$

(assume $f \geq 0$ or else absolute convergence or other conditions)

Binomial expressible as integral $d\#$:

$$\text{Binomial}(n, r)(A) = \int_A \lambda i \cdot \binom{n}{i} r^i (1-r)^{n-i} d\#$$

Hence $\lambda i \cdot \binom{n}{i} r^i (1-r)^{n-i}$ is probability mass function.

$$\int f d(\text{Binomial}(n, r)) = \int \lambda i \cdot f(i) \binom{n}{i} r^i (1-r)^{n-i} d\#$$

Continuous Integration (Sorry!)

$\int f \, dm$ default for $X = \mathbb{R}$ or subspace. Riemann toolbox reusable because:

Theorem: For Riemann-integrable $f : [a, b] \rightarrow \mathbb{R}$,

$$\int_{[a,b]} f \, dm = \text{Riemann} \int_a^b f(x) \, dx$$

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Uniform distribution: Reuse m with rescaling:

$$\int f d(\text{Uniform}(a, b)) = \frac{1}{b-a} \int_{[a,b]} f dm$$

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$$\int_{[a,b]} f dm = \text{Riemann} \int_a^b f(x) dx$$

Uniform distribution: Reuse m with rescaling:

$$\int f d(\text{Uniform}(a, b)) = \frac{1}{b-a} \int_{[a,b]} f dm$$

Most continuous distributions have probability density functions:

$$\begin{aligned}\mu(A) &= \int_A \text{pdf} dm \\ \int f d\mu &= \int f \text{pdf} dm\end{aligned}$$

Unit Integration

Sifting property:

$$\int f d(\text{Unit}(x)) = f(x)$$

Integral well defined (and beautiful), even in continuous case, even if no pdf. The power of measure theory!

Chaining Probability Measures

Chaining operator “bind”, “then”, “flat-map”

$$\gg= : \Pi X \times (X \rightarrow \Pi Y) \rightarrow \Pi Y$$

Intuition for $(\mu \gg= k)(B)$: For each $x \in X$, $k(x) \in \Pi Y$, $k(x)(B)$ is probability of B . Average over X according to μ . (Total probability).

Likewise for expected values.

$$\begin{aligned}(\mu \gg= k)(B) &= \int \lambda x \cdot k(x)(B) d\mu \\ \int f d(\mu \gg= k) &= \int \left(\lambda x \cdot \int f d(k(x)) \right) d\mu\end{aligned}$$

(Require $k : X \rightarrow \Pi Y$ measurable function. Boils down to $(\lambda x \cdot k(x)(B)) : X \rightarrow [0, 1]$ measurable function for all $B \in \mathfrak{M}_Y$.)

Interlude

Happy Belated Halloween! 🎃

$(\Pi, \text{Unit}, \gg=)$ is a programmer-friendly version of . . .

The Giry monad! Due to Michèle Giry. More in appendix.

Restricting Probability Measures

Restriction operator

$$| : \Pi X \times (X \rightarrow \mathbb{B}) \rightarrow \Pi X$$

Conditional probability.

$$\begin{aligned}(\mu | pred)(A) &= \mu(A \cap B) / \mu(B) \\ \int f d(\mu | pred) &= \frac{1}{\mu(B)} \int f \chi_B d\mu\end{aligned}$$

where $B = \{x \mid pred(x)\}$, assuming $\in \mathfrak{M}$.

(One may say: $pred$ is a measurable predicate.)

Re-read Program as Probability Measure

Define

$$g = \text{Uniform}(0, 1) \gg \lambda r \cdot \text{Binomial}(n, r) \gg \lambda c \cdot \text{Unit}(r, c)$$

$$g' = g \mid (\lambda(r, c) \cdot c = k)$$

$$\mu = g' \gg \lambda(r, c) \cdot \text{Unit}(r)$$

Then μ is the probability measure of the r in question.

$$\begin{aligned} \text{expected} &= \int \lambda r \cdot r d\mu \\ &= (n+1) \int_0^1 r \binom{n}{k} r^k (1-r)^{n-k} dr && \text{appendix} \\ &= \frac{k+1}{n+2} \\ \text{pdf}(r) &= (n+1) \binom{n}{k} r^k (1-r)^{n-k} \end{aligned}$$

Conclusion

Conclusion

Formal constructs for expressing probabilistic models.

Program interpretation gives executable samplers.

Measure-theory interpretation gives resulting distributions.

Works the same way for discrete, continuous, hybrid, nested.

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Appendix

Lebesgue Measure And Measurable Subsets

The following is well-defined for all $A \in \wp(\mathbb{R})$; denoted $m^*(A)$:

- ▶ let $\{I_n\}$ be sequence of disjoint open intervals, $\bigcup_n I_n \supseteq A$
- ▶ $\sum_n \text{length}(I_n)$ uncontroversial
- ▶ take infimum over all possibilities

Only issue: Not countably additive for some subsets.

Carathéodory's solution: Restrict to

$$\mathfrak{M} = \{A \mid \forall B. m^*(B) = m^*(B \cap A) + m^*(B - A)\}$$

Adopted for Lebesgue-measurable subsets.

Then define Lebesgue measure $m = m^*|_{\mathfrak{M}}$

The Giry Monad 1/2

Prologue: Generalize “measurable functions” from $X \rightarrow [-\infty, \infty]$ to $X \rightarrow Y$, with Y any measurable space:

$h : X \rightarrow Y$ measurable iff $\forall B \in \mathfrak{M}_Y \cdot h^{-1}(B) \in \mathfrak{M}_X$

Π as endofunctor (on category of measurable spaces):

Object map: $\Pi X =$ set of probability measures over (X, \mathfrak{M}_X) .

σ -algebra: Smallest s.t. for all $A \in \mathfrak{M}_X$, $(\lambda \mu \cdot \mu(A)) : \Pi X \rightarrow [0, 1]$ measurable function.

Morphism map: For measurable $h : X \rightarrow Y$, $\Pi h : \Pi X \rightarrow \Pi Y$

$$\begin{aligned}(\Pi h)(\mu)(B) &= \mu(h^{-1}(B)) \\ \int f d((\Pi h)(\mu)) &= \int f \circ h d\mu\end{aligned}$$

The Giry Monad 2/2

Π as monad:

$\text{Unit}_X : X \rightarrow \Pi X$ as defined earlier.

Multiplication $\text{Flat}_X : \Pi(\Pi X) \rightarrow \Pi X$

$$\begin{aligned}\text{Flat}(\mu)(A) &= \int \lambda v \cdot v(A) d\mu \\ \int f d(\text{Flat}(\mu)) &= \int \left(\lambda v \cdot \int f dv \right) d\mu\end{aligned}$$

Flattens “probability of probabilities” to total probability.

Then define $\mu \gg= k = \text{Flat}((\Pi k)(\mu))$.

Detailed Calculation 1/2

Let $B = \{(r, c) \mid c = k\} = [0, 1] \times \{k\}$.

$$\begin{aligned}\int f dg &= \int \left(\lambda r \cdot \int \left(\lambda c \cdot \int f d(\text{Unit}(r, c)) \right) d(\text{Binomial}(n, r)) \right) \\ &\quad d(\text{Uniform}(0, 1)) \\ &= \int_0^1 \sum_{c=0}^n f(r, c) \binom{n}{c} r^c (1-r)^{n-c} dr \\ g(B) &= \int \chi_B dg \\ &= \int_0^1 \binom{n}{k} r^k (1-r)^{n-k} dr \\ &= \binom{n}{k} \frac{k!(n-k)!}{(n+1)!} \quad (\text{Beta functions}) \\ &= \frac{1}{n+1}\end{aligned}$$

Detailed Calculation 2/2

$$\begin{aligned}\int \lambda r \cdot r d\mu &= \int \left(\lambda(r, c) \cdot \int \lambda r \cdot r d(\text{Unit}(r)) \right) dg' \\ &= \int (\lambda(r, c) \cdot r) dg' \\ &= \frac{1}{g(B)} \int (\lambda(r, c) \cdot r \chi_B(r, c)) dg \\ &= \frac{1}{g(B)} \int_0^1 r \binom{n}{k} r^k (1-r)^{n-k} dr \\ &= (n+1) \binom{n}{k} \frac{(k+1)!(n-k)!}{(n+2)!} \quad (\text{Beta functions}) \\ &= \frac{k+1}{n+2}\end{aligned}$$