Lagrange Duality & PCA CS 411 Tutorial

Wenjie Luo November 7, 2014 Lagrange Duality

PCA Tutorial

Dimensionality Reduction

- We have some data $X \in \mathbb{R}^{N \times D}$
- D may be huge, etc.
- We would like to find a new representation $Z \in \mathbb{R}^{N \times K}$ where K << D.
 - For computational reasons.
 - To better understand (e.g., visualize) the data.
 - For compression.

• ...

• We will restrict ourselves to linear transformations for the time being.

Example

- In this dataset, there are only 3 degrees of freedom: horizontal and vertical translations, and rotations.
- Yet each image contains 784 pixels, so X will be 784 elements wide.



Abstract Visualization



What is a Good Transformation?

- Goal is to find good directions u that preserves "important" aspects of x_2 the data.
- In a linear setting: $z = x^T u$
- This will turn out to be the top-K eigenvalues of the data covariance.
- Two ways to view this:
 - 1. Find directions of maximum variation
 - 2. Find projections that minimize reconstruction error



Principal Component Analysis (Maximum Variance)

$$\begin{aligned} \text{maximize} \frac{1}{2N} \sum_{n=1}^{N} (u_1^T x_n - u_1^T \bar{x}_n)^2 & \text{i.e.,} \\ &= u_1^T S u_1 & \text{variance of} \\ &= u_1^T S u_1 & \text{the projected} \\ &= u_1^T a_1 & \text{the projected} \end{aligned}$$

where the sample mean and covariance are given by:

$$\bar{x} = \frac{1}{N} \sum_{n=1}^{N} x_n$$
$$S = \frac{1}{N} \sum_{n=1}^{N} (x_n - \bar{x}) (x_n - \bar{x})^T$$

- We want to maximize $u_1^T S u_1$
 - subject to $||u_1|| = 1$ (since we are finding a direction)
- Use Lagrange multiplier α_1 to express this as

$$u_1^T S u_1 + \alpha_1 (1 - u_1^T u_1)$$

Take derivative and set to 0

$$Su_1 - \alpha_1 u_1 = 0$$
$$Su_1 = \alpha_1 u_1$$

- So u_1 is an eigenvector of S with eigenvalue α_1
- In fact it must be the eigenvector with maximum eigenvalue, since this minimizes the objective.

maximize $u_2^T S u_2$ subject to $||u_2|| = 1$ $u_{2}^{T}u_{1}=0$ $u_{2}^{T}Su_{2} + \alpha_{2}(1 - u_{2}^{T}u_{2}) - \beta u_{2}^{T}u_{1}$ $\frac{\partial}{\partial u_2} = Su_2 - \alpha_2 u_2 - \beta u_1 = 0$ $\implies u_1^T S u_2 - \alpha_2 u_1^T u_2 - \beta u_1^T u_1 = 0$ $\implies \alpha_1 u_1^T u_2 - \alpha_2 u_1^T u_2 - \beta u_1^T u_1 = 0$ $\implies \alpha_1 \cdot 0 - \alpha_2 \cdot 0 - \beta \cdot 1 = 0$ $\implies \beta = 0$

Lagrange form:

Finding β :

maximize
$$u_2^T S u_2$$

subject to $||u_2|| = 1$
 $u_2^T u_1 = 0$ o
 $u_2^T S u_2 + \alpha_2 (1 - u_2^T u_2) - \beta u_2^T u_1$

Lagrange form:

Finding
$$\alpha_2$$
:

$$\frac{\partial}{\partial u_2} = Su_2 - \alpha_2 u_2 = 0$$
$$\implies Su_2 = \alpha_2 u_2$$

So α_2 must be the second largest eigevalue of S.

PCA in General

- We can compute the entire PCA solution by just computing the eigenvectors with the top-k eigenvalues.
- These can be found using the singular value decomposition of S.

• How do we choose the number of components?



- Look at the spectrum of covariance, pick K to capture most of the variation.
- More principled: Bayesian treatment (beyond this course).



• Eigenfaces

Principal Component Analysis (Minimum Reconstruction Error)

• We can also think of PCA as minimizing the *reconstruction error* of the compressed data.

minimize
$$=\frac{1}{2N}\sum_{n=1}^{N}||x_n - \hat{x}_n||^2$$

• We will omit the details for now, but the key is that we define some K-dimensional basis such that:

$$\hat{x} = Wx + const$$

• The solution will turn out to be the same as the minimum variance formulation.

Reconstruction

• PCA learns to represent vectors in terms of sums of basis vectors.

• For images, e.g.,



PCA for Compression





D=50 D=100 D=200 321x481 image, D is the number of basis vectors used

D in this slide is the same as K in the previous slides

Summary

Thank You ;-)